

## TMP75B 1.8V 数字温度传感器，具有两线制接口和报警功能

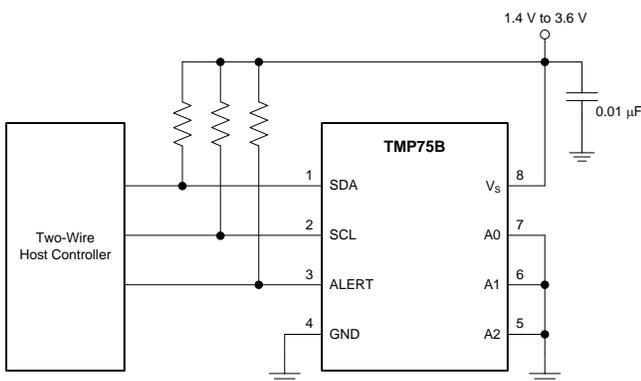
### 1 特性

- LM75 和 TMP75 的低压替代产品
- 具有标准两线制串行接口的数字输出
- 多达 8 个引脚可编程总线地址
- 具有可编程触发值的过热 ALERT 引脚
- 用于节省电池电量的关断模式
- 针对定制更新率的单次转换模式
- 工作温度范围:  $-55^{\circ}\text{C}$  至  $+125^{\circ}\text{C}$
- 工作电源范围: 1.4V 至 3.6V
- 静态电流:
  - 激活时  $45\mu\text{A}$  (典型值)
  - 关断时  $0.3\mu\text{A}$  (典型值)
- 准确度:
  - 温度范围  $-20^{\circ}\text{C}$  至  $+85^{\circ}\text{C}$  时为  $\pm 0.5^{\circ}\text{C}$  (典型值)
  - $-55^{\circ}\text{C}$  至  $+125^{\circ}\text{C}$  范围内为  $\pm 1^{\circ}\text{C}$  (典型值)
- 分辨率: 12 位 ( $0.0625^{\circ}\text{C}$ )
- 封装: 小外形尺寸集成电路 (SOIC)-8 和超薄小外形尺寸封装 (VSSOP)-8

### 2 应用范围

- 服务器和计算机热管理
- 电信设备
- 办公机器
- 视频游戏控制台
- 机顶盒
- 电源和电池热保护
- 恒温器控制
- 环境监测和供热通风与空气调节 (HVAC)
- 电机驱动器热保护

简化电路原理图



### 3 说明

TMP75B 是一款集成数字温度传感器，此传感器具有一个可由 1.8V 电源供电运行的 12 位模数转换器 (ADC)，并且与行业标准 LM75 和 TMP75 引脚和寄存器兼容。此器件采用 SOIC-8 和 VSSOP-8 两种封装，不需要外部元件便可测温。TMP75B 能够以  $0.0625^{\circ}\text{C}$  的分辨率读取温度，并且可在  $-55^{\circ}\text{C}$  至  $+125^{\circ}\text{C}$  的温度范围内额定运行。

TMP75B 特有系统管理总线 (SMBus) 和两线制接口兼容性，并且可在同一总线上，借助 SMBus 过热报警功能支持多达 8 个器件。可编程温度限值和 ALERT 引脚可使传感器运行为一个独立恒温器，或者一个针对节能或系统关断的过热警报器。

厂家校准温度精度和抗扰数字接口使得 TMP75B 成为其他传感器和电子元器件温度补偿的合适解决方案，而且无需针对分布式温度感测的额外系统级校准或复杂的电路板布局布线。

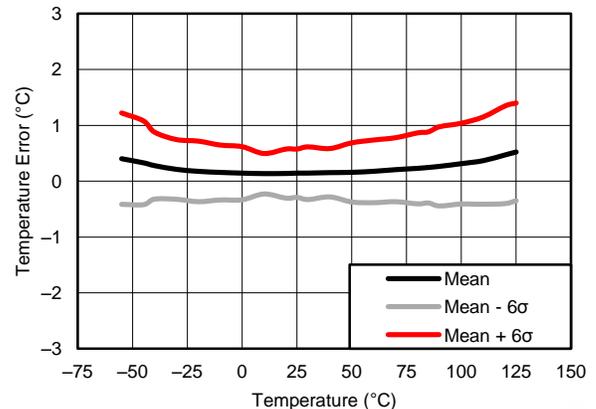
TMP75B 是多种消费类、计算机、通信、工业和环境应用热管理和保护的理想选择。

器件信息<sup>(1)</sup>

| 器件名称   | 封装        | 封装尺寸 (标称值)      |
|--------|-----------|-----------------|
| TMP75B | SOIC (8)  | 4.90mm × 3.90mm |
|        | VSSOP (8) | 3.00mm × 3.00mm |

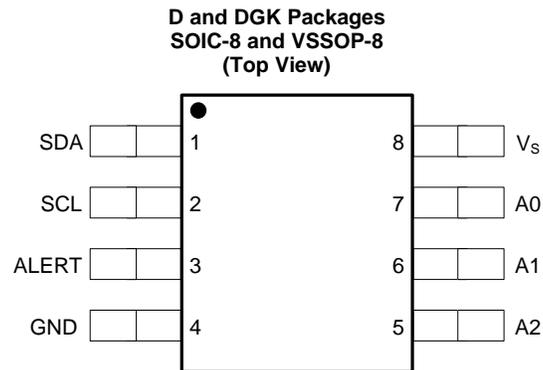
(1) 要了解所有可用封装，请见数据表末尾的封装选项附录。

温度精度 (误差) 与环境温度之间的关系





## 5 Pin Configuration and Functions



### Pin Functions

| PIN   |     | I/O | DESCRIPTION  |
|-------|-----|-----|--|
| NAME  | NO. |     |  |
| A0    | 7   | I   | Address select. Connect to GND or $V_S$ .                              |
| A1    | 6   | I   | Address select. Connect to GND or $V_S$ .                              |
| A2    | 5   | I   | Address select. Connect to GND or $V_S$ .                              |
| ALERT | 3   | O   | Overtemperature alert. Open-drain output; requires a pull-up resistor. |
| GND   | 4   | —   | Ground.  |
| SCL   | 2   | I   | Serial clock.  |
| SDA   | 1   | I/O | Serial data. Open-drain output; requires a pull-up resistor.           |
| $V_S$ | 8   | I   | Supply voltage, 1.4 V to 3.6 V.  |

## 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) <sup>(1)</sup>

|                                |                         | MIN  | MAX           | UNIT |
|--------------------------------|-------------------------|------|---------------|------|
| Supply voltage, $V_S$          |                         |      | 4             | V    |
| Input voltage                  | SDA, SCL, ALERT, A2, A1 | -0.3 | 4             | V    |
|                                | A0                      | -0.3 | $(V_S) + 0.3$ | V    |
| Sink current                   | SDA, ALERT              |      | 10            | mA   |
| Operating junction temperature |                         | -55  | 150           | °C   |

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 6.2 Handling Ratings

|             |                           |  | MIN   | MAX  | UNIT |
|-------------|---------------------------|--|-------|------|------|
| $T_{stg}$   | Storage temperature range |  | -60   | 150  | °C   |
| $V_{(ESD)}$ | Electrostatic discharge   | Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>              | -2000 | 2000 | V    |
|             |                           | Charged device model (CDM), per JEDEC specification JESD22-C101, all pins <sup>(2)</sup> | -1000 | 1000 |      |

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

|                                       |  | MIN | NOM | MAX | UNIT |
|---------------------------------------|--|-----|-----|-----|------|
| Supply voltage                        |  | 1.4 | 1.8 | 3.6 | V    |
| Operating free-air temperature, $T_A$ |  | -55 |     | 125 | °C   |

### 6.4 Thermal Information

| THERMAL METRIC <sup>(1)</sup> |  | TMP75B   |             | UNIT |
|-------------------------------|--|----------|-------------|------|
|                               |  | D (SOIC) | DGK (VSSOP) |      |
|                               |  | 8 PINS   | 8 PINS      |      |
| $R_{\theta JA}$               | Junction-to-ambient thermal resistance       | 125.4    | 188.1       | °C/W |
| $R_{\theta JC(top)}$          | Junction-to-case (top) thermal resistance    | 71.5     | 79.1        |      |
| $R_{\theta JB}$               | Junction-to-board thermal resistance         | 65.8     | 109.6       |      |
| $\Psi_{JT}$                   | Junction-to-top characterization parameter   | 21.1     | 15.3        |      |
| $\Psi_{JB}$                   | Junction-to-board characterization parameter | 65.3     | 108         |      |
| $R_{\theta JC(bot)}$          | Junction-to-case (bottom) thermal resistance | N/A      | N/A         |      |

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).

## 6.5 Electrical Characteristics

At  $T_A = -55^\circ\text{C}$  to  $+125^\circ\text{C}$  and  $V_S = +1.4\text{ V}$  to  $+3.6\text{ V}$ , unless otherwise noted. Typical values at  $T_A = 25^\circ\text{C}$  and  $V_S = +1.8\text{ V}$ .

| PARAMETER                    | TEST CONDITIONS                             | MIN   | TYP       | MAX        | UNIT             |               |
|------------------------------|---|---|-----------|------------|------------------|---------------|
| <b>TEMPERATURE INPUT</b>     |   |   |           |            |                  |               |
| Temperature range            |   | -55   |           | +125       | $^\circ\text{C}$ |               |
| Temperature resolution       |   |   | 0.0625    |            | $^\circ\text{C}$ |               |
| Temperature accuracy (error) | $-20^\circ\text{C}$ to $+85^\circ\text{C}$  |   | $\pm 0.5$ | $\pm 2$    | $^\circ\text{C}$ |               |
|                              | $-55^\circ\text{C}$ to $+125^\circ\text{C}$ |   | $\pm 1$   | $\pm 3$    | $^\circ\text{C}$ |               |
| <b>DIGITAL INPUT/OUTPUT</b>  |   |   |           |            |                  |               |
| $V_{IH}$                     | High-level input voltage                    | $0.7(V_S)$                                      |           | $V_S$      | V                |               |
| $V_{IL}$                     | Low-level input voltage                     | -0.3  |           | $0.3(V_S)$ | V                |               |
| $I_{IN}$                     | Input current                               | $0\text{ V} < V_{IN} < (V_S) + 0.3\text{ V}$    |           | 1          | $\mu\text{A}$    |               |
| $V_{OL}$                     | Low-level output voltage                    | $V_S \geq 2\text{ V}, I_{OUT} = 3\text{ mA}$    |           | 0.4        | V                |               |
|                              |   | $V_S < 2\text{ V}, I_{OUT} = 3\text{ mA}$       |           | $0.2(V_S)$ | V                |               |
|                              | ADC resolution                              |   | 12        |            | Bit              |               |
|                              | Conversion time                             | One-shot mode                                   | 20        | 27         | 35               | ms            |
|                              | Conversion modes                            | CR1 = 0, CR0 = 0 (default)                      |           | 37         | Conv/s           |               |
|                              |   | CR1 = 0, CR0 = 1                                |           | 18         | Conv/s           |               |
|                              |   | CR1 = 1, CR0 = 0                                |           | 9          | Conv/s           |               |
|                              |   | CR1 = 1, CR0 = 1                                |           | 4          | Conv/s           |               |
|                              | Timeout time                                |   | 38        | 54         | 70               | ms            |
| <b>POWER SUPPLY</b>          |   |   |           |            |                  |               |
|                              | Operating supply range                      |   | 1.4       |            | 3.6              | V             |
| $I_Q$                        | Quiescent current                           | Serial bus inactive, CR1 = 0, CR0 = 0 (default) |           | 45         | 89               | $\mu\text{A}$ |
|                              |   | Serial bus inactive, CR1 = 0, CR0 = 1           |           | 22         | 48               | $\mu\text{A}$ |
|                              |   | Serial bus inactive, CR1 = 1, CR0 = 0           |           | 12         | 30               | $\mu\text{A}$ |
|                              |   | Serial bus inactive, CR1 = 1, CR0 = 1           |           | 6.5        | 21               | $\mu\text{A}$ |
| $I_{SD}$                     | Shutdown current                            | Serial bus inactive                             |           | 0.3        | 8                | $\mu\text{A}$ |
|                              |   | Serial bus active, SCL frequency = 400 kHz      |           | 10         |                  | $\mu\text{A}$ |
|                              |   | Serial bus active, SCL frequency = 3.4 MHz      |           | 80         |                  | $\mu\text{A}$ |

### 6.6 Typical Characteristics

At  $T_A = 25^\circ\text{C}$  and  $V_S = +1.8\text{ V}$  (unless otherwise noted).

