

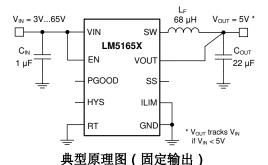
# 具有超低 Io 的 LM5165 3V 至 65V 输入、150mA 同步降压转换器

# 1 特性

- 3V 至 65V 的宽输入电压范围
- 10.5µA 空载静态电流
- -40°C 至 150°C 的结温范围
- 固定(3.3V和5V)或可调节输出电压
- 符合 EN55022/CISPR 22 EMI 标准
- 集成式 2Ω PMOS 降压开关
  - 支持 100% 占空比,可实现低压降
- 集成式 1Ω NMOS 同步整流器
  - 无需使用外部整流二极管
- 可编程电流限制设置点(四级)
- 可选 PFM 或 COT 模式工作
- 1.223V ±1% 内部电压基准
- 900µs 内部或可编程软启动
- 可实现低 EMI 的有效压摆率控制
- 二极管仿真模式和脉冲跳跃模式,可在轻负载下实 现超高效率
- 单调启动至预偏置输出
- 无环路补偿或自举元件
- 具有迟滞功能的精密使能和输入 UVLO
- 与 LM5166 引脚对引脚兼容
- 具有迟滞功能的热关断保护
- 10 引脚 3mm × 3mm VSON 封装
- 使用 TPSM265R1 模块缩短产品上市时间
- 使用 WEBENCH® Power Designer 创建定制稳压器 设计

# 2 应用

- 4-20mA 环路供电式传感器
- 汽车和电池供电设备
- 高电压 LDO 替代产品
- 工业控制系统
- 通用偏置电源



### 3 说明

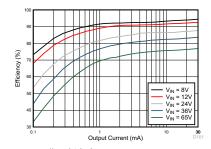
LM5165 器件是一款易于使用的紧凑型 3V 至 65V、超 低 Io 同步降压转换器,可在宽输入电压和负载电流范 围内提供高效率。该器件具有集成式高侧和低侧功率 MOSFET,能够以 3.3V 或 5V 的固定输出电压或可调 输出电压提供高达 150mA 的输出电流。该转换器设计 旨在简化实现方案,同时优化目标应用的性能。脉频调 制 (PFM) 模式可确保在轻负载条件下获得最优效率, 恒定导通时间 (COT) 控制可实现近似恒定的工作频 率。这两种控制方案都不需要环路补偿,同时还能够针 对较高的降压转换比实现出色的线路和负载瞬态响应以 及短暂的脉宽调制 (PWM) 导通时间。

高侧 P 沟道 MOSFET 能够以 100% 占空比工作以确 保最低压差电压,而且不需要使用自举电容器进行栅极 驱动。另外,还可以调节电流限制设定值来优化电感器 选择,从而满足特定的输出电流要求。可选和可调节启 动时序选项包括最短延迟(无软启动)、内部固定值 (900µs) 以及可使用电容器进行外部编程的软启动。可 以使用开漏 PGOOD 指示器进行定序、故障报告和输 出电压监视。LM5165 降压转换器采用 10 引脚 3mm× 3mm 热增强型 VSON-10 封装(引脚间距为 0.5mm) 。

#### 器件信息

器件型号	输出	封装 <sup>(1)</sup>
LM5165	可调节	
LM5165X	5V 固定	VSON (10)
LM5165Y	3.3V 固定	

如需了解所有可用封装,请参阅数据表末尾的可订购产品附



典型效率 (V<sub>OUT</sub> = 5V)



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4 Revision History Changes from Revision B (July 2017) to R	evision C (	December 2020) P	
			age
<ul> <li>添加了 TPSM265R1 链接</li> </ul>			
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# **5 Pin Configuration and Functions**

