Dual High-Current Step-Down DC/DC and Dual Linear Regulator with I2C Compatible Interface

Check for Samples: LP3906

FEATURES

- Compatible with Advanced Applications Processors and FPGAs
- 2 LDOs for Powering Internal Processor Functions and I/Os
- High Speed Serial Interface for Independent Control of Device Functions and Settings
- Precision Internal Reference
- Thermal Overload Protection
- Current Overload Protection
- 24-lead 5 × 4 × 0.8 mm WQFN Package
- Software Programmable Regulators

APPLICATIONS

- FPGA, DSP Core Power
- Applications Processors
- Peripheral I/O Power

KEY SPECIFICATIONS

- DC/DC Converter (Buck)
  - 1.5A Output Current
  - Programmable V_{OUT} from:
    - Buck1 : 0.8V–2.0V
    - Buck2 : 1.0V–3.5V
  - Up to 96% Efficiency
  - 2 MHz PWM Switching Frequency
  - ±3% Output Voltage Accuracy
  - Automatic Soft Start
- Linear Regulators (LDO)
  - Programmable V_{OUT} of 1.0V–3.5V
  - ±3% Output Voltage Accuracy
  - 300 mA Output Currents
  - 25 mW (Typ) Dropout

DESCRIPTION

The LP3906 is a multi-function, programmable Power Management Unit, optimized for low power FPGAs, Microprocessors and DSPs.

Typical Application Circuits

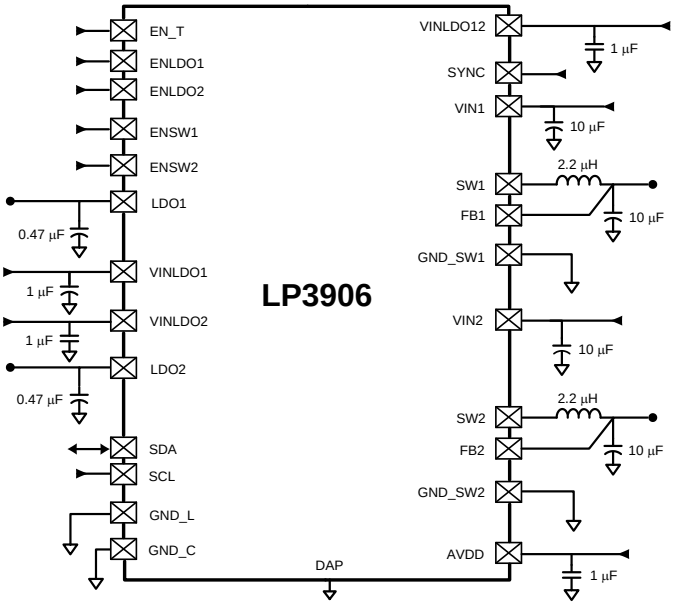


Figure 1. Typical Application Circuit

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For information about how schottky diodes can reduce noise in high load, high Vin applications, see Buck Output Ripple Management.

DESCRIPTION (CONTINUED)

This device integrates two highly efficient 1.5A Step-Down DC/DC converters with dynamic voltage management (DVM), two 300mA Linear Regulators and a 400kHz I^2C compatible interface to allow a host controller access to the internal control registers of the LP3906. The LP3906 additionally features programmable power-on sequencing and is offered in a tiny 5 x 4 x 0.8mm WQFN-24 pin package.

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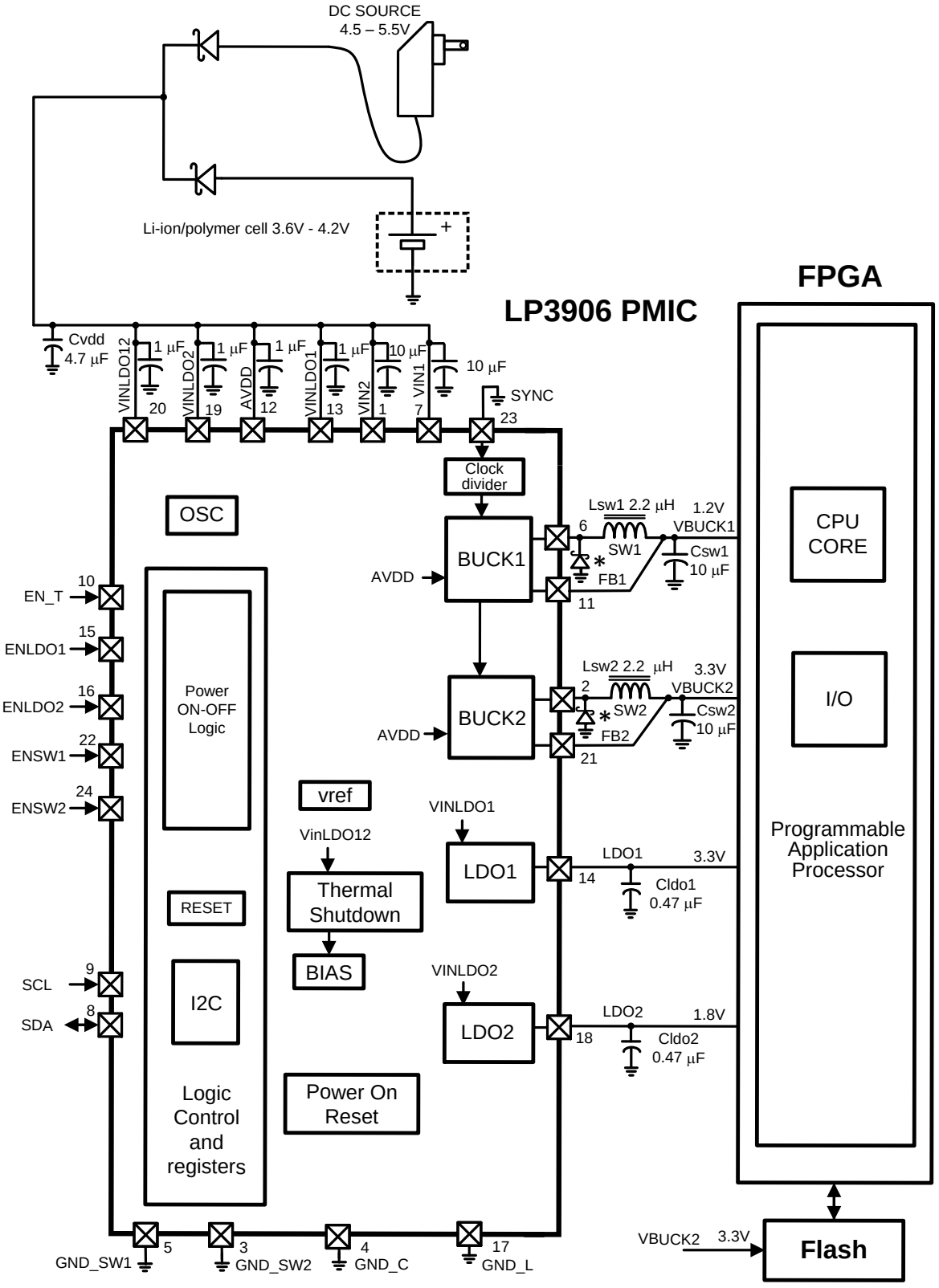


Figure 2. Typical Application Circuit

Connection Diagram

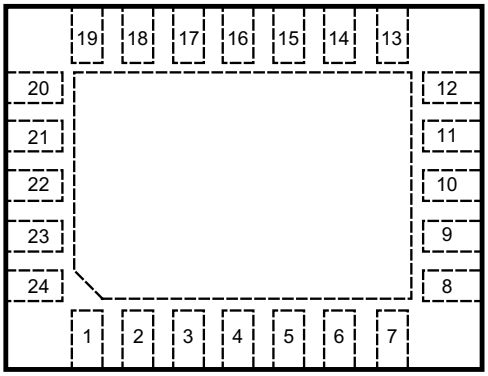


Figure 3. 24-Lead WQFN Package (Top View)
See Package Number NHZ0024B

Table 1. Default Voltage Options(1)(2)

Part Number	Package Marking	Buck1	Buck2	LDO1	LDO2
LP3906SQ-DJXI/NOPB	06-DJXI	0.9V	1.8V	3.3V	1.8V
LP3906SQ-FXPI/NOPB	06-FXPI	1.0V	3.3V	2.5V	1.8V
LP3906SQ-JXXI/NOPB	06-JXXI	1.2V	3.3V	3.3V	1.8V
LP3906SQ-PPXP/NOPB	06-PPXP	1.5V	2.5V	3.3V	2.5V
LP3906SQ-TKXII/NOPB(3)	06-TKXII(3)	1.25V	3.3V	1.8V	1.8V
LP3906SQ-VPFP/NOPB	06-VPFP	1.8V	2.5V	1.5V	2.5V
LP3906SQE-PPXP/NOPB	06-PPXP	1.5V	2.5V	3.3V	2.5V
LP3906SQE-VPFP/NOPB	06-VPFP	1.8V	2.5V	1.5V	2.5V
LP3906SQX-DJXI/NOPB	06-DJXI	0.9V	1.8V	3.3V	1.8V
LP3906SQX-FXPI/NOPB	06-FXPI	1.0V	3.3V	2.5V	1.8V
LP3906SQX-JXXI/NOPB	06-JXXI	1.2V	3.3V	3.3V	1.8V
LP3906SQX-PPXP/NOPB	06-PPXP	1.5V	2.5V	3.3V	2.5V
LP3906SQX-TKXII/NOPB(3)	06-TKXII(3)	1.25V	3.3V	1.8V	1.8V
LP3906SQX-VPFP/NOPB	06-VPFP	1.8V	2.5V	1.5V	2.5V

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at www.ti.com.
(2) Package drawings, thermal data, and symbolization are available at www.ti.com/packaging.
(3) Option only available with default EN_T of 001; all other options use 010.

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Pin Descriptions(1)

Pin Name	Pin No.	I/O	Type	Description
VIN2	1	I	PWR	Power in from either DC source or Battery to Buck 2
SW2	2	O	PWR	Buck2 switcher output pin
GND_SW2	3	G	G	Buck2 NMOS Power Ground
GND_C	4	G	G	Non switching core ground pin
GND_SW1	5	G	G	Buck1 NMOS Power Ground
SW1	6	O	PWR	Buck1 switcher output pin
VIN1	7	I	PWR	Power in from either DC source or Battery to buck 1
SDA	8	I/O	D	I^2C Data (Bidirectional)
SCL	9	I	D	I^2C Clock
EN_T	10	I	D	Enable for preset power on sequence.
FB1	11	I	A	Buck1 input feedback terminal
AVDD	12	I	PWR	Analog Power for Buck converters.
VINLDO1	13	I	PWR	Power in from either DC source or Battery to input terminal of LDO1
LDO1	14	O	PWR	LDO1 Output
ENLDO1	15	I	D	LDO1 enable pin, a logic HIGH enables the LDO1
ENLDO2	16	I	D	LDO2 enable pin, a logic HIGH enables the LDO2
GND_L	17	G	G	LDO Ground
LDO2	18	O	PWR	LDO2 Output
VINLDO2	19	I	PWR	Power in from either DC source or battery to input terminal to LDO2
VinLDO12	20	I	PWR	Analog Power for Internal Functions (VREF, BIAS, I2C, Logic)
FB2	21	I	A	Buck2 input feedback terminal
ENSW1	22	I	D	Enable Pin for Buck1 switcher, a logic HIGH enables Buck1
SYNC	23	I	D	Frequency Synchronization pin which allows the user to connect an external clock signal PLL to synchronize the PMIC internal oscillator.
ENSW2	24	I	D	Enable Pin for Buck2 switcher, a logic HIGH enables Buck2
DAP	DAP	GND	GND	Connection isn't necessary for electrical performance, but it is recommended for better thermal dissipation.

(1) A: Analog Pin D: Digital Pin G: Ground Pin PWR: Power Pin I: Input Pin I/O: Input/Output Pin O: Output Pin



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

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ABSOLUTE MAXIMUM RATINGS(1)(2)(3)

V_{IN}, SDA, SCL	−0.3V to +6V
GND to GND SLUG	±0.3V
Power Dissipation (P_{D_MAX}) (T_A=85°C, T_{MAX}=125°C,)(4)	1.43 W
Junction Temperature ($T_{J\text{-}MAX}$)	150°C
Storage Temperature Range	−65°C to +150°C
Maximum Lead Temperature (Soldering)	260°C
ESD Ratings Human Body Model (5)	2 kV

(1) Absolute Maximum Ratings indicate limits beyond which damage to the component may occur. Operating Ratings are conditions under which operation of the device is specified. Operating Ratings do not imply specified performance limits. For specified performance limits and associated test conditions, see the Electrical Characteristics.
(2) All voltages are with respect to the potential at the GND pin.
(3) If Military/Aerospace specified devices are required, please contact the TI Sales Office/Distributors for availability and specifications.
(4) In applications where high power dissipation and/or poor package thermal resistance is present, the maximum ambient temperature may have to be derated. Maximum ambient temperature ($T_{A\text{-}MAX}$) is dependent on the maximum operating junction temperature ($T_{J\text{-}MAX\text{-}OP}$ = 125°C), the maximum power dissipation of the device in the application ($P_{D\text{-}MAX}$), and the junction-to-ambient thermal resistance of the part/package in the application (θ_{JA}), as given by the following equation: $T_{A\text{-}MAX} = T_{J\text{-}MAX\text{-}OP} - (\theta_{JA} \times P_{D\text{-}MAX})$. See APPLICATION NOTES.
(5) The Human body model is a 100 pF capacitor discharged through a 1.5 kΩ resistor into each pin. (MILSTD - 883 3015.7)

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OPERATING RATINGS(1)(2)(3)

Bucks	
V_{IN}	2.7V to 5.5V
V_{EN}	0 to (V_{IN} + 0.3V)
Junction Temperature (T_J) Range	−40°C to +125°C
Ambient Temperature (T_A) Range(4)	−40°C to +85°C
Thermal Properties(5)(6) (4)	
Junction-to-Ambient Thermal Resistance (θ_{JA})NHZ0024B	28°C/W

(1) Absolute Maximum Ratings indicate limits beyond which damage to the component may occur. Operating Ratings are conditions under which operation of the device is specified. Operating Ratings do not imply specified performance limits. For specified performance limits and associated test conditions, see the Electrical Characteristics.
(2) All voltages are with respect to the potential at the GND pin.
(3) Min and Max limits are ensured by design, test, or statistical analysis. Typical numbers are not specifications, but do represent the most likely norm.
(4) Junction-to-ambient thermal resistance is highly application and board-layout dependent. In applications where high maximum power dissipation exists, special care must be paid to thermal dissipation issues in board design.
(5) Internal thermal shutdown circuitry protects the device from permanent damage. Thermal shutdown engages at T_J = 160°C (typ.) and disengages at T_J = 140°C (typ.)
(6) In applications where high power dissipation and/or poor package thermal resistance is present, the maximum ambient temperature may have to be derated. Maximum ambient temperature (T_{A-MAX}) is dependent on the maximum operating junction temperature ($T_{J-MAX-OP}$ = 125°C), the maximum power dissipation of the device in the application (P_{D-MAX}), and the junction-to-ambient thermal resistance of the part/package in the application (θ_{JA}), as given by the following equation: $T_{A-MAX} = T_{J-MAX-OP} - (\theta_{JA} \times P_{D-MAX})$. See APPLICATION NOTES.