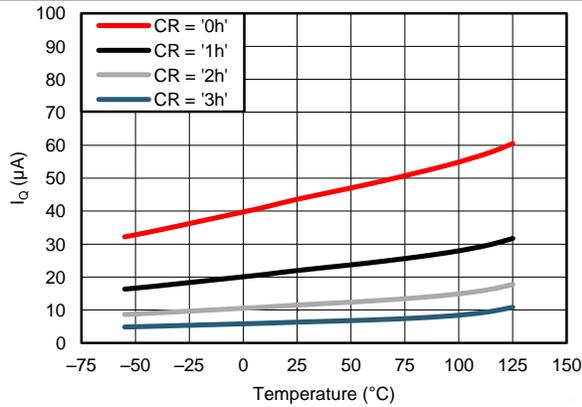


Figure 1. Quiescent Current vs Temperature

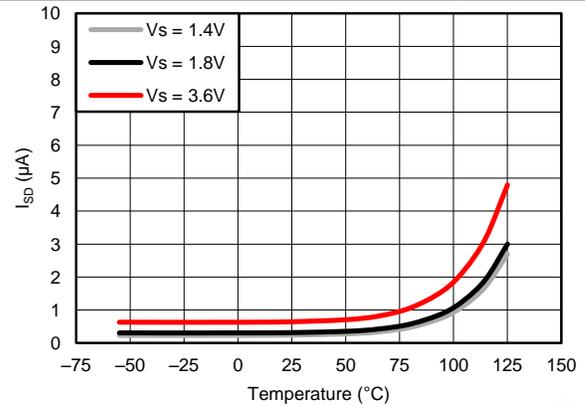


Figure 2. Shutdown Current vs Temperature

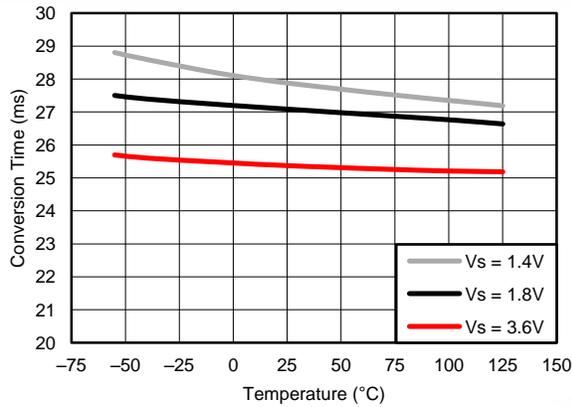


Figure 3. Conversion Time vs Temperature

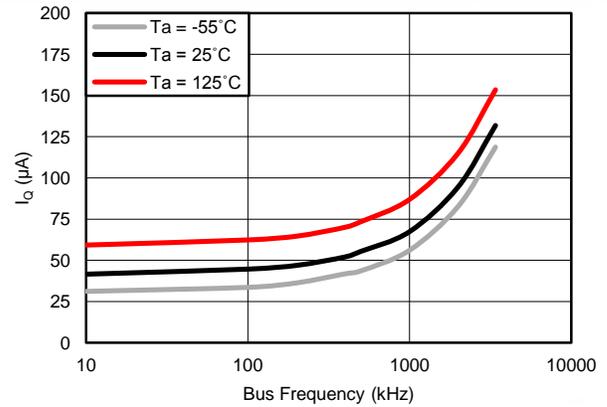


Figure 4. Quiescent Current vs Bus Frequency

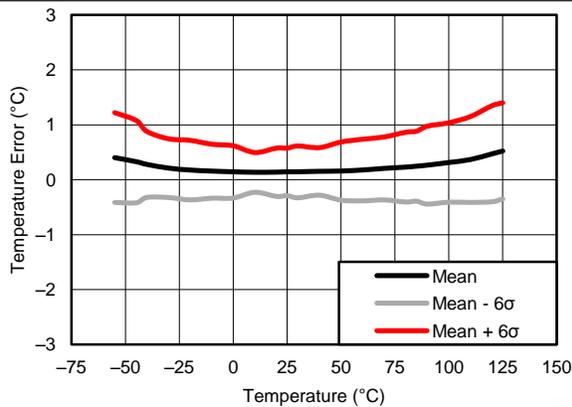


Figure 5. Temperature Error vs Temperature

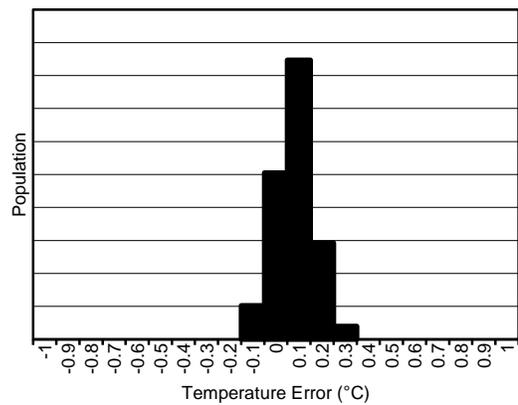


Figure 6. Temperature Error at 25°C

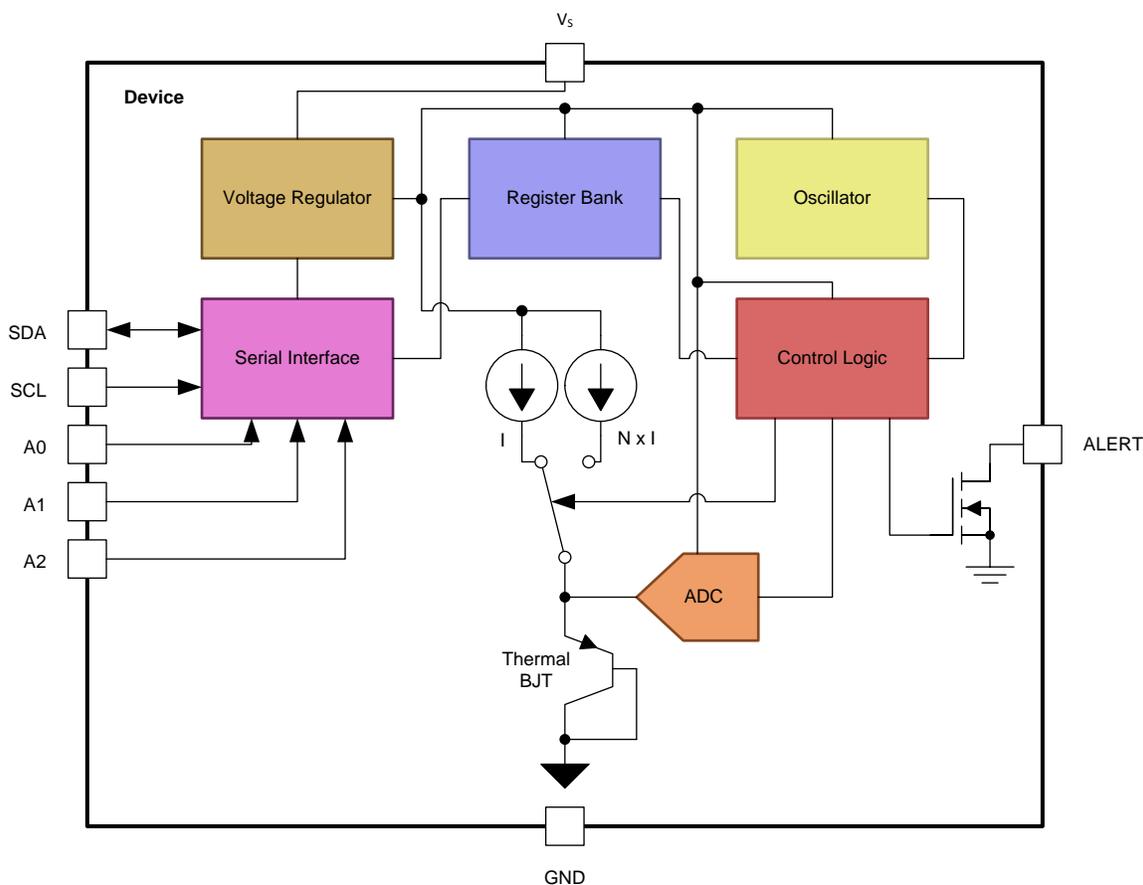
## 7 Detailed Description

### 7.1 Overview

The TMP75B is a digital temperature sensor optimal for thermal management and thermal protection applications. The TMP75B is two-wire and SMBus interface compatible, and is specified over a temperature range of  $-55^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ .

The temperature sensing device for the TMP75B is the chip itself. A bipolar junction transistor (BJT) inside the chip is used in a band-gap configuration to produce a voltage proportional to the chip temperature. The voltage is digitized and converted to a 12-bit temperature result in degrees Celsius, with a resolution of  $0.0625^{\circ}\text{C}$ . The package leads provide the primary thermal path because of the lower thermal resistance of the metal. Thus, the temperature result is equivalent to the local temperature of the printed circuit board (PCB) where the sensor is mounted.

### 7.2 Functional Block Diagram



## 7.3 Feature Description

### 7.3.1 Digital Temperature Output

The 12-bit digital output from each temperature measurement conversion is stored in the read-only temperature register. Two bytes must be read to obtain the data, as shown in [Figure 15](#). Note that byte 1 is the most significant byte, followed by byte 2, the least significant byte. The temperature result is left-justified with the 12 most significant bits used to indicate the temperature. There is no need to read the second byte if resolution below 1°C is not required. [Table 1](#) summarizes the temperature data format. One LSB equals 0.0625°C. Negative numbers are represented in binary twos complement format.

**Table 1. Temperature Data Format<sup>(1)</sup>**

| TEMPERATURE (°C) | DIGITAL OUTPUT |     |
|------------------|----------------|-----|
|                  | BINARY         | HEX |
| 128              | 0111 1111 1111 | 7FF |
| 127.9375         | 0111 1111 1111 | 7FF |
| 100              | 0110 0100 0000 | 640 |
| 80               | 0101 0000 0000 | 500 |
| 75               | 0100 1011 0000 | 4B0 |
| 50               | 0011 0010 0000 | 320 |
| 25               | 0001 1001 0000 | 190 |
| 0.25             | 0000 0000 0100 | 004 |
| 0                | 0000 0000 0000 | 000 |
| -0.25            | 1111 1111 1100 | FFC |
| -25              | 1110 0111 0000 | E70 |
| -55              | 1100 1001 0000 | C90 |

(1) The temperature sensor resolution is 0.0625°C/LSB.

[Table 1](#) does not supply a full list of all temperatures. Use the following rules to obtain the digital data format for a given temperature, and vice versa.

To convert positive temperatures to a digital data format:

Divide the temperature by the resolution. Then, convert the result to binary code with a 12-bit, left-justified format, and MSB = 0 to denote a positive sign.

Example:  $(+50^{\circ}\text{C}) / (0.0625^{\circ}\text{C} / \text{LSB}) = 800 = 320\text{h} = 0011\ 0010\ 0000$

To convert a positive digital data format to temperature:

Convert the 12-bit, left-justified binary temperature result, with the MSB = 0 to denote a positive sign, to a decimal number. Then, multiply the decimal number by the resolution to obtain the positive temperature.

Example:  $0011\ 0010\ 0000 = 320\text{h} = 800 \times (0.0625^{\circ}\text{C} / \text{LSB}) = +50^{\circ}\text{C}$

To convert negative temperatures to a digital data format:

Divide the absolute value of the temperature by the resolution, and convert the result to binary code with a 12-bit, left-justified format. Then, generate the twos complement of the result by complementing the binary number and adding one. Denote a negative number with MSB = 1.

Example:  $(|-25^{\circ}\text{C}|) / (0.0625^{\circ}\text{C} / \text{LSB}) = 400 = 190\text{h} = 0001\ 1001\ 0000$

Two's complement format:  $1110\ 0110\ 1111 + 1 = 1110\ 0111\ 0000$

To convert a negative digital data format to temperature:

Generate the twos complement of the 12-bit, left-justified binary number of the temperature result (with MSB = 1, denoting negative temperature result) by complementing the binary number and adding one. This represents the binary number of the absolute value of the temperature. Convert to decimal number and multiply by the resolution to get the absolute temperature, then multiply by -1 for the negative sign.

Example:  $1110\ 0111\ 0000$  has twos complement of  $0001\ 1001\ 0000 = 0001\ 1000\ 1111 + 1$

Convert to temperature:  $0001\ 1001\ 0000 = 190\text{h} = 400$ ;  $400 \times (0.0625^{\circ}\text{C} / \text{LSB}) = 25^{\circ}\text{C} = (|-25^{\circ}\text{C}|)$ ;  $(|-25^{\circ}\text{C}|) \times (-1) = -25^{\circ}\text{C}$

### 7.3.2 Temperature Limits and Alert

The temperature limits are stored in the  $T_{LOW}$  and  $T_{HIGH}$  registers (Table 8 and Table 9) in the same format as the temperature result, and their values are compared to the temperature result on every conversion. The outcome of the comparison drives the behavior of the ALERT pin, which can operate as a comparator output or an interrupt, and is set by the TM bit in the configuration register (Table 7).

In comparator mode (TM = 0, default), the ALERT pin becomes active when the temperature is equal to or exceeds the value in  $T_{HIGH}$  (fault conditions) for a consecutive number of conversions as set by the FQ bits of the configuration register. ALERT clears when the temperature falls below  $T_{LOW}$  for the same consecutive number of conversions. The difference between the two limits acts as a hysteresis on the comparator output, and a fault counter prevents false alerts as a result of environmental noise.

In interrupt mode (TM = 1), the ALERT pin becomes active when the temperature equals or exceeds the value in  $T_{HIGH}$  for a consecutive number of fault conditions. The ALERT pin remains active until a read operation of any register occurs, or the device successfully responds to the SMBus alert response address. The ALERT pin is also cleared if the device is placed in shutdown mode (see Shutdown Mode section for shutdown mode description). After the ALERT pin is cleared, this pin becomes active again only when the temperature falls below  $T_{LOW}$  for a consecutive number of fault conditions, and remains active until cleared by a read operation of any register, or a successful response to the SMBus alert response address. After the ALERT pin is cleared, the cycle repeats with the ALERT pin becoming active when the temperature equals or exceeds  $T_{HIGH}$ , and so on. The ALERT pin can also be cleared by resetting the device with the general-call reset command. This action also clears the state of the internal registers in the device and the fault counter memory, returning the device to comparator mode (TM = 0).

The active state of the ALERT pin is set by the POL bit in the configuration register. When POL = 0 (default), the ALERT pin is active low. When POL = 1, the ALERT pin is active high. The operation of the ALERT pin in various modes is illustrated in Figure 7.

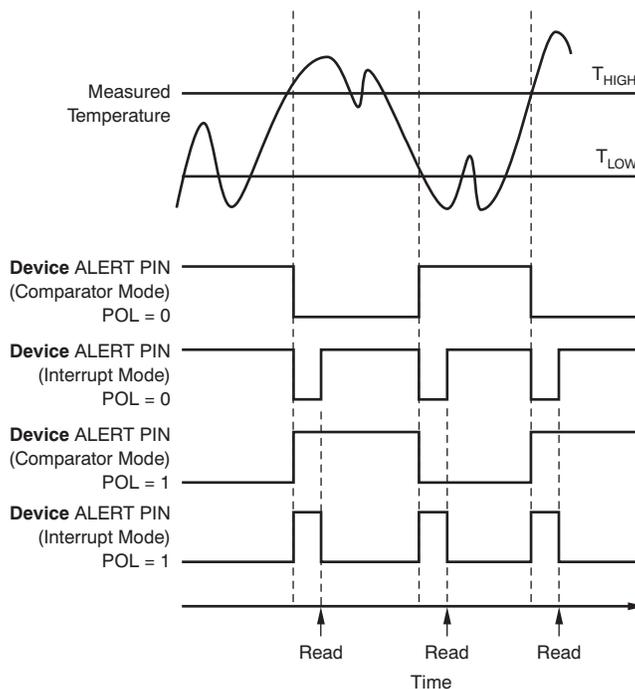


Figure 7. ALERT Pin Modes of Operation

### 7.3.3 Serial Interface

The TMP75B operates as a slave device only on the two-wire bus and SMBus. Connections to the bus are made using the open-drain I/O lines, SDA and SCL. The SDA and SCL pins feature integrated spike-suppression filters and Schmitt triggers to minimize the effects of input spikes and bus noise. The TMP75B supports the transmission protocol for both fast (1 kHz to 400 kHz) and high-speed (1 kHz to 3 MHz) modes. All data bytes are transmitted MSB first.

#### 7.3.3.1 Bus Overview

The device that initiates the transfer is called a *master*, and the devices controlled by the master are *slaves*. The bus must be controlled by a master device that generates the serial clock (SCL), controls the bus access, and generates the start and stop conditions.

To address a specific device, initiate a start condition by pulling the data line (SDA) from a high to a low logic level while SCL is high. All slaves on the bus shift in the slave address byte; the last bit indicates whether a read or write operation follows. During the ninth clock pulse, the slave being addressed responds to the master by generating an acknowledge bit and pulling SDA low.

Data transfer is then initiated and sent over eight clock pulses followed by an acknowledge bit. During data transfer, SDA must remain stable while SCL is high because any change in SDA while SCL is high is interpreted as a start or stop signal.

After all data have been transferred, the master generates a stop condition indicated by pulling SDA from low to high, while SCL is high.

#### 7.3.3.2 Serial Bus Address

To communicate with the TMP75B, the master must first communicate with slave devices using a slave address byte. The slave address byte consists of seven address bits, and a direction bit indicating the intent of executing either a read or write operation. The TMP75B features three address pins that allow up to eight devices to be addressed on a single bus. The TMP75B latches the status of the address pins at the start of a communication. [Table 2](#) describes the pin logic levels and the corresponding address values.

**Table 2. Address Pin Connections and Slave Addresses**

| DEVICE TWO-WIRE ADDRESS | A2             | A1             | A0             |
|-------------------------|----------------|----------------|----------------|
| 1001000                 | GND            | GND            | GND            |
| 1001001                 | GND            | GND            | V <sub>S</sub> |
| 1001010                 | GND            | V <sub>S</sub> | GND            |
| 1001011                 | GND            | V <sub>S</sub> | V <sub>S</sub> |
| 1001100                 | V <sub>S</sub> | GND            | GND            |
| 1001101                 | V <sub>S</sub> | GND            | V <sub>S</sub> |
| 1001110                 | V <sub>S</sub> | V <sub>S</sub> | GND            |
| 1001111                 | V <sub>S</sub> | V <sub>S</sub> | V <sub>S</sub> |

#### 7.3.3.3 Writing and Reading Operation

Accessing a particular register on the TMP75B is accomplished by writing the appropriate value to the pointer register. The value for the pointer register is the first byte transferred after the slave address byte with the R/W bit low. Every write operation to the TMP75B requires a value for the pointer register (see [Figure 9](#)).

When reading from the TMP75B, the last value stored in the pointer register by a write operation is used to determine which register is read by a read operation. To change the register pointer for a read operation, a new value must be written to the pointer register. This action is accomplished by issuing a slave address byte with the R/W bit low, followed by the pointer register byte. No additional data are required. The master can then generate a start condition and send the slave address byte with the R/W bit high to initiate the read command. See [Figure 10](#) for details of this sequence. If repeated reads from the same register are desired, there is no need to continually send the pointer register bytes because the TMP75B stores the pointer register value until it is changed by the next write operation.

Note that register bytes are sent with the most significant byte first, followed by the least significant byte.

### 7.3.3.4 Slave-Mode Operations

The TMP75B can operate as a slave receiver or slave transmitter.

#### 7.3.3.4.1 Slave Receiver Mode:

The first byte transmitted by the master is the slave address, with the  $\overline{R/\overline{W}}$  bit low. The TMP75B then acknowledges reception of a valid address. The next byte transmitted by the master is the pointer register. The TMP75B then acknowledges reception of the pointer register byte. The next byte or bytes are written to the register addressed by the pointer register. The TMP75B acknowledges reception of each data byte. The master can terminate data transfer by generating a start or stop condition.