GENERAL ELECTRICAL CHARACTERISTICS(1)(2)(3)(4)

Unless otherwise noted, V_{IN} = 3.6V, Typical values and limits appearing in normal type apply for T_J = 25°C. Limits appearing in **boldface type** apply over the entire junction temperature range for operation, −40°C to +125°C.

Parameter		Test Conditions	Min	Typ	Max	Units
V_{POR}	Power-On Reset Threshold	V_{DD} Falling Edge		1.9		V
T_{SD}	Thermal Shutdown Threshold			160		°C
T_{SDH}	Themal Shutdown Hysteresis			20		°C

(1) Absolute Maximum Ratings indicate limits beyond which damage to the component may occur. Operating Ratings are conditions under which operation of the device is specified. Operating Ratings do not imply specified performance limits. For specified performance limits and associated test conditions, see the Electrical Characteristics.
(2) All voltages are with respect to the potential at the GND pin.
(3) Min and Max limits are specified by design, test, or statistical analysis. Typical numbers are not specified, but do represent the most likely norm.
(4) This specification is ensured by design.

I²C COMPATIBLE INTERFACE ELECTRICAL SPECIFICATIONS(1)

Unless otherwise noted, V_{IN} = 3.6V. Typical values and limits appearing in normal type apply for T_J = 25°C. Limits appearing in **boldface type** apply over the entire junction temperature range for operation, −40°C to +125°C

Parameter		Test Conditions	Min	Typ	Max	Units
F_{CLK}	Clock Frequency				400	kHz
t_{BF}	Bus-Free Time Between Start and Stop	See(1)	1.3			µs
t_{HOLD}	Hold Time Repeated Start Condition	See(1)	0.6			µs
t_{CLKLP}	CLK Low Period	See(1)	1.3			µs
t_{CLKHP}	CLK High Period	See(1)	0.6			µs
t_{SU}	Set Up Time Repeated Start Condition	See(1)	0.6			µs
$t_{DATAHLD}$	Data Hold time	See(1)	0			µs
t_{DATASU}	Data Set Up Time	See(1)	100			ns
T_{SU}	Set Up Time for Start Condition	See(1)	0.6			µs
T_{TRANS}	Maximum Pulse Width of Spikes that Must be Suppressed by the Input Filter of Both DATA & CLK Signals.	See(1)		50		ns

(1) This specification is ensured by design.

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LOW DROP OUT REGULATORS, LDO1 AND LDO2

Unless otherwise noted, V_{IN} = 3.6, C_{IN} = 1.0 µF, C_{OUT} = 0.47 µF. Typical values and limits appearing in normal type apply for T_J = 25°C. Limits appearing in **boldface type** apply over the entire junction temperature range for operation, −40°C to +125°C. (1)(2) (3)(4)(5)(6) (7)

Parameter		Test Conditions	Min	Typ	Max	Units
V_{IN}	Operational Voltage Range	VINLDO1 and VINLDO2 PMOS pins(8)	**1.74**		**5.5**	V
V_{OUT} Accuracy	Output Voltage Accuracy (Default V_{OUT})	Load current = 1 mA	**−3**		**3**	%
ΔV_{OUT}	Line Regulation	V_{IN} = (V_{OUT} + 0.3V) to 5.0V, (7), Load Current = 1 mA			**0.15**	%/V
	Load Regulation	V_{IN} = 3.6V, Load Current = 1 mA to I_{MAX}			**0.011**	%/mA
I_{SC}	Short Circuit Current Limit	LDO1-2, V_{OUT} = 0V		500		mA
$V_{IN} - V_{OUT}$	Dropout Voltage	Load Current = 50 mA(5)		25	**200**	mV
PSRR	Power Supply Ripple Rejection	F = 10 kHz, Load Current = I_{MAX}		45		dB
θn	Supply Output Noise	10 Hz < F < 100 KHz		80		µVrms
I_Q(6) (9)	Quiescent Current “On”	I_{OUT} = 0 mA		40		µA
	Quiescent Current “On”	I_{OUT} = I_{MAX}		60		µA
	Quiescent Current “Off”	EN is de-asserted(10)		0.03		µA
T_{ON}	Turn On Time	Start up from shut-down		300		µs
C_{OUT}	Output Capacitor	Capacitance for stability 0°C ≤ T_J ≤ 125°C	**0.33**	0.47		µF
		−40°C ≤ T_J ≤ 125°C	**0.68**	1.0		µF
		ESR	**5**		**500**	mΩ

(1) All voltages are with respect to the potential at the GND pin.
(2) Min and Max limits are ensured by design, test, or statistical analysis. Typical numbers are not specifications, but do represent the most likely norm.
(3) C_{IN}, C_{OUT}: Low-ESR Surface-Mount Ceramic Capacitors (MLCCs) used in setting electrical characteristics.
(4) The device maintains a stable, regulated output voltage without a load.
(5) Dropout voltage is the voltage difference between the input and the output at which the output voltage drops to 100 mV below its nominal value.
(6) Quiescent current is defined here as the difference in current between the input voltage source and the load at V_{OUT}.
(7) V_{IN} minimum for line regulation values is 1.8V.
(8) Pins 13, 19 can operate from Vin min of 1.74 to a Vin max of 5.5V this rating is only for the series pass pmos power fet. It allows the system design to use a lower voltage rating if the input voltage comes from a buck output.
(9) The Iq can be defined as the standing current of the LP3906 when the I2C bus is active and all other power blocks have been disabled via the I2C bus, or it can be defined as the I2C bus active, and the other power blocks are active under no load condition. These two values can be used by the system designer when the LP3906 is powered using a battery. If the user plans to use the HW enable pins to disable each block of the IC please contact the factory applications for IQ details.
(10) The Iq exhibits a higher current draw when the EN pin is de-asserted because the I2C buffer pins draw an additional 2µA

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BUCK CONVERTERS SW1, SW2

Unless otherwise noted, V_{IN} = 3.6, C_{IN} = 10 µF, C_{OUT} = 10 µF, L_{OUT} = 2.2 µH ceramic. Typical values and limits appearing in normal type apply for T_J = 25°C. Limits appearing in **boldface type** apply over the entire junction temperature range for operation, −40°C to +125°C. (1) (2) (3) (4) (5)

Parameter		Test Conditions	Min	Typ	Max	Units
V_{OUT}	Output Voltage Accuracy	Default V_{OUT}	−3		+3	%
	Line Regulation	2.7< V_{IN} < 5.5 I_O =10 mA		0.089		%/V
	Load Regulation	100 mA < I_O < I_{MAX}		0.0013		%/mA
Eff	Efficiency	Load Current = 250 mA		96		%
I_{SHDN}	Shutdown Supply Current	EN is de-asserted		0.01		µA
f_{OSC}	Sync Mode Clock Frequency	Synchronized from 13 MHz system clock		2.0		MHz
	Internal Oscillator Frequency			2.0		MHz
I_{PEAK}	Peak Switching Current Limit			2.0		A
I_Q (5)	Quiescent Current “On”	No load PFM Mode		33		µA
R_{DSON} (P)	Pin-Pin Resistance PFET			200		mΩ
R_{DSON} (N)	Pin-Pin Resistance NFET			180		mΩ
T_{ON}	Turn On Time	Start up from shut-down		500		µs
C_{IN}	Input Capacitor	Capacitance for stability	10			µF
C_O	Output Capacitor	Capacitance for stability	10			µF

(1) All voltages are with respect to the potential at the GND pin.
(2) Min and Max limits are ensured by design, test, or statistical analysis. Typical numbers are not specifications, but do represent the most likely norm.
(3) C_{IN}, C_{OUT}: Low-ESR Surface-Mount Ceramic Capacitors (MLCCs) used in setting electrical characteristics.
(4) The device maintains a stable, regulated output voltage without a load.
(5) The Iq can be defined as the standing current of the LP3906 when the I2C bus is active and all other power blocks have been disabled via the I2C bus, or it can be defined as the I2C bus active, and the other power blocks are active under no load condition. These two values can be used by the system designer when the LP3906 is powered using a battery. If the user plans to use the HW enable pins to disable each block of the IC please contact the factory applications for IQ details.

I/O ELECTRICAL CHARACTERISTICS

Unless otherwise noted: Typical values and limits appearing in normal type apply for T_J = 25°C. Limits appearing in **boldface type** apply over the entire junction temperature range for operation, T_J = 0°C to +125°C. (1)

Parameter		Test Conditions	Limit		Units
			Min	Max	
V_{IL}	Input Low Level			**0.4**	V
V_{IH}	Input High Level		**1.2**		V

(1) This specification is ensured by design.

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TYPICAL PERFORMANCE CHARACTERISTICS — LDO

T_A = 25°C unless otherwise noted

Output Voltage Change vs Temperature (LDO1) Vin = 4.3V, Vout = 3.3V, 100 mA load

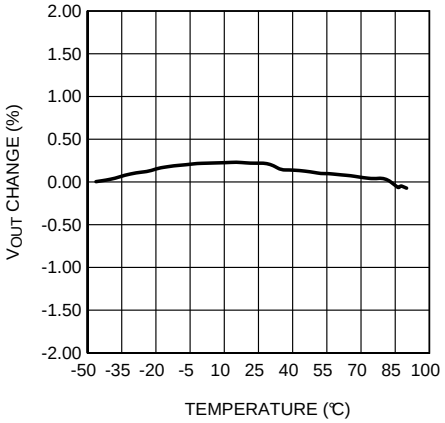


Figure 4.

Output Voltage Change vs Temperature (LDO2) Vin = 4.3V, Vout = 1.8V, 100 mA load

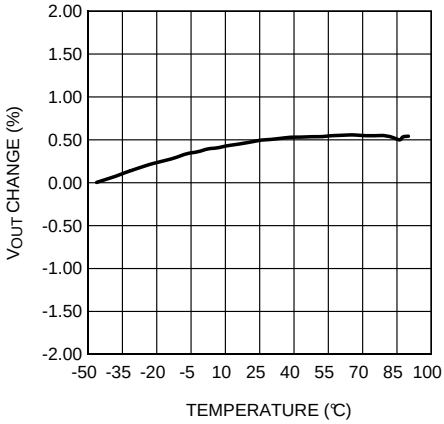


Figure 5.

Load Transient (LDO1) 3.6 Vin, 3.3 Vout, 0 – 100 mA load

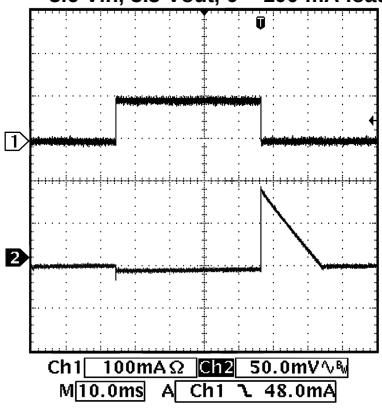


Figure 6.

Load Transient (LDO2) 3.6 Vin, 1.8 Vout, 0 – 100 mA load

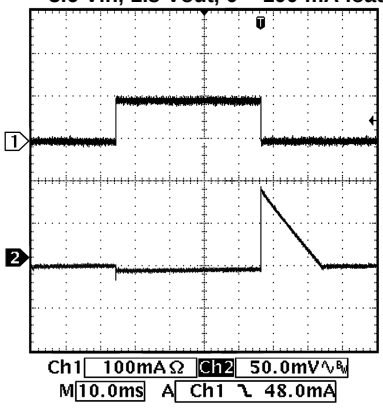


Figure 7.

Line Transient (LDO1) 3.6 - 4.5 Vin, 3.3 Vout, 150 mA load

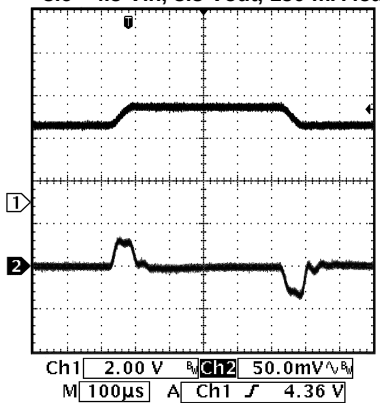


Figure 8.

Line Transient (LDO2) 3 – 4.2 Vin, 1.8 Vout, 150 mA load

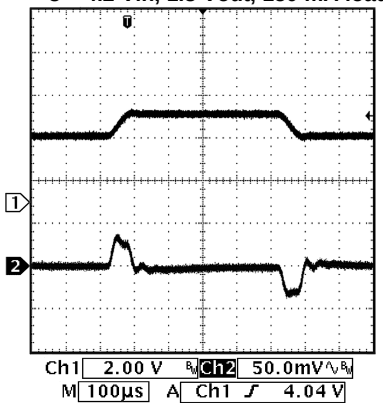


Figure 9.