#### 7.3.3.4.2 Slave Transmitter Mode:

The first byte transmitted by the master is the slave address, with the  $\overline{R/\overline{W}}$  bit high. The slave acknowledges reception of a valid slave address. The next byte is transmitted by the slave and is the most significant byte of the register indicated by the pointer register. The master acknowledges reception of the data byte. The next byte transmitted by the slave is the least significant byte. The master acknowledges reception of the data byte. The master can terminate data transfer by generating a not-acknowledge bit on reception of any data byte, or by generating a start or stop condition.

### 7.3.3.5 SMBus Alert Function

The TMP75B supports the SMBus alert function. When the TMP75B operates in interrupt mode ( $TM = 1$ ), the ALERT pin may be connected as an SMBus alert signal. When a master senses that an alert condition is present on the ALERT line, the master sends an SMBus alert command (00011001) to the bus. If the ALERT pin is active, the device acknowledges the SMBus alert command and responds by returning its slave address on the SDA line. The eighth bit (LSB) of the slave address byte indicates whether the alert condition is caused by the temperature exceeding  $T_{HIGH}$  or falling below  $T_{LOW}$ . The LSB is high if the temperature is greater than  $T_{HIGH}$ , or low if the temperature is less than  $T_{LOW}$ . See [Figure 11](#) for details of this sequence.

If multiple devices on the bus respond to the SMBus alert command, arbitration during the slave address portion of the SMBus alert command determines which device clears its alert status first. If the TMP75B wins the arbitration, its ALERT pin becomes inactive at the completion of the SMBus alert command. If the TMP75B loses the arbitration, its ALERT pin remains active.

### 7.3.3.6 General Call

The TMP75B responds to a two-wire general call address (0000000) if the eighth bit is 0. The device acknowledges the general call address and responds to commands in the second byte. If the second byte is 00000100, the TMP75B latches the status of the address pin, but does not reset. If the second byte is 00000110, the TMP75B internal registers are reset to power-up values.

### 7.3.3.7 High-Speed (Hs) Mode

In order for the two-wire bus to operate at frequencies above 400 kHz, the master device must issue an SMBus Hs-mode master code (00001xxx) as the first byte after a start condition to switch the bus to high-speed operation. The TMP75B does not acknowledge this byte, but does switch its input filters on SDA and SCL and its output filters on SDA to operate in Hs-mode, allowing transfers at up to 3 MHz. After the Hs-mode master code has been issued, the master transmits a two-wire slave address to initiate a data-transfer operation. The bus continues to operate in Hs-mode until a stop condition occurs on the bus. Upon receiving the stop condition, the TMP75B switches the input and output filters back to fast-mode operation.

### 7.3.3.8 Timeout Function

The TMP75B resets the serial interface if SCL or SDA are held low for 54 ms (typ) between a start and stop condition. If the TMP75B is pulled low, it releases the bus and then waits for a start condition. To avoid activating the timeout function, it is necessary to maintain a communication speed of at least 1 kHz for the SCL operating frequency.

### 7.3.3.9 Two-Wire Timing

The TMP75B is two-wire and SMBus compatible. Figure 8 to Figure 11 describe the various operations on the TMP75B. Parameters for Figure 8 are defined in Table 3. Bus definitions are:

**Bus Idle** Both SDA and SCL lines remain high.

**Start Data Transfer** A change in the state of the SDA line, from high to low, while the SCL line is high defines a start condition. Each data transfer is initiated with a start condition.

**Stop Data Transfer** A change in the state of the SDA line from low to high while the SCL line is high defines a stop condition. Each data transfer is terminated with a repeated start or stop condition.

**Data Transfer** The number of data bytes transferred between a start and a stop condition is not limited, and is determined by the master device.

The receiver acknowledges the transfer of data. It is also possible to use the TMP75B for single-byte updates. To update only the MS byte, terminate communication by issuing a start or stop condition on the bus.

**Acknowledge** Each receiving device, when addressed, must generate an acknowledge bit.

A device that acknowledges must pull down the SDA line during the acknowledge clock pulse so that the SDA line is stable low during the high period of the acknowledge clock pulse. Setup and hold times must be taken into account. When a master receives data, the termination of the data transfer can be signaled by the master generating a *not-acknowledge* (1) on the last byte transmitted by the slave.

**Table 3. Timing Diagram Requirements**

| SYMBOL                   | PARAMETER  |                         | FAST MODE |      | HIGH-SPEED MODE |     | UNIT |
|--------------------------|--|-------------------------|-----------|------|-----------------|-----|------|
|                          |  |                         | MIN       | MAX  | MIN             | MAX |      |
| $f_{(SCL)}$              | SCL operating frequency  | $V_S \geq 1.8\text{ V}$ | 0.001     | 0.4  | 0.001           | 3   | MHz  |
|                          |  | $V_S < 1.8\text{ V}$    | 0.001     | 0.4  | 0.001           | 2.5 | MHz  |
| $t_{(BUF)}$              | Bus free time between stop and start conditions  | $V_S \geq 1.8\text{ V}$ | 1300      |      | 160             |     | ns   |
|                          |  | $V_S < 1.8\text{ V}$    | 1300      |      | 260             |     | ns   |
| $t_{(HDSTA)}$            | Hold time after repeated start condition. After this period, the first clock is generated. |                         | 600       |      | 160             |     | ns   |
| $t_{(SUSTA)}$            | Repeated start condition setup time  |                         | 600       |      | 160             |     | ns   |
| $t_{(SUSTO)}$            | Stop condition setup time  |                         | 600       |      | 160             |     | ns   |
| $t_{(HDDAT)}$            | Data hold time   | $V_S \geq 1.8\text{ V}$ | 0         | 900  | 0               | 100 | ns   |
|                          |  | $V_S < 1.8\text{ V}$    | 0         | 900  | 0               | 140 | ns   |
| $t_{(SUDAT)}$            | Data setup time  | $V_S \geq 1.8\text{ V}$ | 100       |      | 10              |     | ns   |
|                          |  | $V_S < 1.8\text{ V}$    | 100       |      | 20              |     | ns   |
| $t_{(LOW)}$              | SCL clock low period   | $V_S \geq 1.8\text{ V}$ | 1300      |      | 190             |     | ns   |
|                          |  | $V_S < 1.8\text{ V}$    | 1300      |      | 240             |     | ns   |
| $t_{(HIGH)}$             | SCL clock high period  |                         | 600       |      | 60              |     | ns   |
| $t_{R(SDA)}, t_{F(SDA)}$ | Data rise and fall time  |                         |           | 300  |                 | 80  | ns   |
| $t_{R(SCL)}, t_{F(SCL)}$ | Clock rise and fall time   |                         |           | 300  |                 | 40  | ns   |
| $t_R$                    | Clock and data rise time for $SCLK \leq 100\text{ kHz}$                                    |                         |           | 1000 |                 |     | ns   |

7.3.3.10 Two-Wire Timing Diagrams

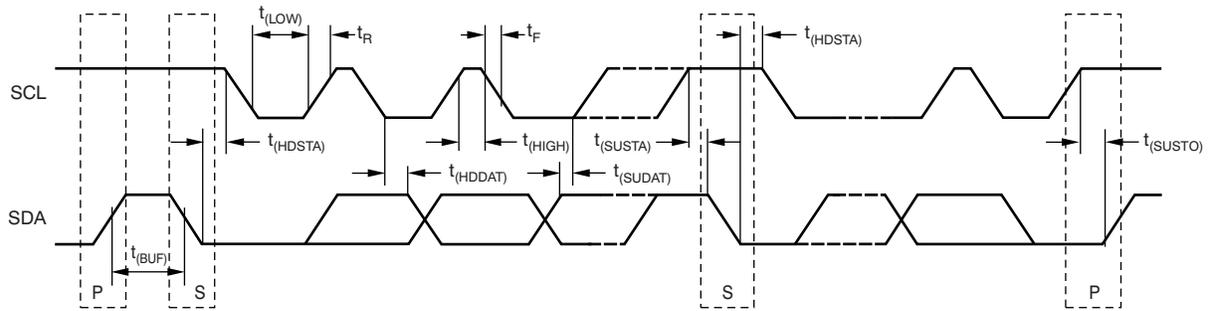
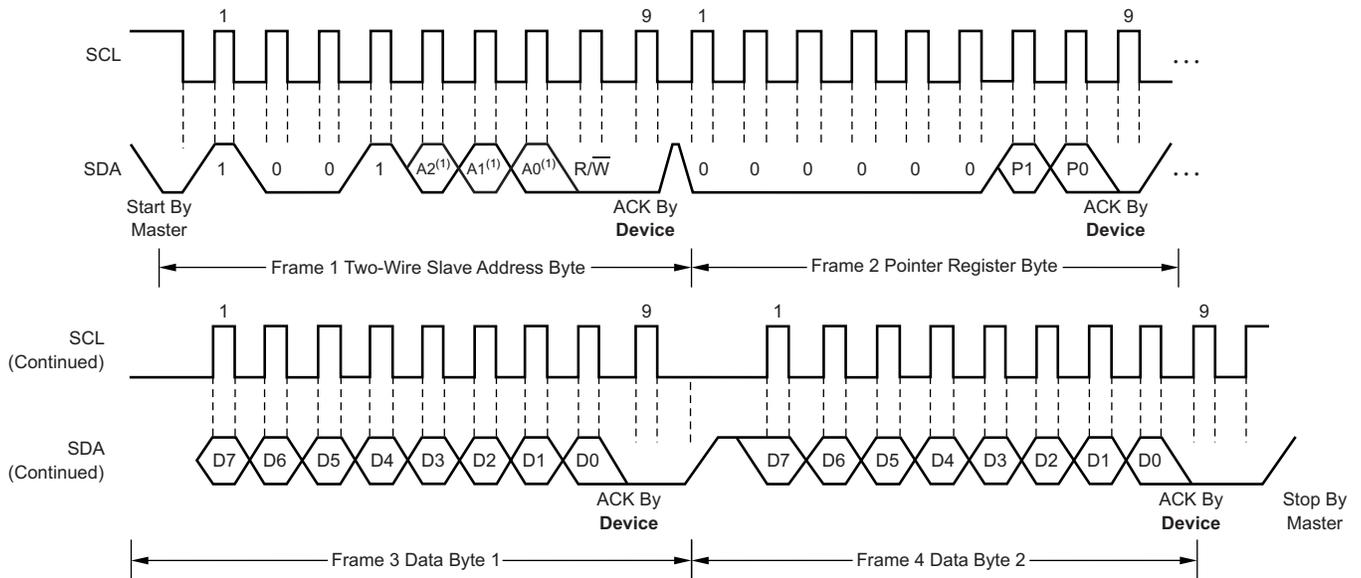
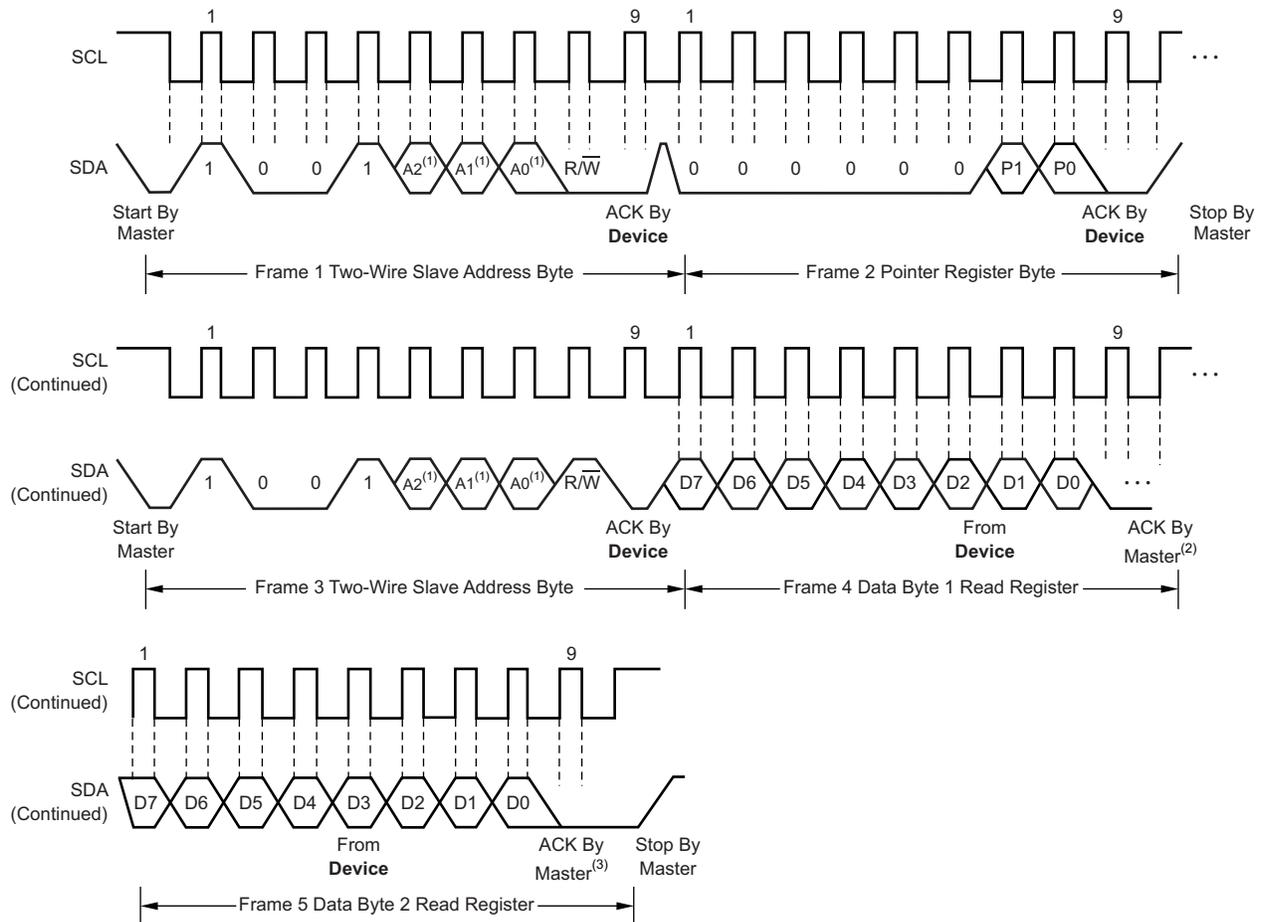