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TYPICAL PERFORMANCE CHARACTERISTICS — LDO (continued)

T_A = 25°C unless otherwise noted

Enable Start-up time (LDO1))
0-3.6 Vin, 3.3 Vout, 1mA load

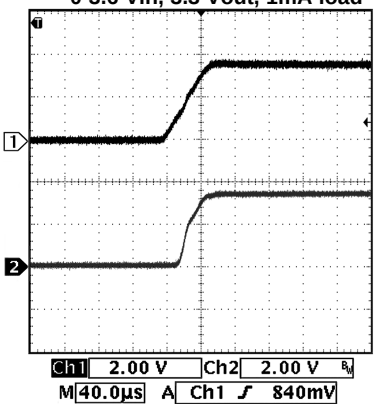


Figure 10.

Enable Start-up time (LDO2)
0 – 3.6 Vin, 1.8 Vout, 1 mA load

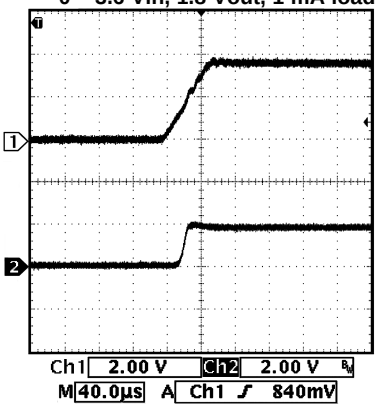


Figure 11.

TYPICAL PERFORMANCE CHARACTERISTICS — BUCK

T_A = 25°C unless otherwise noted

Shutdown Current vs. Temp

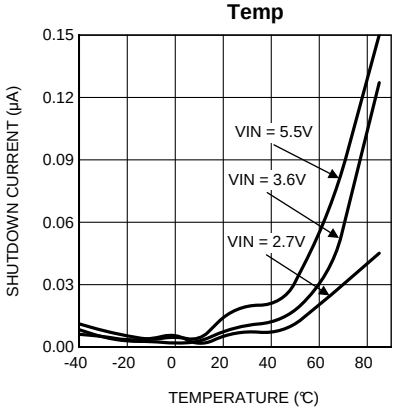


Figure 12.

Output Voltage vs. Supply Voltage (Vout = 1.0 V)

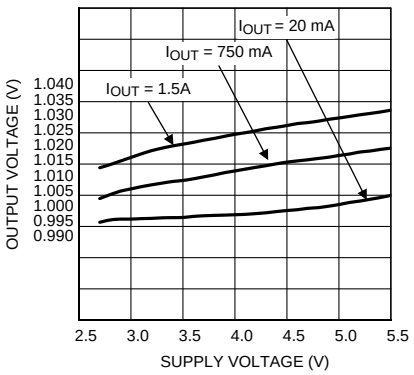


Figure 13.

Output Voltage vs. Supply Voltage (Vout = 1.8V)

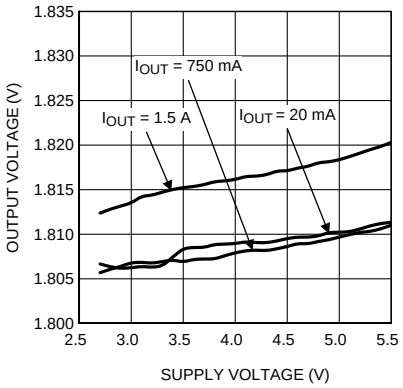


Figure 14.

Output Voltage vs. Supply Voltage (Vout = 3.5V)

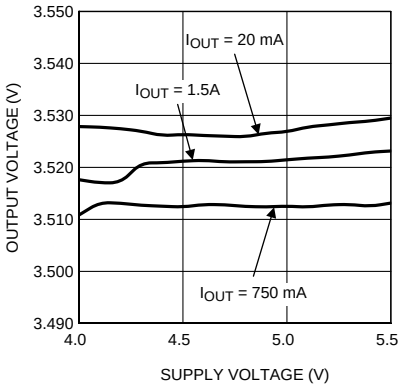


Figure 15.

Buck 1 Efficiency vs Output Current (Forced PWM Mode, Vout =1.2V, L= 2.2µH)

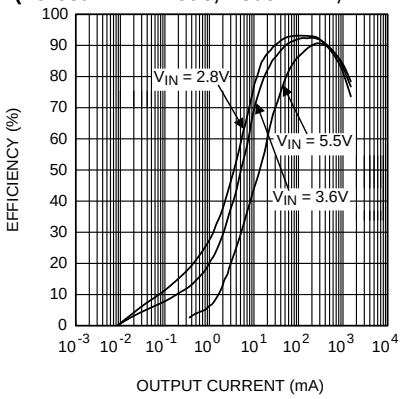


Figure 16.

Buck 1 Efficiency vs Output Current (Forced PWM Mode, Vout =2.0V, L= 2.2µH)

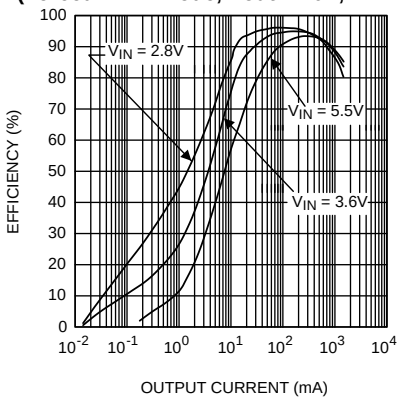


Figure 17.

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TYPICAL PERFORMANCE CHARACTERISTICS — BUCK (continued)

T_A = 25°C unless otherwise noted

Buck 1 Efficiency vs Output Current (PFM to PWM mode, Vout =1.2V, L= 2.2µH)

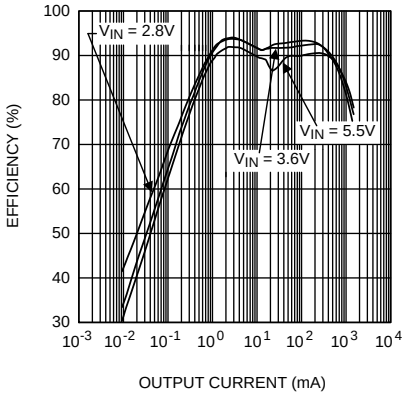


Figure 18.

Buck 1 Efficiency vs Output Current (PFM to PWM mode, Vout =2.0V, L= 2.2µH)

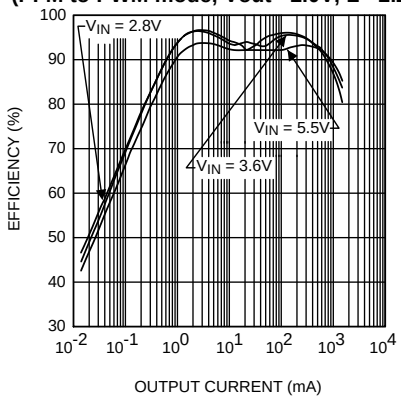


Figure 19.

Buck 2 Efficiency vs Output Current (Forced PWM Mode, Vout =1.8V, L= 2.2µH)

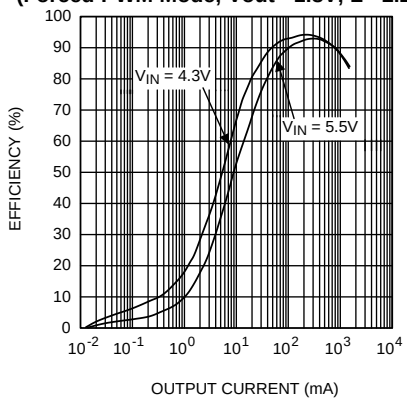


Figure 20.

Buck 2 Efficiency vs Output Current (Forced PWM Mode, Vout =3.3V, L= 2.2µH)

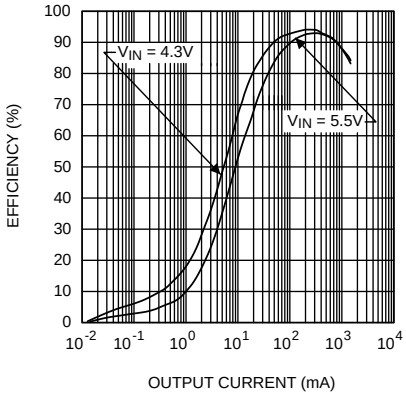


Figure 21.

Buck 2 Efficiency vs Output Current (PFM to PWM Mode, Vout =1.8V, L= 2.2µH)

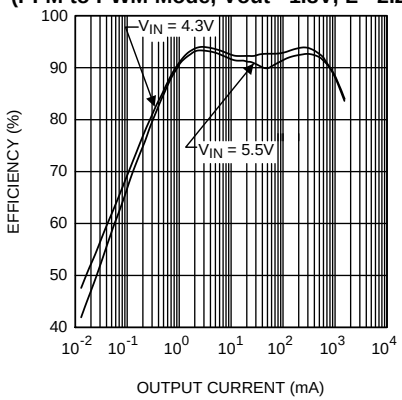


Figure 22.

Buck 2 Efficiency vs Output Current (PFM to PWM Mode, Vout =3.3V, L= 2.2µH)

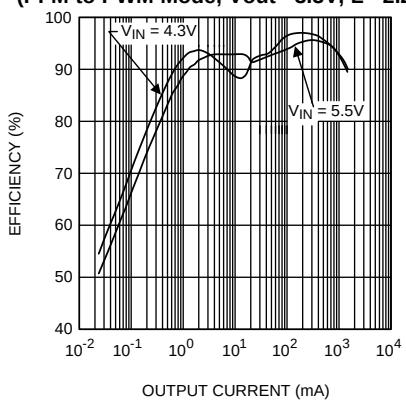


Figure 23.

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TYPICAL PERFORMANCE CHARACTERISTICS — BUCK (continued)

T_A = 25°C unless otherwise noted

Load Transient Response
Vout = 1.2 (PWM Mode)

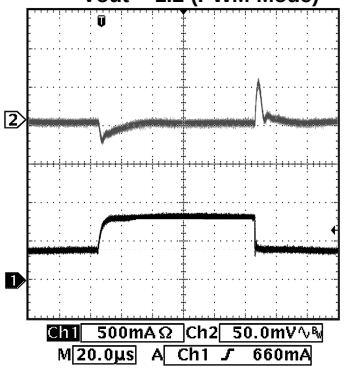


Figure 24.

Mode Change by Load Transient
Vout = 1.2V (PWM to PFM)

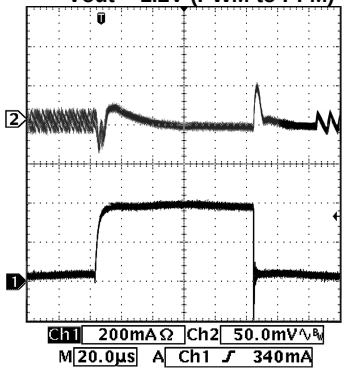


Figure 25.

Line Transient Response
Vin = 3 – 3.6 V, Vout = 1.2 V, 250 mA load

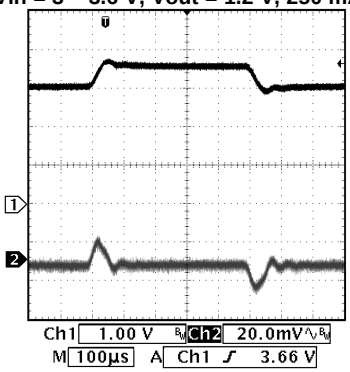


Figure 26.

Line Transient Response
Vin = 3 – 3.6 V, Vout = 3.3 V, 250 mA load

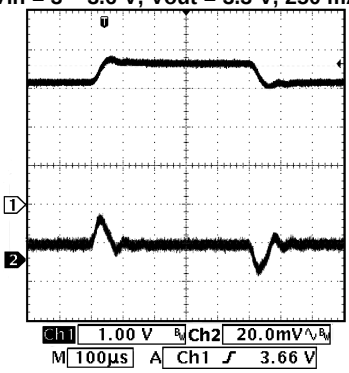


Figure 27.

Start up into PWM Mode
Vout = 1.8 V, 1.2 A load

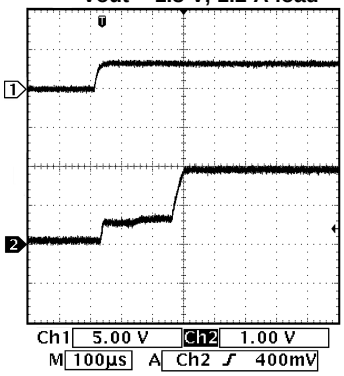


Figure 28.

Start up into PWM Mode
Vout = 3.3 V, 1.2 A load

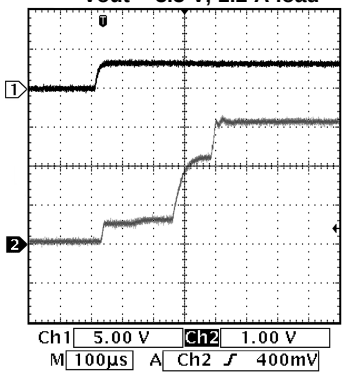


Figure 29.

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TYPICAL PERFORMANCE CHARACTERISTICS — BUCK (continued)

T_A = 25°C unless otherwise noted

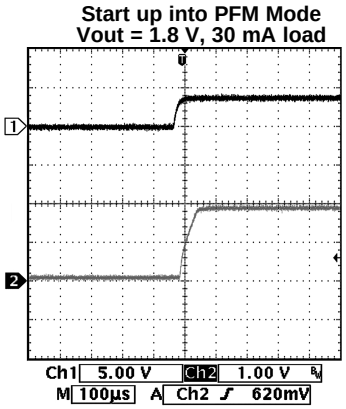


Figure 30.

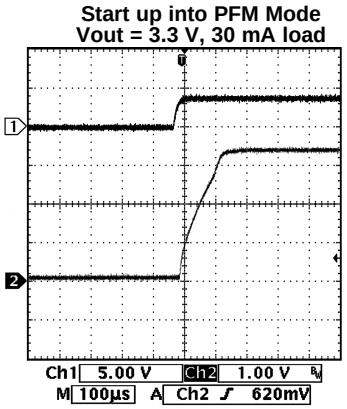


Figure 31.

HIGH VIN-HIGH LOAD OPERATION

Additional information is provided when the IC is operated at extremes of Vin and regulator loads. These are described in terms of the Junction Temperature and Buck Output Ripple Management.