Figure 8. Two-Wire Timing Diagram

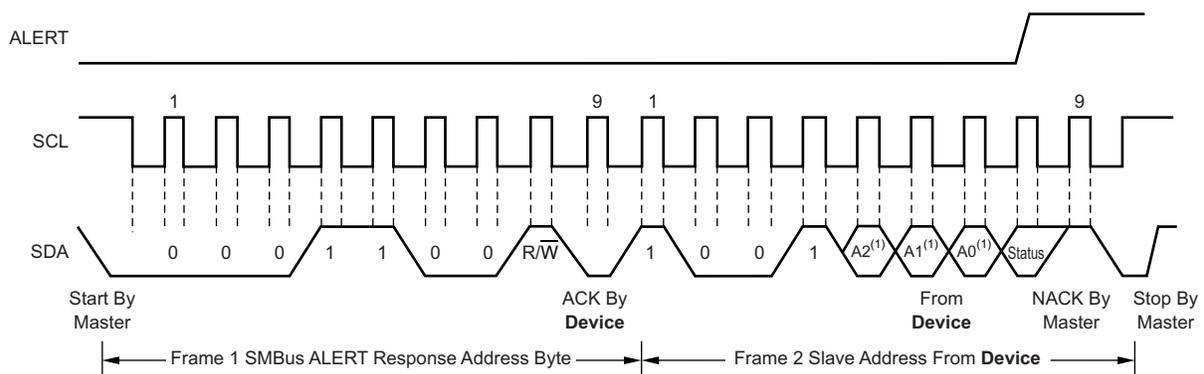


(1) The value of A0, A1, and A2 are determined by the connections of the corresponding pins.

Figure 9. Two-Wire Timing Diagram for Write Word Format



- (1) The value of  $A_0$ ,  $A_1$ , and  $A_2$  are determined by the connections of the corresponding pins.
- (2) Master should leave SDA high to terminate a single-byte read operation.
- (3) Master should leave SDA high to terminate a two-byte read operation.

**Figure 10. Two-Wire Timing Diagram for Read Word Format**


- (1) The value of  $A_0$ ,  $A_1$ , and  $A_2$  are determined by the connections of the corresponding pins.

**Figure 11. Timing Diagram for SMBus Alert**

## 7.4 Device Functional Modes

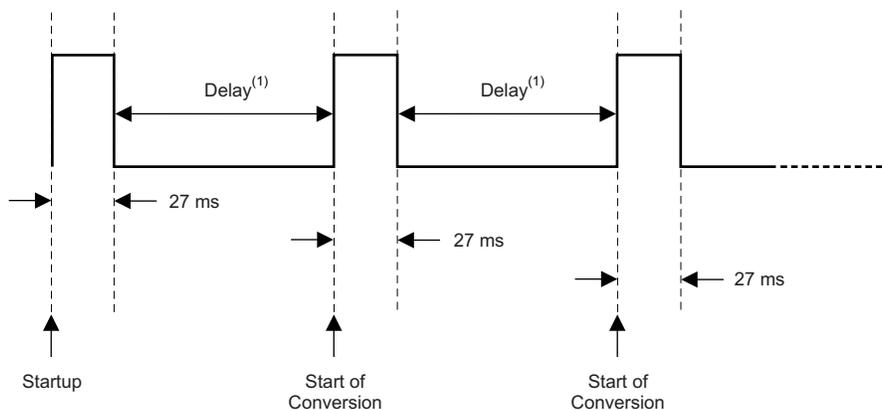
### 7.4.1 Continuous-Conversion Mode

The default mode of the TMP75B is continuous conversion, where the ADC performs continuous temperature conversions and stores each result to the temperature register, overwriting the result from the previous conversion. Conversion rate bits CR1 and CR0 in the configuration register configure the TMP75B for typical conversion rates of 37 Hz, 18 Hz, 9 Hz, or 4 Hz. The TMP75B has a typical conversion time of 27 ms. To achieve different conversion rates, the TMP75B makes a conversion, and then powers down and waits for the appropriate delay set by CR1 and CR0. The default rate is 37 Hz (no delay between conversions). Table 4 shows the settings for CR1 and CR0.

Table 4. Conversion Rate Settings

| CR1 | CR0 | CONVERSION RATE (TYP)                  | I <sub>q</sub> (TYP) |
|-----|-----|--|----------------------|
| 0   | 0   | 37 Hz (continuous conversion, default) | 45 μA                |
| 0   | 1   | 18 Hz                                  | 22 μA                |
| 1   | 0   | 9 Hz                                   | 12 μA                |
| 1   | 1   | 4 Hz                                   | 6.5 μA               |

After power-up or a general-call reset, the TMP75B immediately starts a conversion, as shown in Figure 12. The first result is available after 27 ms (typical). The active quiescent current during conversion is 45 μA (typical at +25°C). The quiescent current during delay is 1 μA (typical at +25°C).



(1) Delay is set by the CR bits in the configuration register.

Figure 12. Conversion Start

### 7.4.2 Shutdown Mode

Shutdown mode saves maximum power by shutting down all device circuitry other than the serial interface, and reduces current consumption to typically less than 0.3 μA. Shutdown mode is enabled when the SD bit in the configuration register is set to 1; the device shuts down after the current conversion is completed. When SD is equal to 0, the device operates in continuous-conversion mode. When shutdown mode is enabled, the ALERT pin and fault counter clear in both comparator and interrupt modes; however, this clearing occurs with the rising edge of the shutdown signal. After shutdown is enabled, reprogramming shutdown does not clear the ALERT pin and the fault counter until a rising edge is generated on the shutdown signal.

### 7.4.3 One-Shot Mode

The TMP75B features a *one-shot* temperature measurement mode. When the device is in shutdown mode, writing a 1 to the OS bit starts a single temperature conversion. The device returns to the shutdown state at the completion of the single conversion. This mode reduces power consumption in the TMP75B when continuous temperature monitoring is not required. When the configuration register is read, the OS bit always reads zero.

## 7.5 Programming

Figure 13 shows the internal register structure of the TMP75B. Use the 8-bit pointer register to address a given data register. The pointer register uses the two LSBs to identify which of the data registers respond to a read or write command. Figure 14 identifies the bits of the pointer register byte.

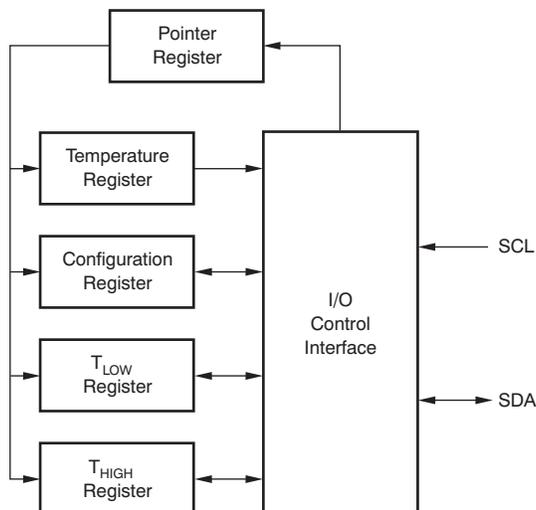


Figure 13. Internal Register Structure

## 7.6 Register Map

Table 5 describes the registers available in the TMP75B with their pointer addresses, followed by the description of the bits in each register.

Table 5. Register Map and Pointer Addresses

| P1 | P0 | REGISTER                                  |
|----|----|---|
| 0  | 0  | Temperature register (read only, default) |
| 0  | 1  | Configuration register (read/write)       |
| 1  | 0  | T <sub>LOW</sub> register (read/write)    |
| 1  | 1  | T <sub>HIGH</sub> register (read/write)   |

Figure 14. Pointer Register (pointer = N/A) [reset = 00h]

| 7        | 6 | 5 | 4 | 3 | 2 | 1    | 0    |
|----------|---|---|---|---|---|------|------|
| Reserved |   |   |   |   |   | P1   | P0   |
| W-0h     |   |   |   |   |   | W-0h | W-0h |

LEGEND: R/W = Read/Write; R = Read only; W = Write only; -n = value after reset

**Figure 15. Temperature Register (pointer = 0h) [reset = 0000h]**

|      |     |    |    |          |    |    |    |
|------|-----|----|----|----------|----|----|----|
| 15   | 14  | 13 | 12 | 11       | 10 | 9  | 8  |
| T11  | T10 | T9 | T8 | T7       | T6 | T5 | T4 |
| R-0h |     |    |    |          |    |    |    |
| 7    | 6   | 5  | 4  | 3        | 2  | 1  | 0  |
| T3   | T2  | T1 | T0 | Reserved |    |    |    |
| R-0h |     |    |    | R-0h     |    |    |    |

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 6. Temperature Register Description**

| Name      | Description   |
|-----------|---|
| T11 to T4 | The 8 MSBs of the temperature result (resolution of 1°C)      |
| T3 to T0  | The 4 LSBs of the temperature result (resolution of 0.0625°C) |

**Figure 16. Configuration Register (pointer = 1h) [reset = 00FFh]**

|          |        |    |        |    |        |        |        |
|----------|--------|----|--------|----|--------|--------|--------|
| 15       | 14     | 13 | 12     | 11 | 10     | 9      | 8      |
| OS       | CR     |    | FQ     |    | POL    | TM     | SD     |
| R/W-0h   | R/W-0h |    | R/W-0h |    | R/W-0h | R/W-0h | R/W-0h |
| 7        | 6      | 5  | 4      | 3  | 2      | 1      | 0      |
| Reserved |        |    |        |    |        |        |        |
| R-FFh    |        |    |        |    |        |        |        |

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 7. Configuration Register Description**

| Name | Description   |
|------|---|
| OS   | One-shot mode<br>In shutdown (SD = 1), write 1 to start a conversion. OS always reads back 0.   |
| CR   | Conversion rate control<br>CR = 0h: 37-Hz conversion rate (typ) (default)<br>CR = 1h: 18-Hz conversion rate (typ)<br>CR = 2h: 9-Hz conversion rate (typ)<br>CR = 3h: 4-Hz conversion rate (typ) |
| FQ   | Fault queue to trigger the ALERT pin<br>FQ = 0h: 1 fault (default)<br>FQ = 1h: 2 faults<br>FQ = 2h: 4 faults<br>FQ = 3h: 6 faults   |
| POL  | ALERT polarity control<br>POL = 0: ALERT is active low (default)<br>POL = 1: ALERT is active high   |
| TM   | ALERT thermostat mode control<br>TM = 0: ALERT is in comparator mode (default)<br>TM = 1: ALERT is in interrupt mode  |
| SD   | Shutdown control bit<br>SD = 0: Device is in continuous conversion mode (default)<br>SD = 1: Device is in shutdown mode   |

**Figure 17. T<sub>LOW</sub> - Temperature Low Limit Register (pointer = 2h) [reset = 4B00h]<sup>(1)</sup>**

|         |     |    |    |          |    |    |    |
|---------|-----|----|----|----------|----|----|----|
| 15      | 14  | 13 | 12 | 11       | 10 | 9  | 8  |
| L11     | L10 | L9 | L8 | L7       | L6 | L5 | L4 |
| R/W-4Bh |     |    |    |          |    |    |    |
| 7       | 6   | 5  | 4  | 3        | 2  | 1  | 0  |
| L3      | L2  | L1 | L0 | Reserved |    |    |    |
| R/W-0h  |     |    |    | R-0h     |    |    |    |

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

(1) 4B00h = 75°C.

**Table 8. T<sub>LOW</sub> Register Description**

| Name      | Description  |
|-----------|--|
| L11 to L4 | The 8 MSBs of the temperature low limit (resolution of 1°C)      |
| L3 to L0  | The 4 LSBs of the temperature low limit (resolution of 0.0625°C) |

**Figure 18. T<sub>HIGH</sub> - Temperature High Limit Register (pointer = 3h) [reset = 5000h]<sup>(1)</sup>**

|         |     |    |    |          |    |    |    |
|---------|-----|----|----|----------|----|----|----|
| 15      | 14  | 13 | 12 | 11       | 10 | 9  | 8  |
| H11     | H10 | H9 | H8 | H7       | H6 | H5 | H4 |
| R/W-50h |     |    |    |          |    |    |    |
| 7       | 6   | 5  | 4  | 3        | 2  | 1  | 0  |
| H3      | H2  | H1 | H0 | Reserved |    |    |    |
| R/W-0h  |     |    |    | R-0h     |    |    |    |

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

(1) 5000h = 80°C.

**Table 9. T<sub>HIGH</sub> Register Description**

| Name      | Description   |
|-----------|---|
| H11 to H4 | The 8 MSBs of the temperature high limit (resolution of 1°C)      |
| H3 to H0  | The 4 LSBs of the temperature high limit (resolution of 0.0625°C) |

## 8 Application and Implementation

### 8.1 Application Information

The TMP75B is used to measure the PCB temperature of the location it is mounted. The programmable address options allow up to eight locations on the board to be monitored on a single serial bus. Connecting the ALERT pins together and programming the temperature limit registers to desired values allows for a temperature watchdog operation of all devices, interrupting the host controller only if the temperature exceeds the limits.

### 8.2 Typical Application

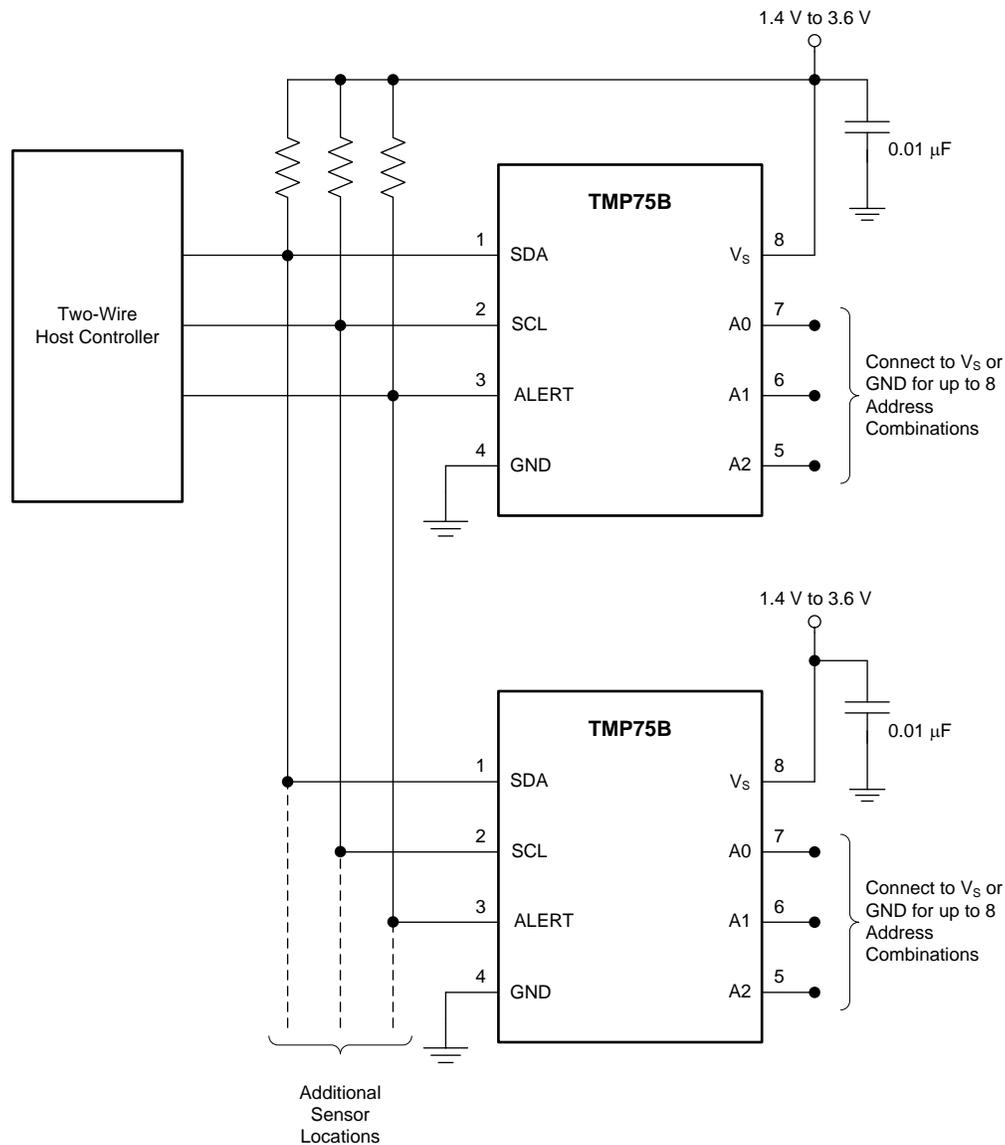


Figure 19. Temperature Monitoring of Multiple Locations on a PCB

## Typical Application (continued)

### 8.2.1 Design Requirements

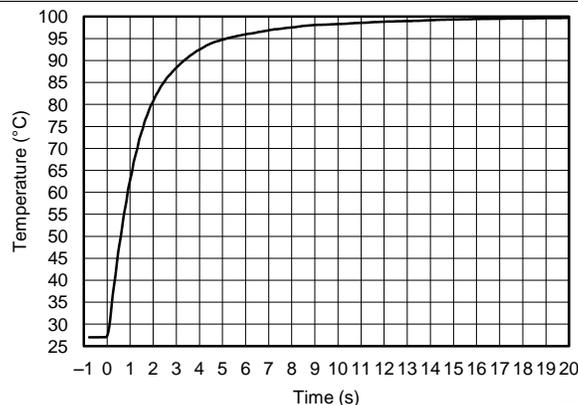
The TMP75B only requires pull-up resistors on SDA and ALERT, although a pull-up resistor is typically present on the SCL as well. A 0.01- $\mu\text{F}$  bypass capacitor on the supply is recommended, as shown in [Figure 19](#). The SCL, SDA, and ALERT lines can be pulled up to a supply that is equal to or higher than  $V_S$  through the pull-up resistors. To configure one of eight different addresses on the bus, connect A0, A1, and A2 to either  $V_S$  or GND.

### 8.2.2 Detailed Design Procedure

The TMP75B should be placed in close proximity to the heat source to be monitored, with a proper layout for good thermal coupling. This ensures that temperature changes are captured within the shortest possible time interval.

### 8.2.3 Application Curves

[Figure 20](#) shows the step response of the TMP75B to a submersion in an oil bath of 100°C from room temperature (27°C). The time-constant, or the time for the output to reach 63% of the input step, is 1.5 seconds.