Junction Temperature

The maximum junction temperature TJ-MAX-OP of 125ºC of the IC package.

The following equations demonstrate junction temperature determination, ambient temperature TA-MAX and Total chip power must be controlled to keep TJ below this maximum:

TJ-MAX-OP = TA-MAX + (θJA) [°C/ Watt] * (PD-MAX) [Watts]

Total IC power dissipation PD-MAX is the sum of the individual power dissipation of the four regulators plus a minor amount for chip overhead. Chip overhead is Bias, TSD & LDO analog.

PD-MAX = P_{LDO1} + P_{LD02} + P_{BUCK1} + P_{BUCK2} + (0.0001A * Vin) [Watts].

Power dissipation of LDO1

P_{LDO1} = (Vin_{LDO1}- $Vout_{LDO1}$) * $Iout_{LDO1}$ [V*A]

Power dissipation of LDO2

P_{LDO2} = (Vin_{LDO2} - $Vout_{LDO2}$) * $Iout_{LDO2}$ [V*A]

Power dissipation of Buck1

P_{Buck1} = P_{IN} – P_{OUT} =

$Vout_{Buck1}$* $Iout_{Buck1}$ * (1 -η_1) / η_1 [V*A]

η_1 = efficiency of buck 1

Power dissipation of Buck2

P_{Buck2} = P_{IN} – P_{OUT} =

$Vout_{Buck2}$ * $Iout_{Buck2}$ * (1 - η_2) / η_2 [V*A]

η_2 = efficiency of buck 2

η is the efficiency for the specific condition taken from efficiency graphs.

Buck Output Ripple Management

If Vin and ILoad increase, the output ripple associated with the Buck Regulators also increases. Figure 32 shows the safe operating area. To ensure operation in the area of concern it is recommended that the system designer circumvents the output ripple issues to install schottky diodes on the Bucks(s) that are expected to perform under these extreme corner conditions.

(Schottky diodes are recommended to reduce the output ripple if the system requirements include this shaded area of operation. Vin > 5.2 V and Iload > 1.24 A)

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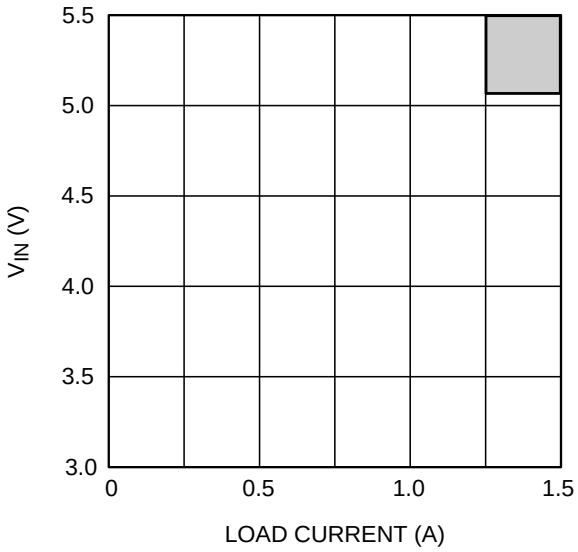


Figure 32. LP3906 Buck Converter V_{IN} vs I_{LOAD} Operating Ranges

Thermal Performance of the WQFN Package

The LP3906 is a monolithic device with integrated power FETs. For that reason, it is important to pay special attention to the thermal impedance of the WQFN package and to the PCB layout rules in order to maximize power dissipation of the WQFN package.

The WQFN package is designed for enhanced thermal performance and features an exposed die attach pad at the bottom center of the package that creates a direct path to the PCB for maximum power dissipation. Compared to the traditional leaded packages where the die attach pad is embedded inside the molding compound, the WQFN reduces one layer in the thermal path.

The thermal advantage of the WQFN package is fully realized only when the exposed die attach pad is soldered down to a thermal land on the PCB board with thermal vias planted underneath the thermal land. Based on thermal analysis of the WQFN package, the junction-to-ambient thermal resistance (θJA) can be improved by a factor of two when the die attach pad of the WQFN package is soldered directly onto the PCB with thermal land and thermal vias, as opposed to an alternative with no direct soldering to a thermal land. Typical pitch and outer diameter for thermal vias are 1.27mm and 0.33mm respectively. Typical copper via barrel plating is 1oz, although thicker copper may be used to further improve thermal performance. The LP3906 die attach pad is connected to the substrate of the IC and therefore, the thermal land and vias on the PCB board need to be connected to ground (GND pin).

For more information on board layout techniques, refer to Application Note AN–1187 (Literature Number SNOA401) “Leadless Lead frame Package (WQFN).” This application note also discusses package handling, solder stencil and the assembly process.

DC/DC Converters

OVERVIEW

The LP3906 supplies the various power needs of the application by means of two Linear Low Drop Regulators LDO1 and LDO2 and two Buck converters SW1 and SW2. The table here under lists the output characteristics of the various regulators.

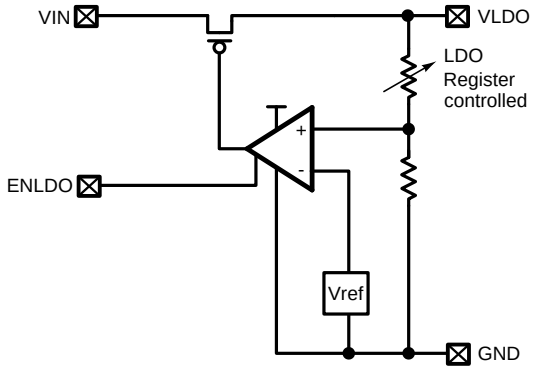
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Table 2. SUPPLY SPECIFICATION

Supply	Load	Output		
		V_{OUT} Range(V)	Resolution (mV)	I_{MAX} Maximum Output Current (mA)
LDO1	analog	1.0 to 3.5	100	300
LDO2	analog	1.0 to 3.5	100	300
SW1	digital	0.8 to 2.0	50	1500
SW2	digital	1.0 to 3.5	100	1500

LINEAR LOW DROP-OUT REGULATORS (LDOS)

LDO1 and LDO2 are identical linear regulators targeting analog loads characterized by low noise requirements. LDO1 and LDO2 are enabled through the ENLDO pin or through the corresponding LDO1 or LDO2 control register. The output voltages of both LDOs are register programmable. The default output voltages are factory programmed during Final Test, which can be tailored to the specific needs of the system designer.



NO-LOAD STABILITY

The LDOs will remain stable and in regulation with no external load. This is an important consideration in some circuits, for example CMOS RAM keep-alive applications.

LDO1 AND LDO2 CONTROL REGISTERS

LDO1 and LDO2 can be configured by means of the LDO1 and LDO2 control registers. The output voltage is programmable in steps of 100mV from 1.0V to 3.5V by programming bits D4-0 in the LDO Control registers. Both LDO1 and LDO2 are enabled by applying a logic 1 to the ENLDO1 and ENLDO2 pin. Enable/disable control is also provided through enable bit of the LDO1 and LDO2 control registers. The value of the enable LDO bit in the register is logic 1 by default. The output voltage can be altered while the LDO is enabled.

SW1, SW2: Synchronous Step Down Magnetic DC/DC Converters

FUNCTIONAL DESCRIPTION

The LP3906 incorporates two high efficiency synchronous switching buck regulators, SW1 and SW2 that deliver a constant voltage from a single Li-Ion battery to the portable system processors. Using a voltage mode architecture with synchronous rectification, both bucks have the ability to deliver up to 1500mA depending on the input voltage and output voltage (voltage head room), and the inductor chosen (maximum current capability).

There are three modes of operation depending on the current required - PWM, PFM, and shutdown. PWM mode handles current loads of approximately 70mA or higher, delivering voltage precision of +/-3% with 90% efficiency or better. Lighter output current loads cause the device to automatically switch into PFM for reduced current consumption (I_Q = 15 µA typ.) and a longer battery life. The Standby operating mode turns off the device, offering the lowest current consumption. PWM or PFM mode is selected automatically or PWM mode can be forced through the setting of the buck control register.

Both SW1 and SW2 can operate up to a 100% duty cycle (PMOS switch always on) for low drop out control of the output voltage. In this way the output voltage will be controlled down to the lowest possible input voltage.

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Additional features include soft-start, under-voltage lock-out, current overload protection, and thermal overload protection.

CIRCUIT OPERATION DESCRIPTION

A buck converter contains a control block, a switching PFET connected between input and output, a synchronous rectifying NFET connected between the output and ground (BCKGND pin) and a feedback path. During the first portion of each switching cycle, the control block turns on the internal PFET switch. This allows current to flow from the input through the inductor to the output filter capacitor and load. The inductor limits the current to a ramp with a slope of

$$\frac{V_{IN} - V_{OUT}}{L} \quad (1)$$

by storing energy in a magnetic field. During the second portion of each cycle, the control block turns the PFET switch off, blocking current flow from the input, and then turns the NFET synchronous rectifier on. The inductor draws current from ground through the NFET to the output filter capacitor and load, which ramps the inductor current down with a slope of

$$\frac{-V_{OUT}}{L} \quad (2)$$

The output filter stores charge when the inductor current is high, and releases it when low, smoothing the voltage across the load.

PWM OPERATION

During PWM operation the converter operates as a voltage-mode controller with input voltage feed forward. This allows the converter to achieve excellent load and line regulation. The DC gain of the power stage is proportional to the input voltage. To eliminate this dependence, feed forward voltage inversely proportional to the input voltage is introduced.

INTERNAL SYNCHRONOUS RECTIFICATION

While in PWM mode, the buck uses an internal NFET as a synchronous rectifier to reduce rectifier forward voltage drop and associated power loss. Synchronous rectification provides a significant improvement in efficiency whenever the output voltage is relatively low compared to the voltage drop across an ordinary rectifier diode.

CURRENT LIMITING

A current limit feature allows the converter to protect itself and external components during overload conditions. PWM mode implements current limiting using an internal comparator that trips at 2.0 A (typ). If the output is shorted to ground the device enters a timed current limit mode where the NFET is turned on for a longer duration until the inductor current falls below a low threshold, ensuring inductor current has more time to decay, thereby preventing runaway.

A current limit feature allows the buck to protect itself and external components during overload conditions PWM mode implements cycle-by-cycle current limiting using an internal comparator that trips at 2000mA (typical).

PFM OPERATION

At very light loads, the converter enters PFM mode and operates with reduced switching frequency and supply current to maintain high efficiency.

The part will automatically transition into PFM mode when either of two conditions occurs for a duration of 32 or more clock cycles:

1. The inductor current becomes discontinuous

   or

2. The peak PMOS switch current drops below the I_{MODE} level

   (Typically $I_{MODE} < 66\ mA + \frac{V_{IN}}{160\Omega}$) (3)

During PFM operation, the converter positions the output voltage slightly higher than the nominal output voltage during PWM operation, allowing additional headroom for voltage drop during a load transient from light to heavy load. The PFM comparators sense the output voltage via the feedback pin and control the switching of the output FETs such that the output voltage ramps between 0.8% and 1.6% (typical) above the nominal PWM output voltage. If the output voltage is below the 'high' PFM comparator threshold, the PMOS power switch is turned on. It remains on until the output voltage exceeds the 'high' PFM threshold or the peak current exceeds the I_{PFM} level set for PFM mode. The typical peak current in PFM mode is:

$$I_{PFM} = 66\ mA + \frac{V_{IN}}{80\Omega} \quad (4)$$

Once the PMOS power switch is turned off, the NMOS power switch is turned on until the inductor current ramps to zero. When the NMOS zero-current condition is detected, the NMOS power switch is turned off. If the output voltage is below the 'high' PFM comparator threshold (see Figure 33), the PMOS switch is again turned on and the cycle is repeated until the output reaches the desired level. Once the output reaches the 'high' PFM threshold, the NMOS switch is turned on briefly to ramp the inductor current to zero and then both output switches are turned off and the part enters an extremely low power mode. Quiescent supply current during this 'sleep' mode is less than 30 µA, which allows the part to achieve high efficiencies under extremely light load conditions. When the output drops below the 'low' PFM threshold, the cycle repeats to restore the output voltage to ~1.6% above the nominal PWM output voltage.

If the load current should increase during PFM mode (see Figure 33) causing the output voltage to fall below the 'low2' PFM threshold, the part will automatically transition into fixed-frequency PWM mode.

SW1, SW2 OPERATION

SW1 and SW2 have selectable output voltages ranging from 0.8V to 3.5V (typ.). Both SW1 and SW2 in the LP3906 are I^2C register controlled and are enabled by default through the internal state machine of the LP3906 following a Power-On event that moves the operating mode to the Active state. (see POWER ON). The SW1 and SW2 output voltages revert to default values when the power on sequence has been completed. The default output voltage for each buck converter is factory programmable. (See APPLICATION NOTES).

SW1, SW2 can be enabled/disabled through the corresponding control register.

The Modulation mode PWM/PFM is by default automatic and depends on the load as described above in the functional description. The modulation mode can be overridden by setting I^2C bit to a logic 1 in the corresponding buck control register, forcing the buck to operate in PWM mode regardless of the load condition.