**Figure 20. Temperature Step Response**

## 9 Power Supply Recommendations

The TMP75B operates with power supply in the range of 1.4 V to 3.6 V. It is optimized for operation at 1.8-V supply but can measure temperature accurately in the full supply range.

A power-supply bypass capacitor is required for stability; place this capacitor as close as possible to the supply and ground pins of the device. A typical value for this supply bypass capacitor is 0.01  $\mu\text{F}$ . Applications with noisy or high-impedance power supplies may require additional decoupling capacitors to reject power-supply noise.

## 10 Layout

### 10.1 Layout Guidelines

Place the power-supply bypass capacitor as close as possible to the supply and ground pins. The recommended value of this bypass capacitor is 0.01  $\mu\text{F}$ . Additional decoupling capacitance can be added to compensate for noisy or high-impedance power supplies.

Pull up the open-drain output pins (SDA and ALERT) to a supply voltage rail ( $V_S$  or higher but up to 3.6 V) through 10-k $\Omega$  pull-up resistors.

### 10.2 Layout Example

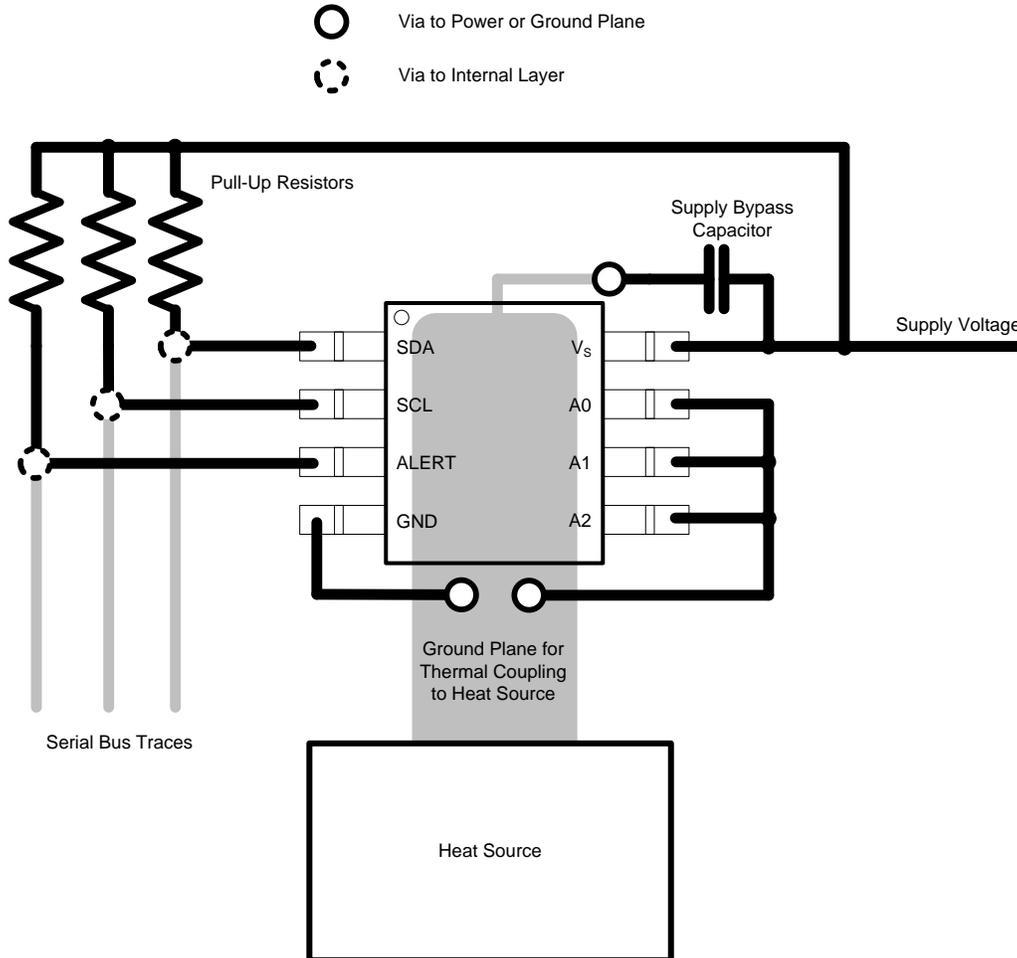


Figure 21. Layout Example

## 11 器件和文档支持

### 11.1 文档支持

#### 11.1.1 相关文档

[SBOU141](#) — 《TMP75xEVM 用户指南》

### 11.2 商标

All trademarks are the property of their respective owners.

### 11.3 静电放电警告



这些装置包含有限的内置 ESD 保护。存储或装卸时，应将导线一起截短或将装置放置于导电泡棉中，以防止 MOS 门极遭受静电损伤。

### 11.4 术语表

[SLYZ022](#) — *TI* 术语表。

这份术语表列出并解释术语、首字母缩略词和定义。

## 12 机械封装和可订购信息

以下页中包括机械封装和可订购信息。 这些信息是针对指定器件可提供的最新数据。 这些数据会在无通知且不对本文档进行修订的情况下发生改变。 欲获得该数据表的浏览器版本，请查阅左侧的导航栏。

**PACKAGING INFORMATION**

| Orderable Device | Status<br>(1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan<br>(2) | Lead finish/<br>Ball material<br>(6) | MSL Peak Temp<br>(3) | Op Temp (°C) | Device Marking<br>(4/5) | Samples                 |
|------------------|---------------|--------------|-----------------|------|-------------|-----------------|--------------------------------------|----------------------|--------------|-------------------------|-------------------------|
| TMP75BID         | ACTIVE        | SOIC         | D               | 8    | 75          | RoHS & Green    | NIPDAU-DCC                           | Level-1-260C-UNLIM   | -55 to 125   | TMP75B                  | <a href="#">Samples</a> |
| TMP75BIDGKR      | ACTIVE        | VSSOP        | DGK             | 8    | 2500        | RoHS & Green    | NIPDAUAG                             | Level-2-260C-1 YEAR  | -55 to 125   | T75B                    | <a href="#">Samples</a> |
| TMP75BIDGKT      | ACTIVE        | VSSOP        | DGK             | 8    | 250         | RoHS & Green    | NIPDAUAG                             | Level-2-260C-1 YEAR  | -55 to 125   | T75B                    | <a href="#">Samples</a> |
| TMP75BIDR        | ACTIVE        | SOIC         | D               | 8    | 2500        | RoHS & Green    | NIPDAU-DCC                           | Level-1-260C-UNLIM   | -55 to 125   | TMP75B                  | <a href="#">Samples</a> |

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) **MSL, Peak Temp.** - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

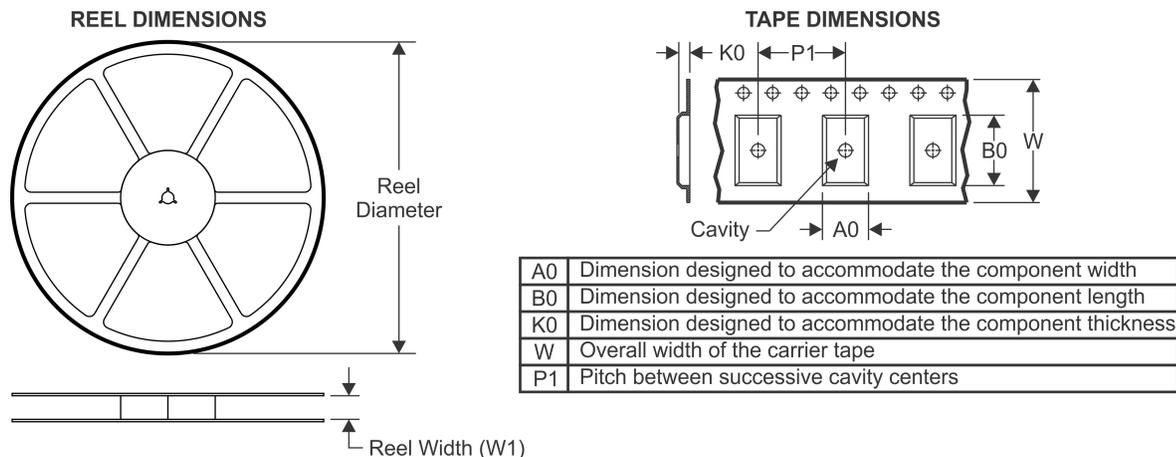
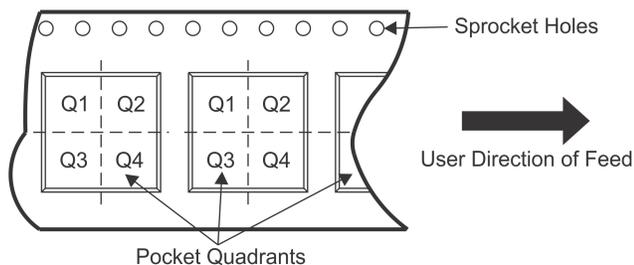
(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) **Lead finish/Ball material** - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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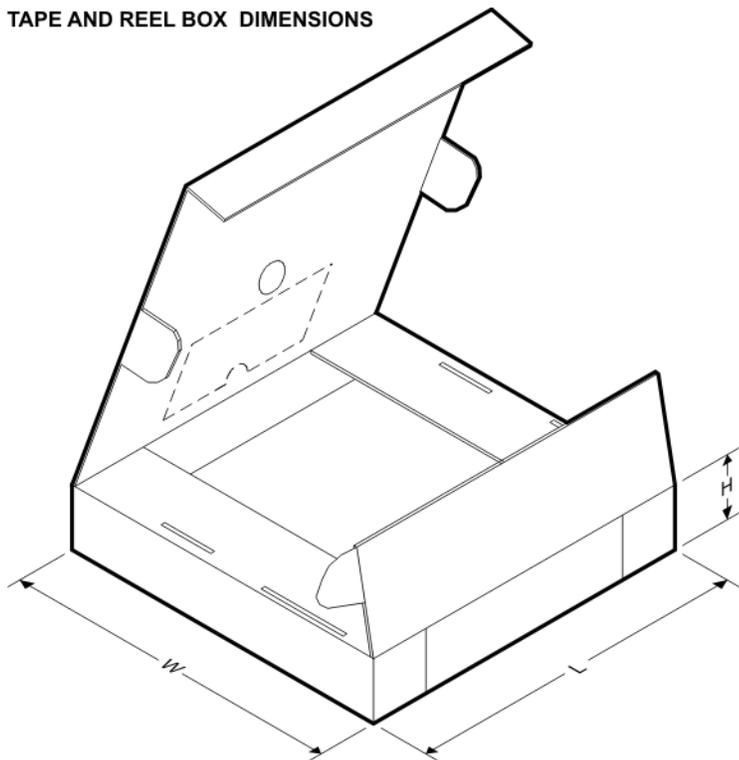
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**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