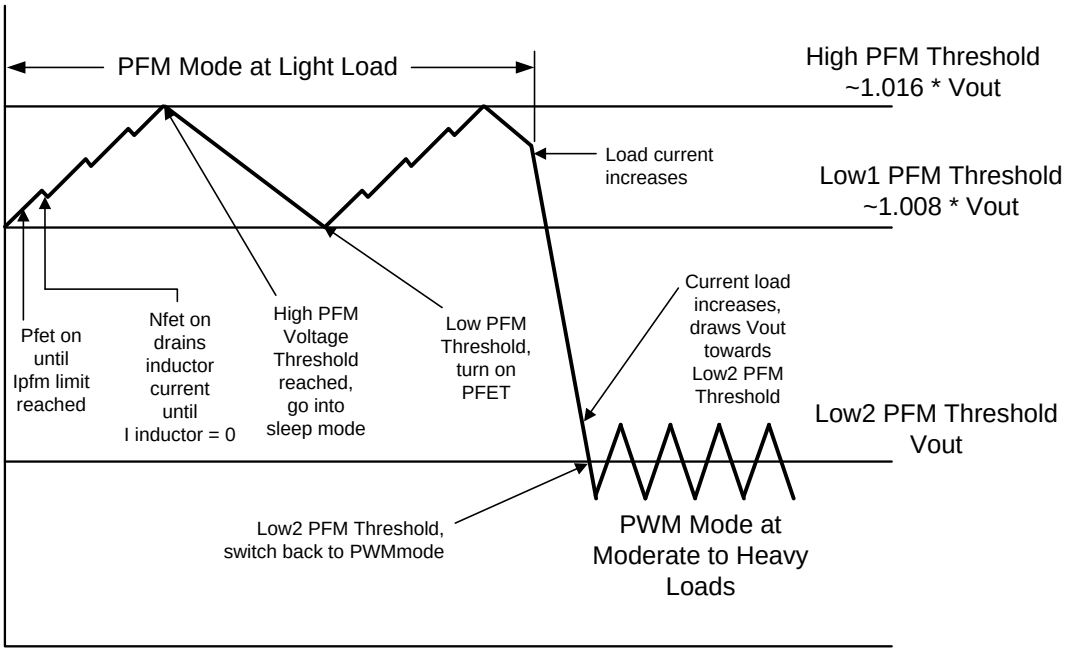


Figure 33.

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SHUTDOWN MODE

During shutdown the PFET switch, reference, control and bias circuitry of the converters are turned off. The NFET switch will be on in shutdown to discharge the output. When the converter is enabled, soft start is activated. It is recommended to disable the converter during the system power up and under voltage conditions when the supply is less than 2.8V.

SOFT START

The soft-start feature allows the power converter to gradually reach the initial steady state operating point, thus reducing start-up stresses and surges. The two LP3906 buck converters have a soft-start circuit that limits in-rush current during start-up. During start-up the switch current limit is increased in steps. Soft start is activated only if EN goes from logic low to logic high after VIN reaches 2.8V. Soft start is implemented by increasing switch current limit in steps of 213 mA, 425 mA, 850 mA and 1700 mA (typ. Switch current limit). The start-up time thereby depends on the output capacitor and load current demanded at start-up.

LOW DROPOUT OPERATION

The LP3906 can operate at 100% duty cycle (noswitching; PMOS switch completely on) for low drop out support of the output voltage. In this way the output voltage will be controlled down to the lowest possible input voltage. When the device operates near 100% duty cycle, output voltage ripple is approximately 25 mV. The minimum input voltage needed to support the output voltage is:

$$V_{IN,\ MIN} = I_{LOAD} * (R_{DSON,\ PFET} + R_{INDUCTOR}) + V_{OUT}$$

Where:

I_{LOAD}	Load current
$R_{DSON,\ PFET}$	Drain to source resistance of PFET switch in the triode region
$R_{INDUCTOR}$	Inductor resistance

FLEXIBLE POWER SEQUENCING OF MULTIPLE POWER SUPPLIES

The LP3906 provides several options for power on sequencing. The two bucks can be individually controlled with ENSW1 and ENSW2. The two LDOs can also be individually controlled with ENLDO1 and ENLDO2.

If the user desires a set power on sequence, all four enables should be tied LOW so that the regulators don't automatically enable when power is supplied. The user can then program the chip through I^2C and raise EN_T from LOW to HIGH to activate the power on sequencing.

POWER ON

EN_T assertion causes the LP3906 to emerge from Standby mode to Full Operation mode at a preset timing sequence. By default, the enables for the LDOs and Bucks are internally pulled up, which causes the part to turn ON automatically. If the user wishes to have a preset timing sequence to power on the regulators, the external regulator enables must be tied LOW. Otherwise, simply tie the enables of each specific regulator HIGH.

EN_T is edge triggered with rising edge signaling the chip to power on. The EN_T input is deglitched and the default is set at 1 ms. As shown in the next 2 diagrams, a rising EN_T edge will start a power on sequence, while a falling EN_T edge will start a shutdown sequence. If EN_T is high, toggling the external enables of the regulators will have no effect on the chip.

Table 3. Default Power ON Sequence:

t_1 (ms)	t_2 (ms)	t_3 (ms)	t_4 (ms)
1.5	2.0	3	6

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NOTE

LP3906 The default Power on delays can be reprogrammed at final test or by using I^2C registers to 1, 1.5, 2, 3, 6, or 11 ms.

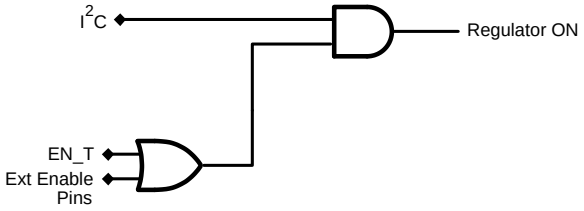
The regulators can also be programmed through I^2C to turn on and off. By default, the I^2C enables for the regulators are ON.

The regulators are on following the pattern below:

Regulators on = (I^2C enable) AND (External pin enable OR EN_T high).

NOTE

The EN_T power-up sequencing may also be employed immediately after V_{IN} is applied to the device. However, V_{IN} must be stable for approximately 8ms minimum before EN_T be asserted high to ensure internal bias, reference, and the Flexible POR timing are stabilized. This initial EN_T delay is necessary only upon first time device power-on for power sequencing function to operate properly.



LP3906 Default Power-Up Sequence

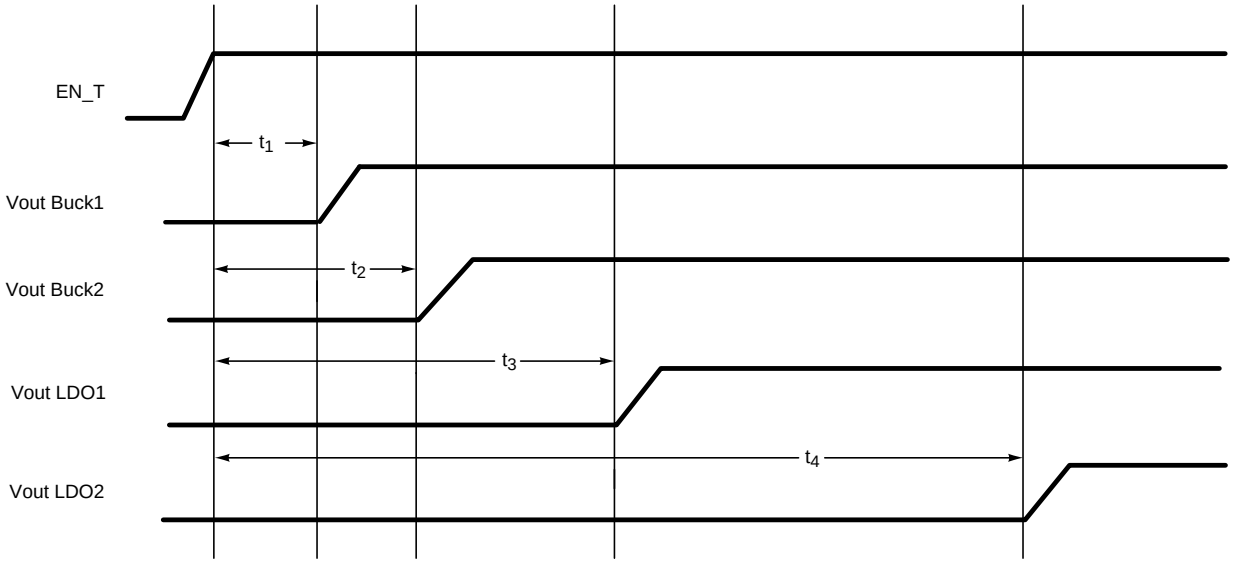


Table 4. Power-On Timing Specification

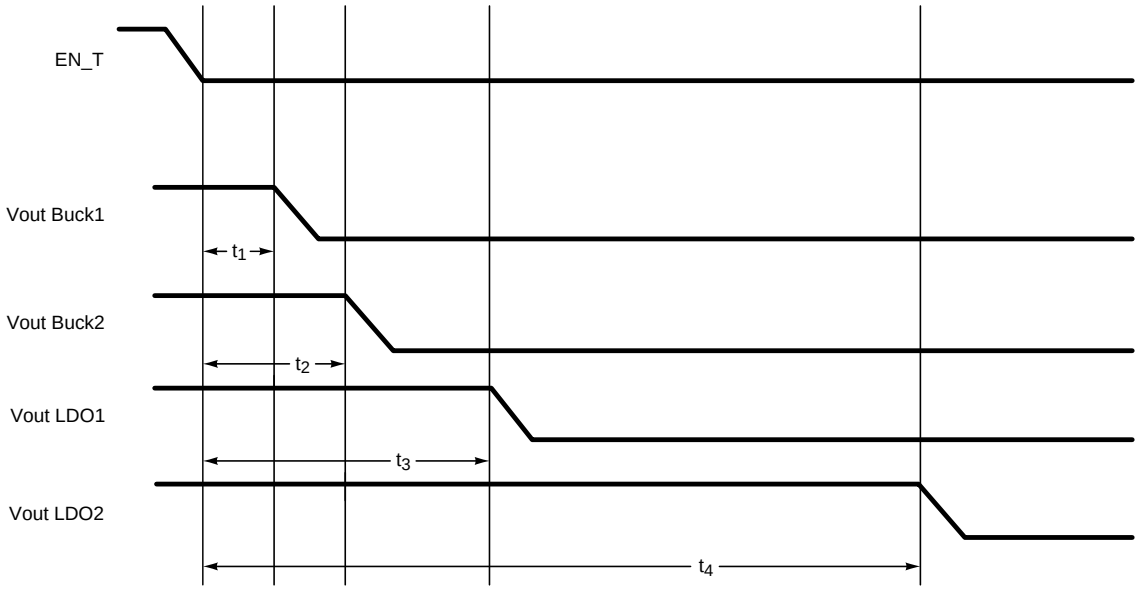
Symbol	Description	Min	Typ	Max	Units
t_1	Programmable Delay from EN_T assertion to V_{CC}_Buck1 On		1.5		ms
t_2	Programmable Delay from EN_T assertion to V_{CC}_Buck2 On		2		ms
t_3	Programmable Delay from EN_T assertion to V_{CC}_LDO1 On		3		ms
t_4	Programmable Delay from EN_T assertion to V_{CC}_LDO2 On		6		ms

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NOTE

LP3906 The default Power on delays can be reprogrammed at final test or I^2C to 1, 1.5, 2, 3, 6, or 11 ms.

LP3906 Default Power-Off Sequence



Symbol	Description	Min	Typ	Max	Units
t_1	Programmable Delay from EN_T deassertion to V_{CC}_Buck1 Off		1.5		ms
t_2	Programmable Delay from EN_T deassertion to V_{CC}_Buck2 Off		2		ms
t_3	Programmable Delay from EN_T deassertion to V_{CC}_LDO1 Off		3		ms
t_4	Programmable Delay from EN_T deassertion to V_{CC}_LDO2 Off		6		ms

NOTE

LP3906 The default Power on delays can be reprogrammed at final test to 0, .5, 1, 2, 5, or 10 ms. Default setting is the same as the on sequence.

Power-On-Reset

The LP3906 is equipped with an internal Power-On-Reset (“POR”) circuit that will reset the logic when VDD < V_{POR}. This ensures that the logic is properly initialized when VDD rises above the minimum operating voltage of the Logic and the internal oscillator that clocks the Sequential Logic in the Control section.

I^2C Compatible Serial Interface

I^2C SIGNALS

The LP3906 features an I^2C compatible serial interface, using two dedicated pins: SCL and SDA for I^2C clock and data respectively. Both signals need a pull-up resistor according to the I^2C specification. The LP3906 interface is an I^2C slave that is clocked by the incoming SCL clock.

Signal timing specifications are according to the I^2C bus specification. The maximum bit rate is 400 kbit/s. See I^2C specification from Philips for further details.

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I²C DATA VALIDITY

The data on the SDA line must be stable during the HIGH period of the clock signal (SCL), e.g.- the state of the data line can only be changed when CLK is LOW.

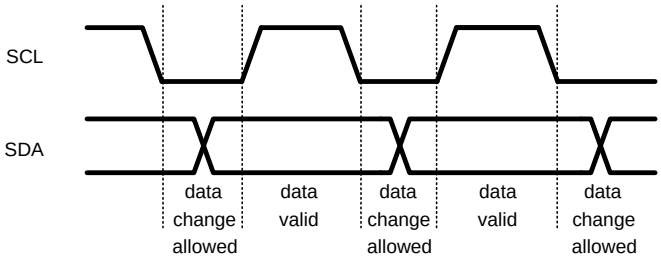


Figure 34. I²C Signals: Data Validity

I²C START AND STOP CONDITIONS

START and STOP bits classify the beginning and the end of the I2C session. START condition is defined as the SDA signal transitioning from HIGH to LOW while the SCL line is HIGH. STOP condition is defined as the SDA transitioning from LOW to HIGH while the SCL is HIGH. The I2C master always generates START and STOP bits. The I2C bus is considered to be busy after START condition and free after STOP condition. During data transmission, I2C master can generate repeated START conditions. First START and repeated START conditions are equivalent, function-wise.

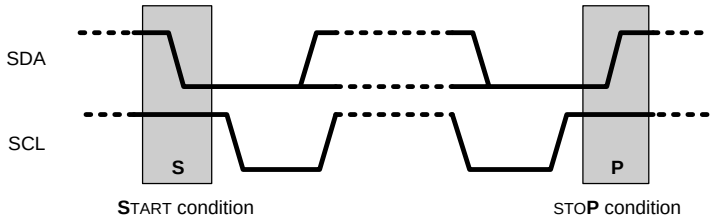


Figure 35. START and STOP Conditions

TRANSFERRING DATA

Every byte put on the SDA line must be eight bits long, with the most significant bit (MSB) being transferred first. Each byte of data has to be followed by an acknowledge bit. The acknowledged related clock pulse is generated by the master. The transmitter releases the SDA line (HIGH) during the acknowledge clock pulse. The receiver must pull down the SDA line during the 9th clock pulse, signifying acknowledgement. A receiver which has been addressed must generate an acknowledgement ("ACK") after each byte has been received.

After the START condition, the I2C master sends a chip address. This address is seven bits long followed by an eighth bit which is a data direction bit (R/W). Please note that according to industry I2C standards for 7-bit addresses, the MSB of an 8-bit address is removed, and communication actually starts with the 7th most significant bit. For the eighth bit (LSB), a "0" indicates a WRITE and a "1" indicates a READ. The second byte selects the register to which the data will be written. The third byte contains data to write to the selected register.

LP3906 has a chip address of 60'h, which is factory programmed.

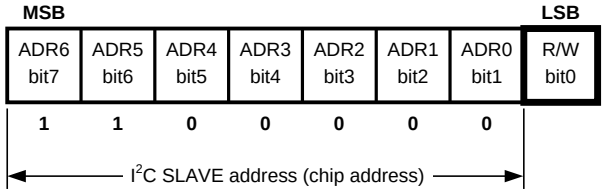
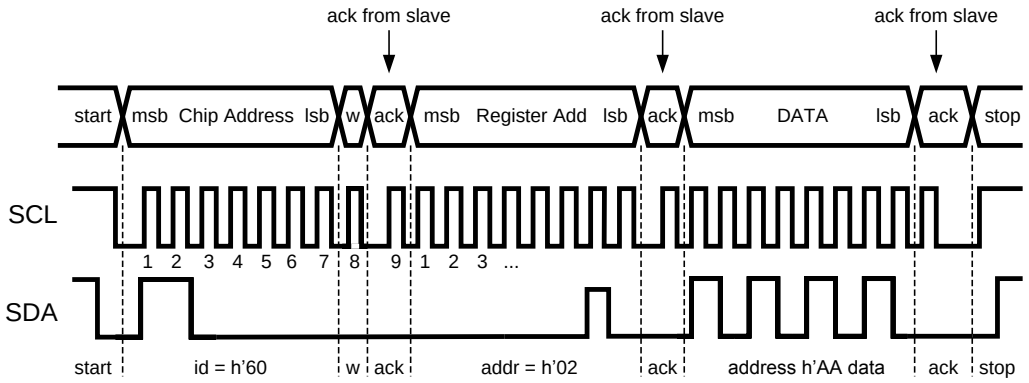


Figure 36. I²C Chip Address

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w = write (SDA = "0")
r = read (SDA = "1")
ack = acknowledge (SDA pulled down by either master or slave)
rs = repeated start
id = LP3906 chip address : **0x60**

Figure 37. I²C Write Cycle

When a READ function is to be accomplished, a WRITE function must precede the READ function, as shown in the Read Cycle waveform.

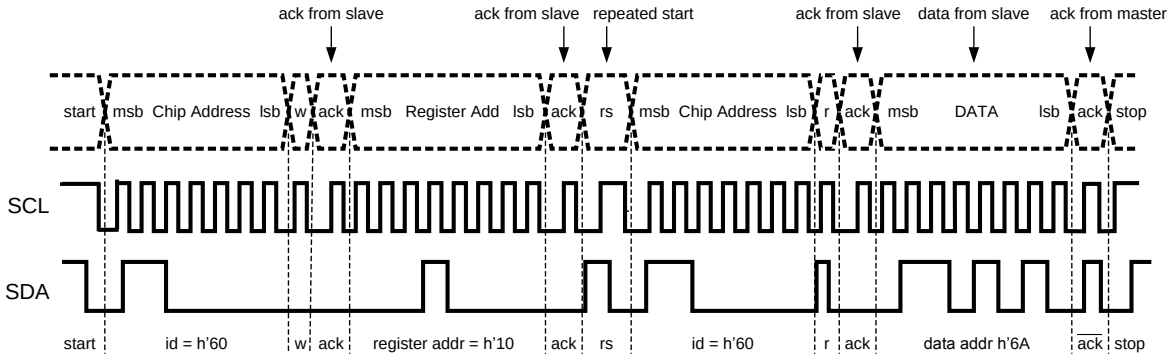


Figure 38. I²C Read Cycle

LP3906 Control Registers

Register Address	Register Name	Read/Write	Register Description
0x02	ICRA	R	Interrupt Status Register A
0x07	SCR1	R/W	System Control 1 Register
0x10	BKLDOEN	R/W	Buck and LDO Output Voltage Enable Register
0x11	BKLDOSR	R	Buck and LDO Output Voltage Status Register
0x20	VCCR	R/W	Voltage Change Control Register 1
0x23	B1TV1	R/W	Buck 1 Target Voltage 1 Register
0x24	B1TV2	R/W	Buck 1 Target Voltage 2 Register
0x25	B1RC	R/W	Buck 1 Ramp Control
0x29	B2TV1	R/W	Buck 2 Target Voltage 1 Register
0x2A	B2TV2	R/W	Buck 2 Target Voltage 2 Register
0x2B	B2RC	R/W	Buck 2 Ramp Control
0x38	BFCR	R/W	Buck Function Register
0x39	LDO1VCR	R/W	LDO1 Voltage control Registers
0x3A	LDO2VCR	R/W	LDO2 Voltage control Registers

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INTERRUPT STATUS REGISTER (ISRA) 0X02

This register informs the user of the temperature status of the chip.

	D7-2	D1	D0
Name	—	Temp 125°C	—
Access	—	R	—
Data	Reserved	Status bit for thermal warning PMIC T>125°C 0 – PMIC Temp. < 125°C 1 – PMIC Temp. > 125°C	Reserved
Reset	0	0	0

CONTROL 1 REGISTER (SCR1) 0X07

This register allows the user to select the preset delay sequence for power-on timing, to switch between PFM and PWM mode for the bucks, and also to select between an internal and external clock for the bucks.

The external LDO and SW enables should be pulled LOW to allow the blocks to sequence correctly through assertion of the EN_T pin.

	D7	D6-4	D3	D2	D1	D0
Name	—	EN_DLY	—	FPWM2	FPWM1	ECEN
Access	—	R/W	—	R/W	R/W	R/W
Data	Reserved	Selects the preset delay sequence from EN_T assertion (shown below)	Reserved	Buck 2 PWM /PFM Mode select 0 – Auto Switch PFM - PWM operation 1 – PWM Mode Only	Buck 1 PWM /PFM Mode select 0 – Auto Switch PFM - PWM operation 1 – PWM Mode Only	External Buck Clock Select 0 – Internal 2 MHz Oscillator clock 1 – External 13 MHz Oscillator clock
Reset	0	010	1	0	0	0

EN_DLY PRESET DELAY SEQUENCE AFTER EN_T ASSERTION

EN_DLY<2:0>	Delay (ms)			
	Buck1	Buck2	LDO1	LDO2
000	1	1	1	1
001	1	1.5	2	2
010	1.5	2	3	6
011	1.5	2	1	1
100	1.5	2	3	6
101	1.5	1.5	2	2
110	3	2	1	1.5
111	2	3	6	11

BUCK AND LDO OUTPUT VOLTAGE ENABLE REGISTER (BKLDOEN) – 0X10

This register controls the enables for the Bucks and LDOs.

	D7	D6	D5	D4	D3	D2	D1	D0
Name	—	LDO2EN	—	LDO1EN	—	BK2EN	—	BK1EN
Access	—	R/W	—	R/W	—	R/W	—	R/W
Data	Reserved	0 – Disable 1 – Enable	Reserved	0 – Disable 1 – Enable	Reserved	0 – Disable 1 – Enable	Reserved	0 – Disable 1 – Enable
Reset	0	1	1	1	0	1	0	1

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BUCK AND LDO STATUS REGISTER (BKLDOSR) – 0X11

This register monitors whether the Bucks and LDOs meet the voltage output specifications.

	D7	D6	D5	D4	D3	D2	D1	D0
Name	BKS_OK	LDOS_OK	LDO2_OK	LDO1_OK	—	BK2_OK	—	BK1_OK
Access	R	R	R	R	—	R	—	R
Data	0 – Buck 1-2 Not Valid 1 – Bucks Valid	0 – LDO 1-2 Not Valid 1 – LDOs Valid	0 – LDO2 Not Valid 1 – LDO2 Valid	0 – LDO1 Not Valid 1 – LDO1 Valid	Reserved	0 – Buck2 Not Valid 1 – Buck2 Valid	Reserved	0 – Buck1 Not Valid 1 – Buck1 Valid
Reset	0	0	0	0	0	0	0	0

BUCK VOLTAGE CHANGE CONTROL REGISTER 1 (VCCR) – 0X20

This register selects and controls the output target voltages for the buck regulators.

	D7-6	D5	D4	D3-2	D1	D0
Name	—	B2VS	B2GO	—	B1VS	B1GO
Access	—	R/W	R/W	—	R/W	R/W
Data	Reserved	Buck2 Target Voltage Select 0 – B2VT1 1 – B2VT2	Buck2 Voltage Ramp CTRL 0 – Hold 1 – Ramp to B2VS selection	Reserved	Buck1 Target Voltage Select 0 – B1VT1 1 – B1VT2	Buck1 Voltage Ramp CTRL 0 – Hold 1 – Ramp to B1VS selection
Reset	00	0	0	00	0	0

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BUCK1 TARGET VOLTAGE 1 REGISTER (B1TV1) – 0X23

This register allows the user to program the output target voltage of Buck 1.

	D7-5	D4-0	
Name	—	BK1_VOUT1	
Access	—	R/W	
Data	Reserved	Buck1 Output Voltage (V)	
		5'h00	Ext Ctrl
		5'h01	0.80
		5'h02	0.85
		5'h03	0.90
		5'h04	0.95
		5'h05	1.00
		5'h06	1.05
		5'h07	1.10
		5'h08	1.15
		5'h09	1.20
		5'h0A	1.25
		5'h0B	1.30
		5'h0C	1.35
		5'h0D	1.40
		5'h0E	1.45
		5'h0F	1.50
		5'h10	1.55
		5'h11	1.60
		5'h12	1.65
		5'h13	1.70
		5'h14	1.75
		5'h15	1.80
		5'h16	1.85
		5'h17	1.90
		5'h18	1.95
		5'h19	2.00
		5'h1A–5'h1F	2.00
Reset	000	Factory Programmed Default	

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BUCK 1 TARGET VOLTAGE 2 REGISTER (B1TV2) – 0X24

This register allows the user to program the output target voltage of Buck 1.

	D7-5	D4-0	
Name	—	BK1_VOUT2	
Access	—	R/W	
Data	Reserved	Buck1 Output Voltage (V)	
		5'h00	Ext Ctrl
		5'h01	0.80
		5'h02	0.85
		5'h03	0.90
		5'h04	0.95
		5'h05	1.00
		5'h06	1.05
		5'h07	1.10
		5'h08	1.15
		5'h09	1.20
		5'h0A	1.25
		5'h0B	1.30
		5'h0C	1.35
		5'h0D	1.40
		5'h0E	1.45
		5'h0F	1.50
		5'h10	1.55
		5'h11	1.60
		5'h12	1.65
		5'h13	1.70
		5'h14	1.75
		5'h15	1.80
		5'h16	1.85
		5'h17	1.90
		5'h18	1.95
		5'h19	2.00
		5'h1A–5'h1F	2.00
Reset	000	Factory Programmed Default	

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BUCK 1 RAMP CONTROL REGISTER (B1RC) - 0x25

This register allows the user to program the rate of change between the target voltages of Buck 1.

	D7	D6-4	D3-0	
Name	- - - -	- - - -	B1RS	
Access	- - - -	- - - -	R/W	
Data	Reserved	Reserved	Data Code	Ramp Rate mV/us
			4h'0	Instant
			4h'1	1
			4h'2	2
			4h'3	3
			4h'4	4
			4h'5	5
			4h'6	6
			4h'7	7
			4h'8	**8**
			4h'9	9
			4h'A	10
			4h'B - 4h'F	10
Reset	0	010	1000	

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BUCK 2 TARGET VOLTAGE 1 REGISTER (B2TV1) – 0X29

This register allows the user to program the output target voltage of Buck 2.

	D7-5	D4-0	
Name	—	BK2_VOUT1	
Access	—	R/W	
Data	Reserved	Buck2 Output Voltage (V)	
		5'h00	Ext Ctrl
		5'h01	1.0
		5'h02	1.1
		5'h03	1.2
		5'h04	1.3
		5'h05	1.4
		5'h06	1.5
		5'h07	1.6
		5'h08	1.7
		5'h09	1.8
		5'h0A	1.9
		5'h0B	2.0
		5'h0C	2.1
		5'h0D	2.2
		5'h0E	2.4
		5'h0F	2.5
		5'h10	2.6
		5'h11	2.7
		5'h12	2.8
		5'h13	2.9
		5'h14	3.0
		5'h15	3.1
		5'h16	3.2
		5'h17	3.3
		5'h18	3.4
		5'h19	3.5
		5'h1A–5'h1F	3.5
Reset	000	Factory Programmed Default	

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BUCK 2 TARGET VOLTAGE 2 REGISTER (B2TV2) – 0X2A

This register allows the user to program the output target voltage of Buck 2.