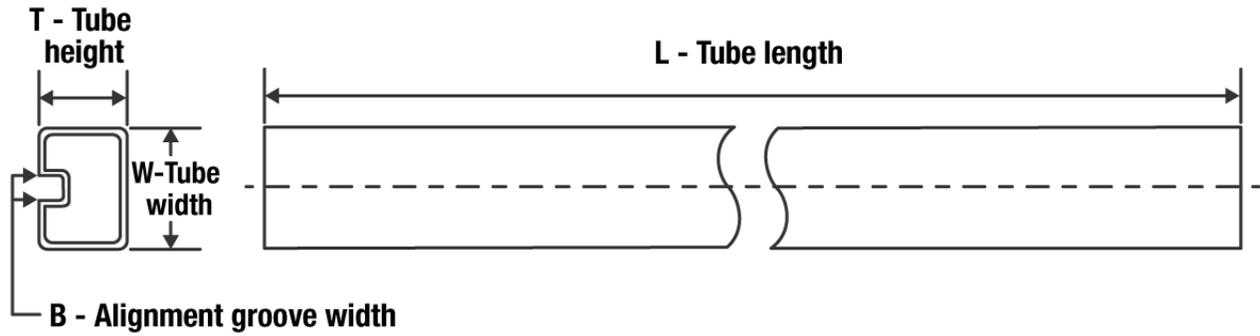
\*All dimensions are nominal

| Device      | Package Type | Package Drawing | Pins | SPQ  | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|-------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| TMP75BIDGKR | VSSOP        | DGK             | 8    | 2500 | 330.0              | 12.4               | 5.3     | 3.4     | 1.4     | 8.0     | 12.0   | Q1            |
| TMP75BIDGKT | VSSOP        | DGK             | 8    | 250  | 330.0              | 12.4               | 5.3     | 3.4     | 1.4     | 8.0     | 12.0   | Q1            |
| TMP75BIDR   | SOIC         | D               | 8    | 2500 | 330.0              | 12.4               | 6.4     | 5.2     | 2.1     | 8.0     | 12.0   | Q1            |

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

| Device      | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |
|-------------|--------------|-----------------|------|------|-------------|------------|-------------|
| TMP75BIDGKR | VSSOP        | DGK             | 8    | 2500 | 366.0       | 364.0      | 50.0        |
| TMP75BIDGKT | VSSOP        | DGK             | 8    | 250  | 366.0       | 364.0      | 50.0        |
| TMP75BIDR   | SOIC         | D               | 8    | 2500 | 853.0       | 449.0      | 35.0        |

**TUBE**


\*All dimensions are nominal

| Device   | Package Name | Package Type | Pins | SPQ | L (mm) | W (mm) | T (μm) | B (mm) |
|----------|--------------|--------------|------|-----|--------|--------|--------|--------|
| TMP75BID | D            | SOIC         | 8    | 75  | 506.6  | 8      | 3940   | 4.32   |



D0008A

# PACKAGE OUTLINE

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



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## NOTES:

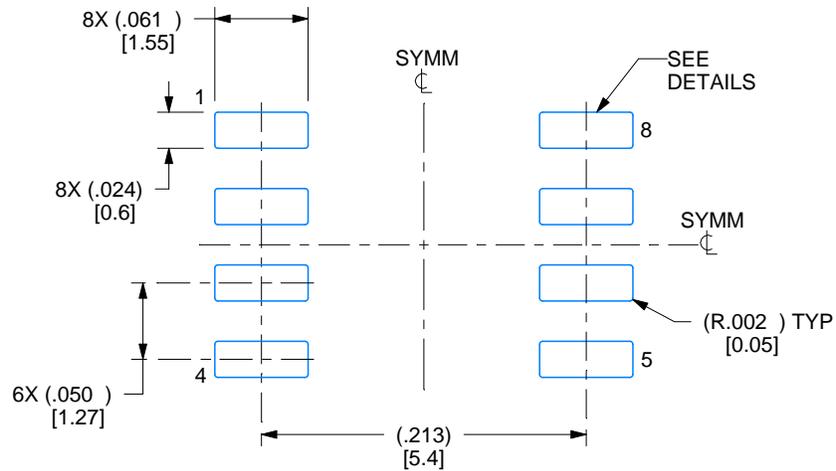
- Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- This drawing is subject to change without notice.
- This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed  $.006$  [0.15] per side.
- This dimension does not include interlead flash.
- Reference JEDEC registration MS-012, variation AA.

# EXAMPLE BOARD LAYOUT

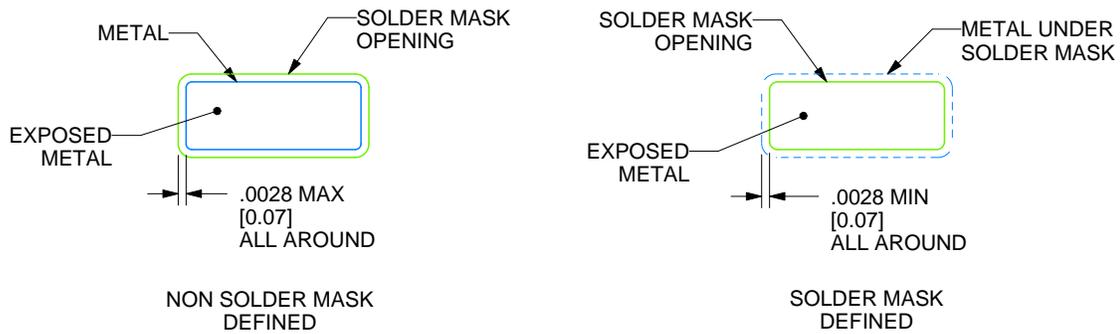
D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:8X



SOLDER MASK DETAILS

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NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

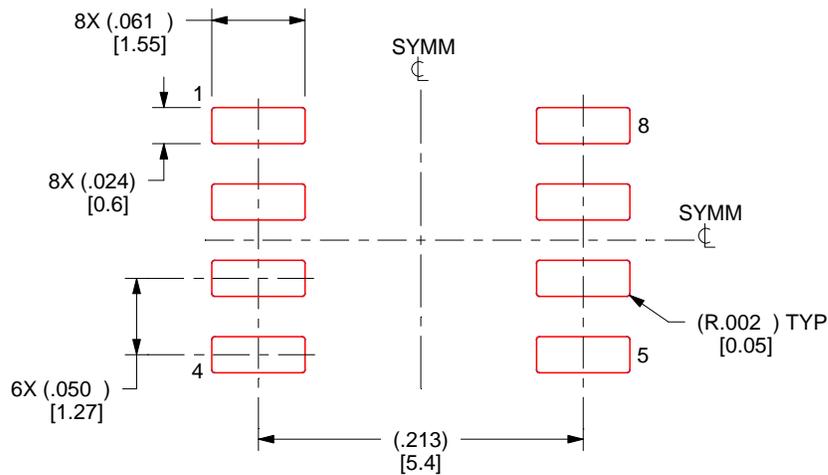
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

# EXAMPLE STENCIL DESIGN

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SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



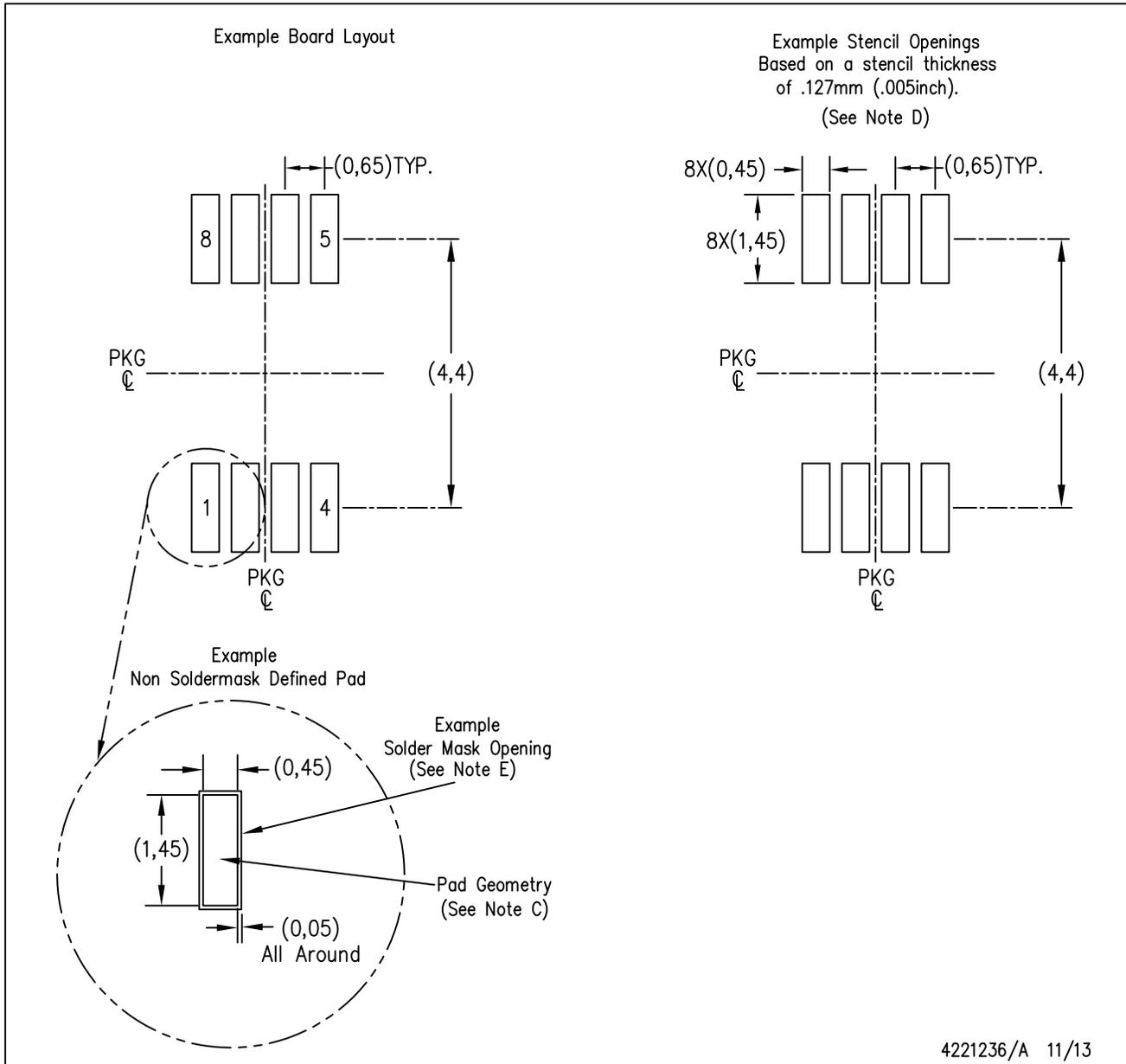
SOLDER PASTE EXAMPLE  
BASED ON .005 INCH [0.125 MM] THICK STENCIL  
SCALE:8X

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NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.





- NOTES:
- A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Publication IPC-7351 is recommended for alternate designs.
  - D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
  - E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

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