	D7-5	D4-0	
Name	—	BK2_VOUT2	
Access	—	R/W	
Data	Reserved	Buck2 Output Voltage (V)	
		5'h00	Ext Ctrl
		5'h01	1.0
		5'h02	1.1
		5'h03	1.2
		5'h04	1.3
		5'h05	1.4
		5'h06	1.5
		5'h07	1.6
		5'h08	1.7
		5'h09	1.8
		5'h0A	1.9
		5'h0B	2.0
		5'h0C	2.1
		5'h0D	2.2
		5'h0E	2.4
		5'h0F	2.5
		5'h10	2.6
		5'h11	2.7
		5'h12	2.8
		5'h13	2.9
		5'h14	3.0
		5'h15	3.1
		5'h16	3.2
		5'h17	3.3
		5'h18	3.4
		5'h19	3.5
		5'h1A–5'h1F	3.5
Reset	000	Factory Programmed Default	

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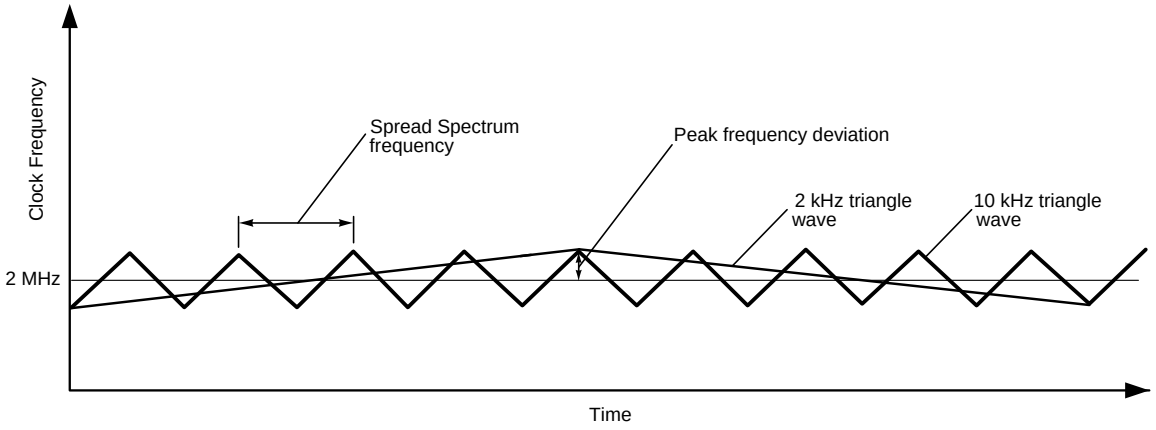
BUCK 2 RAMP CONTROL REGISTER (B2RC) - 0x2B

This register allows the user to program the rate of change between the target voltages of Buck 2

	D7	D6-4	D3-0	
Name	- - - -	- - - -	B2RS	
Access	- - - -	- - - -	R/W	
Data	Reserved	Reserved	Data Code	Ramp Rate mV/us
			4h'0	Instant
			4h'1	1
			4h'2	2
			4h'3	3
			4h'4	4
			4h'5	5
			4h'6	6
			4h'7	7
			4h'8	**8**
			4h'9	9
			4h'A	10
			4h'B - 4h'F	10
Reset	0	010	1000	

BUCK FUNCTION REGISTER (BFCR) – 0x38

This register allows the Buck switcher clock frequency to be spread across a wider range, allowing for less Electro-magnetic Interference (EMI). The spread spectrum modulation frequency refers to the rate at which the frequency ramps up and down, centered at 2 MHz.



	D7-2	D1	D0
Name	—	BK_SLOMOD	BK_SSEN
Access	—	R/W	R/W
Data	Reserved	Buck Spread Spectrum Modulation 0 – 10 kHz triangular wave 1 – 2 kHz triangular wave	Spread Spectrum Function Output 0 – Disabled 1 – Enabled
Reset	000010	1	0

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LDO1 CONTROL REGISTER (LDO1VCR) – 0X39

This register allows the user to program the output target voltage of LDO 1.

	D7-5	D4-0	
Name	—	LDO1_OUT	
Access	—	R/W	
Data	Reserved	LDO1 Output voltage (V)	
		5'h00	1.0
		5'h01	1.1
		5'h02	1.2
		5'h03	1.3
		5'h04	1.4
		5'h05	1.5
		5'h06	1.6
		5'h07	1.7
		5'h08	1.8
		5'h09	1.9
		5'h0A	2.0
		5'h0B	2.1
		5'h0C	2.2
		5'h0D	2.3
		5'h0E	2.4
		5'h0F	2.5
		5'h10	2.6
		5'h11	2.7
		5'h12	2.8
		5'h13	2.9
		5'h14	3.0
		5'h15	3.1
		5'h16	3.2
		5'h17	3.3
		5'h18	3.4
		5'h19	3.5
		5'h1A–5'h1F	3.5
Reset	000	Factory Programmed Default	

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LDO2 CONTROL REGISTER (LDO2VCR) – 0X3A

This register allows the user to program the output target voltage of LDO 2.

	D7-5	D4-0	
Name	—	LDO2_OUT	
Access	—	R/W	
Data	Reserved	LDO2 Output voltage (V)	
		5'h00	1.0
		5'h01	1.1
		5'h02	1.2
		5'h03	1.3
		5'h04	1.4
		5'h05	1.5
		5'h06	1.6
		5'h07	1.7
		5'h08	1.8
		5'h09	1.9
		5'h0A	2.0
		5'h0B	2.1
		5'h0C	2.2
		5'h0D	2.3
		5'h0E	2.4
		5'h0F	2.5
		5'h10	2.6
		5'h11	2.7
		5'h12	2.8
		5'h13	2.9
		5'h14	3.0
		5'h15	3.1
		5'h16	3.2
		5'h17	3.3
		5'h18	3.4
		5'h19	3.5
		5'h1A–5'h1F	3.5
Reset	000	Factory Programmed Default	

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APPLICATION NOTES

SYSTEM CLOCK INPUT (SYNC) PIN

Pin 23 of the chip allows for a system clock input in order to synchronize the buck converters in PWM mode. This is useful if the user wishes to force the bucks to work synchronously with the system. Otherwise, the user should tie the pin to GND and the bucks will operate on an internal 2 MHz clock.

The signal applied to the SYNC pin must be 13 MHz as per application processor specifications, but we can be contacted to modify that specification if so desired. Upon inputting the 13 MHz clock signal, the bucks will scale it down and continue to run at 2 MHz based off the 13 MHz clock.

ANALOG POWER SIGNAL ROUTING

All power inputs should be tied to the main VDD source (i.e. battery), unless the user wishes to power it from another source. (i.e. external LDO output).

The analog VDD inputs power the internal bias and error amplifiers, so they should be tied to the main VDD. The analog VDD inputs must have an input voltage between 2.7 and 5.5 V, as specified on pg. 6 of the datasheet.

The other V_{IN}s (V_{IN}LDO1, V_{IN}LDO2, V_{IN}1, V_{IN}2) can actually have inputs lower than 2.7V, as long as it's higher than the programmed output (+0.3V, to be safe).

The analog and digital grounds should be tied together outside of the chip to reduce noise coupling.

COMPONENT SELECTION

Inductors for SW1 and SW2

There are two main considerations when choosing an inductor; the inductor should not saturate and the inductor current ripple is small enough to achieve the desired output voltage ripple. Care should be taken when reviewing the different saturation current ratings that are specified by different manufacturers. Saturation current ratings are typically specified at 25ºC, so ratings at maximum ambient temperature of the application should be requested from the manufacturer.

There are two methods to choose the inductor saturation current rating:

Method 1

The saturation current is greater than the sum of the maximum load current and the worst case average to peak inductor current. This can be written as follows:

$$I_{sat} > I_{outmax} + I_{ripple}$$

$$\text{where} \quad I_{ripple} = \left(\frac{1}{f}\right) \times \left(\frac{V_{IN} - V_{OUT}}{2L}\right) \times \left(\frac{V_{OUT}}{V_{IN}}\right) \tag{5}$$

I_{RIPPLE}: Average to peak inductor current

I_{OUTMAX}: Maximum load current

V_{IN}: Maximum input voltage to the buck

L: Min inductor value including worse case tolerances (30% drop can be considered for method 1)

f: Minimum switching frequency (1.6 MHz)

V_{OUT}: Buck Output voltage

Method 2

A more conservative and recommended approach is to choose an inductor that has saturation current rating greater than the maximum current limit of 2375 mA.

Given a peak-to-peak current ripple (I_{PP}) the inductor needs to be at least:

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$$L \geq \left(\frac{V_{IN} - V_{OUT}}{I_{PP}}\right) x \left(\frac{V_{OUT}}{V_{IN}}\right) x \left(\frac{1}{f}\right) \quad (6)$$

Inductor	Value	Unit	Description	Notes
$L_{SW}1,2$	2.2	µH	SW1,2 inductor	D.C.R. 70 mΩ

External Capacitors

The regulators on the LP3906 require external capacitors for regulator stability. These are specifically designed for portable applications requiring minimum board space and smallest components. These capacitors must be correctly selected for good performance.

LDO CAPACITOR SELECTION

Input Capacitor

An input capacitor is required for stability. It is recommended that a 1.0 µF capacitor be connected between the LDO input pin and ground (this capacitance value may be increased without limit).

This capacitor must be located a distance of not more than 1 cm from the input pin and returned to a clean analog ground. Any good quality ceramic, tantalum, or film capacitor may be used at the input.

Important: Tantalum capacitors can suffer catastrophic failures due to surge currents when connected to a low impedance source of power (like a battery or a very large capacitor). If a tantalum capacitor is used at the input, it must be ensured by the manufacturer to have a surge current rating sufficient for the application.

There are no requirements for the ESR (Equivalent Series Resistance) on the input capacitor, but tolerance and temperature coefficient must be considered when selecting the capacitor to ensure the capacitance will remain approximately 1.0 µF over the entire operating temperature range.

Output Capacitor

The LDOs on the LP3906 are designed specifically to work with very small ceramic output capacitors. A 1.0 µF ceramic capacitor (temperature types Z5U, Y5V or X7R) with ESR between 5 mΩ to 500 mΩ, are suitable in the application circuit.

It is also possible to use tantalum or film capacitors at the device output, C_{OUT} (or V_{OUT}), but these are not as attractive for reasons of size and cost.

The output capacitor must meet the requirement for the minimum value of capacitance and also have an ESR value that is within the range 5 mΩ to 500 mΩ for stability.

Capacitor Characteristics

The LDOs are designed to work with ceramic capacitors on the output to take advantage of the benefits they offer. For capacitance values in the range of 0.47 µF to 4.7 µF, ceramic capacitors are the smallest, least expensive and have the lowest ESR values, thus making them best for eliminating high frequency noise. The ESR of a typical 1.0 µF ceramic capacitor is in the range of 20 mΩ to 40 mΩ, which easily meets the ESR requirement for stability for the LDOs.

For both input and output capacitors, careful interpretation of the capacitor specification is required to ensure correct device operation. The capacitor value can change greatly, depending on the operating conditions and capacitor type.

In particular, the output capacitor selection should take account of all the capacitor parameters, to ensure that the specification is met within the application. The capacitance can vary with DC bias conditions as well as temperature and frequency of operation. Capacitor values will also show some decrease over time due to aging. The capacitor parameters are also dependent on the particular case size, with smaller sizes giving poorer performance figures in general. As an example, the graph below shows a typical graph comparing different capacitor case sizes in a Capacitance vs. DC Bias plot.

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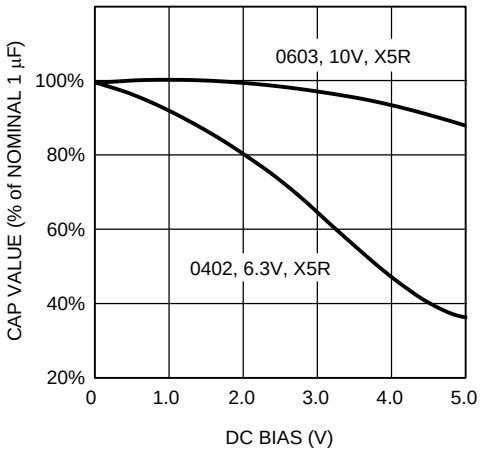


Figure 39. Graph Showing a Typical Variation in Capacitance vs. DC Bias

As shown in the graph, increasing the DC Bias condition can result in the capacitance value that falls below the minimum value given in the recommended capacitor specifications table. Note that the graph shows the capacitance out of spec for the 0402 case size capacitor at higher bias voltages. It is therefore recommended that the capacitor manufacturers' specifications for the nominal value capacitor are consulted for all conditions, as some capacitor sizes (e.g. 0402) may not be suitable in the actual application.

The ceramic capacitor's capacitance can vary with temperature. The capacitor type X7R, which operates over a temperature range of −55°C to +125°C, will only vary the capacitance to within ±15%. The capacitor type X5R has a similar tolerance over a reduced temperature range of −55°C to +85°C. Many large value ceramic capacitors, larger than 1 µF are manufactured with Z5U or Y5V temperature characteristics. Their capacitance can drop by more than 50% as the temperature varies from 25°C to 85°C. Therefore X7R is recommended over Z5U and Y5V in applications where the ambient temperature will change significantly above or below 25°C.

Tantalum capacitors are less desirable than ceramic for use as output capacitors because they are more expensive when comparing equivalent capacitance and voltage ratings in the 0.47 µF to 4.7 µF range.

Another important consideration is that tantalum capacitors have higher ESR values than equivalent size ceramics. This means that while it may be possible to find a tantalum capacitor with an ESR value within the stable range, it would have to be larger in capacitance (which means bigger and more costly) than a ceramic capacitor with the same ESR value. It should also be noted that the ESR of a typical tantalum will increase about 2:1 as the temperature goes from 25°C down to −40°C, so some guard band must be allowed.

Input Capacitor Selection for SW1 and SW2

A ceramic input capacitor of 10 µF, 6.3V is sufficient for the magnetic dc/dc converters. Place the input capacitor as close as possible to the input of the device. A large value may be used for improved input voltage filtering. The recommended capacitor types are X7R or X5R. Y5V type capacitors should not be used. DC bias characteristics of ceramic capacitors must be considered when selecting case sizes like 0805 and 0603. The input filter capacitor supplies current to the PFET switch of the dc/dc converter in the first half of each cycle and reduces voltage ripple imposed on the input power source. A ceramic capacitor's low ESR (Equivalent Series Resistance) provides the best noise filtering of the input voltage spikes due to fast current transients. A capacitor with sufficient ripple current rating should be selected. The Input current ripple can be calculated as:

$$I_{rms} = I_{outmax} \sqrt{\frac{V_{OUT}}{V_{IN}} \left(1 - \frac{V_{OUT}}{V_{IN}} + \frac{r^2}{12}\right)}$$

$$\text{where} \quad r = \frac{(V_{in} - V_{out}) \times V_{out}}{L \times f \times I_{outmax} \times V_{in}} \tag{7}$$

The worse case is when $V_{IN} = 2V_{OUT}$

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Output Capacitor Selection for SW1, SW2

A 10 µF, 6.3V ceramic capacitor should be used on the output of the sw1 and sw2 magnetic dc/dc converters. The output capacitor needs to be mounted as close as possible to the output of the device. A large value may be used for improved input voltage filtering. The recommended capacitor types are X7R or X5R. Y5V type capacitors should not be used. DC bias characteristics of ceramic capacitors must be considered when selecting case sizes like 0805 and 0603. DC bias characteristics vary from manufacturer to manufacturer and DC bias curves should be requested from them and analyzed as part of the capacitor selection process.

The output filter capacitor of the magnetic dc/dc converter smoothes out current flow from the inductor to the load, helps maintain a steady output voltage during transient load changes and reduces output voltage ripple. These capacitors must be selected with sufficient capacitance and sufficiently low ESD to perform these functions.

The output voltage ripple is caused by the charging and discharging of the output capacitor and also due to its ESR and can be calculated as follows:

$$V_{pp\text{-}c} = \frac{I_{ripple}}{4 \times f \times C} \tag{8}$$

Voltage peak-to-peak ripple due to ESR can be expressed as follows:

$$V_{PP-ESR} = 2 \times I_{RIPPLE} \times R_{ESR} \tag{9}$$

Because the $V_{PP\text{-}C}$ and $V_{PP\text{-}ESR}$ are out of phase, the rms value can be used to get an approximate value of the peak-to-peak ripple:

$$V_{pp\text{-}rms} = \sqrt{V_{pp\text{-}c}^{\,2} + V_{pp\text{-}esr}^{\,2}} \tag{10}$$

Note that the output voltage ripple is dependent on the inductor current ripple and the equivalent series resistance of the output capacitor (R_{ESR}). The R_{ESR} is frequency dependent as well as temperature dependent. The R_{ESR} should be calculated with the applicable switching frequency and ambient temperature.

Capacitor	Min Value	Unit	Description	Recommended Type
C_{LDO1}	0.47	µF	LDO1 output capacitor	Ceramic, 6.3V, X5R
C_{LDO2}	0.47	µF	LDO2 output capacitor	Ceramic, 6.3V, X5R
C_{SW1}	10.0	µF	SW1 output capacitor	Ceramic, 6.3V, X5R
C_{SW2}	10.0	µF	SW2 output capacitor	Ceramic, 6.3V, X5R

I^2C Pullup Resistor

Both I^2C_SDA and I^2C_SCL terminals need to have pullup resistors connected to VINLDO12 or to the power supply of the I^2C master. The values of the pull-up resistors (typ. ~1.8kΩ) are determined by the capacitance of the bus. Too large of a resistor combined with a given bus capacitance will result in a rise time that would violate the max. rise time specification. A too small resistor will result in a contention with the pull-down transistor on either slave(s) or master.

Operation without I^2C Interface

Operation of the LP3906 without the I^2C interface is possible if the system can operate with default values for the LDO and Buck regulators. (See Factory Programmable Options .) The I^2C-less system must rely on the correct default output values of the LDO and Buck converters.

Factory Programmable Options

The following options are EPROM programmed during final test of the LP3906. The system designer that needs specific options is advised to contact the local Texas Instruments sales office.

Factory programmable options	Current value
Enable delay for power on	code 010 (see BUCK VOLTAGE CHANGE CONTROL REGISTER 1 (VCCR) – 0X20)
SW1 ramp speed	8 mV/µs
SW2 ramp speed	8 mV/µs

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The I^2C Chip ID address is offered as a metal mask option. The current value equals **0x60.**

MODE BOUNCE

PFM-PWM transition at low load current.

To improve efficiency at lower load currents LP3906 buck converters employ an automatically invoked PFM mode for the low load operation. The PFM mode operates with a much lower value quiescent current (I_Q) than the PWM mode of operation that is used in the higher load currents.

As shown in the datasheet section about SW operation, there is a DC voltage difference between the two modes of operation, with Vout PFM being typically 1.2% higher than Vout PWM. So there is a DC voltage level transition and some associated dynamic perturbation at the mode transition point.

The transition between the two modes of operation has an associated hysterisis in the transition current value, That is, the transition point for increasing current (PFM to PWM) is at a higher value that the decreasing current (PWM to PFM). This hysterisis is to ensure that in the event that the load current values equals the PFM PWM transition value, the device will not make multiple transitions between modes; this reduces the noise at this load by eliminating multiple transitions between modes (also known as mode bounce).

Under some conditions of high Vin and Low Vout the hystersis value is reduced and some amount of mode bounce can occur. Under these conditions, the regulator still maintains DC regulation, however the output ripple is more pronounced. Refer to the attached Vout vs Vin chart below that shows the operational area that may exhibit this increased output ripple. If the application is expected to be operated in the area of concern AND have a static load current of the transition current value, the user can avoid the possible noise increase by invoking the components' "Force PWM mode".

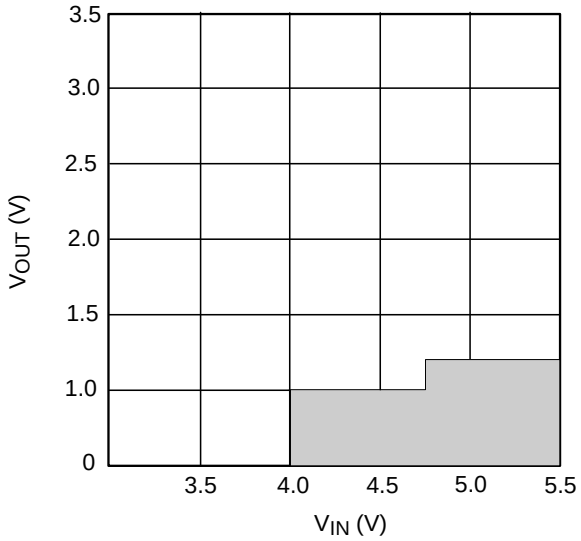


Figure 40. LP3906 Buck Converter V_{OUT} vs V_{IN} Operating Range during PFM-PWM-PPM Transition

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REVISION HISTORY

Changes from Revision L (May 2013) to Revision M	Page
• Changed layout of National Data Sheet to TI format	40

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PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
LP3906SQ-DJXI/NOPB	ACTIVE	WQFN	NHZ	24	1000	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	06-DJXI	Samples
LP3906SQ-FXPI/NOPB	ACTIVE	WQFN	NHZ	24	1000	RoHS & Green	SN	Level-1-260C-UNLIM		06-FXPI	Samples
LP3906SQ-JXXI/NOPB	ACTIVE	WQFN	NHZ	24	1000	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	06-JXXI	Samples
LP3906SQ-VPFP/NOPB	ACTIVE	WQFN	NHZ	24	1000	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	06-VPFP	Samples

(1) The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

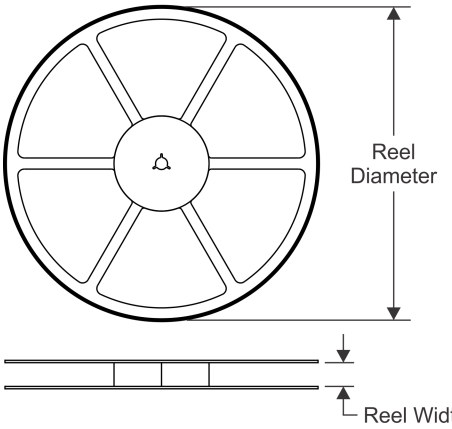
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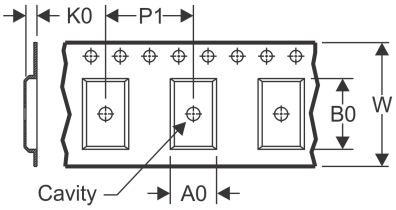
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TAPE AND REEL INFORMATION

REEL DIMENSIONS

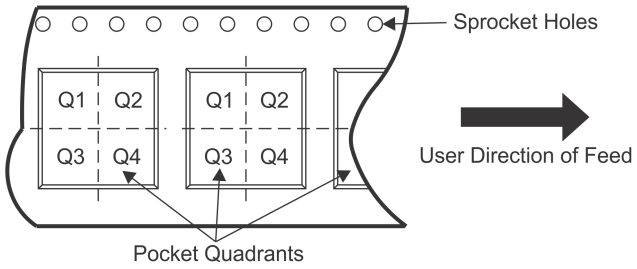


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

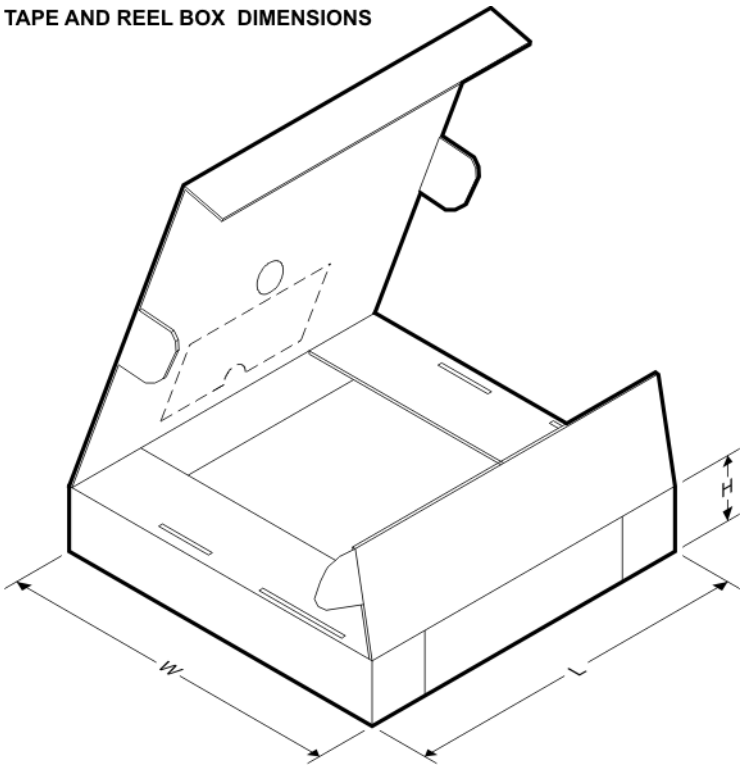
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LP3906SQ-DJXI/NOPB	WQFN	NHZ	24	1000	178.0	12.4	4.3	5.3	1.3	8.0	12.0	Q1
LP3906SQ-FXPI/NOPB	WQFN	NHZ	24	1000	178.0	12.4	4.3	5.3	1.3	8.0	12.0	Q1
LP3906SQ-JXXI/NOPB	WQFN	NHZ	24	1000	178.0	12.4	4.3	5.3	1.3	8.0	12.0	Q1
LP3906SQ-VPFP/NOPB	WQFN	NHZ	24	1000	178.0	12.4	4.3	5.3	1.3	8.0	12.0	Q1

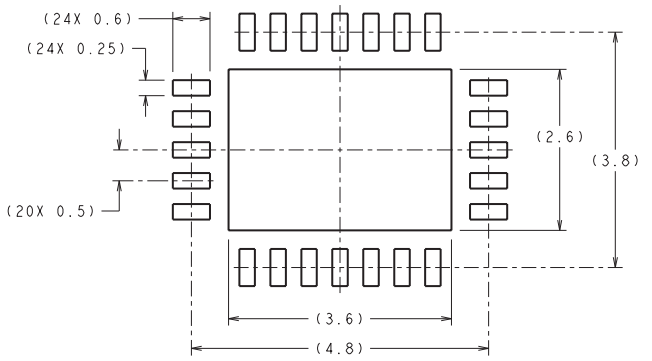
TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

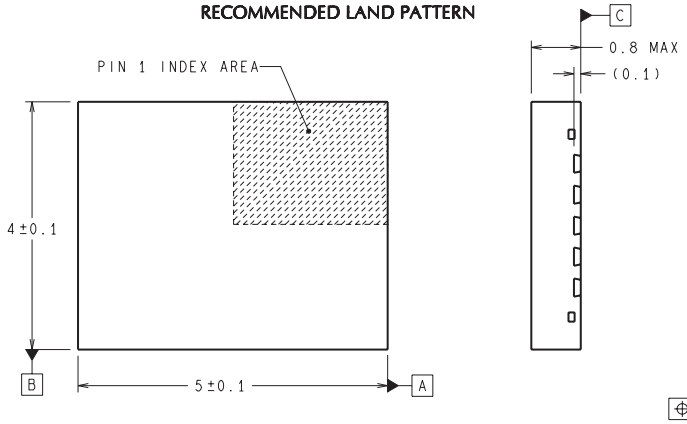
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LP3906SQ-DJXI/NOPB	WQFN	NHZ	24	1000	208.0	191.0	35.0
LP3906SQ-FXPI/NOPB	WQFN	NHZ	24	1000	208.0	191.0	35.0
LP3906SQ-JXXI/NOPB	WQFN	NHZ	24	1000	208.0	191.0	35.0
LP3906SQ-VPFP/NOPB	WQFN	NHZ	24	1000	208.0	191.0	35.0

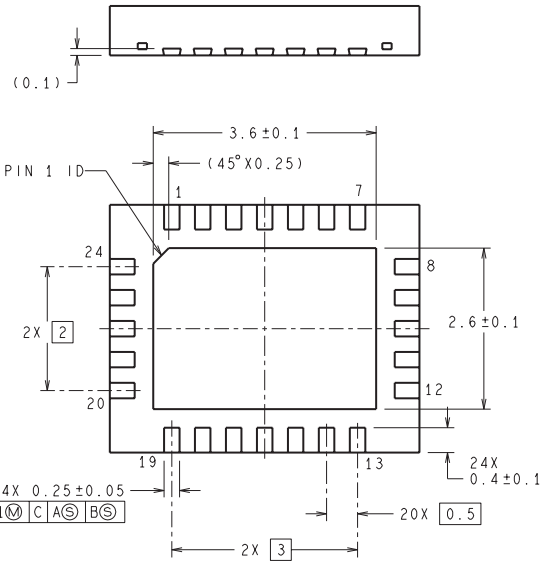
NHZ0024B



RECOMMENDED LAND PATTERN

DIMENSIONS ARE IN MILLIMETERS
DIMENSIONS IN () FOR REFERENCE ONLY





SQA24B (Rev A)

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