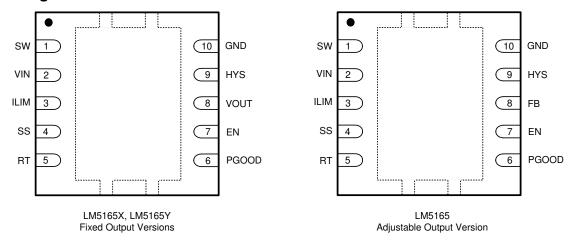


图 5-1. DRC Package 10-Pin VSON With Exposed Thermal Pad (Top View)

表 5-1. Pin Functions

PIN		TYPE(1)	DESCRIPTION		
NO.	NAME	1 TPE	DESCRIPTION		
1	SW	Р	Switching node that is internally connected to the drain of the high-side PMOS buck switch and the drain of the low-side NMOS synchronous rectifier. Connect to the switching side of the power inductor.		
2	VIN	Р	Regulator supply input pin to high-side power MOSFET and internal bias rail LDO. Connect to input supply and input capacitor $C_{IN}$ . Path from VIN to the input capacitor must be as short as possible.		
3	ILIM	I	Programming pin for current limit. Connecting the appropriate resistor from ILIM to GND selects one of four preset current limit options. Short ILIM to GND for the maximum current setting.		
4	SS	1	Programming pin for the soft-start time. If a 100-k $\Omega$ resistor is connected from SS to GND, the internal soft-start circuit is disabled and the FB comparator reference steps immediately from zero to full value when the regulator is enabled by the EN input. If the SS pin is left open, the internal soft-start circuit ramps the FB reference from zero to full value in 900 $\mu$ s. If an appropriate capacitance is connected to the SS pin, the soft-start time can be programmed as required.		
5	RT	I	Mode selection and on-time programming pin for Constant On-Time (COT) control. Short RT to GND to select PFM (pulse frequency modulation) operation. Connect a resistor from RT to GND to program the on-time, which sets the switching frequency for COT.		
6	PGOOD	0	Power Good output flag pin. PGOOD is connected to the drain of an NFET that holds the pin low when either FB or VOUT is below the regulation target. Use a pullup resistor of 10 k $\Omega$ to 100 k $\Omega$ to the system voltage rail or VOUT (no higher than 12 V).		
7	EN	I	Input pin of the precision enable / UVLO comparator. The converter is enabled when the EN voltage is greater than 1.212 V.		
8	VOUT/FB	I	Feedback input to voltage regulation loop. The VOUT pin connects the internal feedback resistor divider to the regulator output voltage for fixed 3.3-V and 5-V options. The FB pin connects the internal feedback comparator to an external resistor divider for the adjustable output voltage option. The FB comparator reference voltage is nominally 1.223 V.		
9	HYS	0	Drain of an internal NFET that is turned off when the EN input is greater than the EN threshold. An external resistor from HYS to the EN pin UVLO resistor divider programs the input UVLO hysteresis voltage.		
10	GND	G	Regulator ground return		
_	PAD	Р	Exposed pad. Connect to the GND pin and system ground on PCB. Path to C <sub>IN</sub> must be as short as possible.		

<sup>(1)</sup> P = Power, G = Ground, I = Input, O = Output.

# **6 Specifications**

# **6.1 Absolute Maximum Ratings**

Over the recommended operating junction temperature range of -40°C to 150°C (unless otherwise noted). (1) (2)

		MIN	MAX	UNIT
VIN, EN to GND		- 0.3	68	V
SW to GND		- 0.7	V <sub>VIN</sub> + 0.3	V
OW to GND	20-ns transient	- 3		V
PGOOD, VOUT <sup>(3)</sup> to GND	Survives short to automotive battery voltage	- 0.3	16	V
HYS to GND		- 0.3	7	V
ILIM, SS, RT, FB <sup>(4)</sup> to GND		- 0.3	3.6	V
Maximum junction temperature, T <sub>J</sub>		- 40	150	°C
Storage temperature, T <sub>stg</sub>		- 55	150	°C

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions may affect device reliability.

### 6.2 ESD Ratings

			VALUE	UNIT
\/_	Electrostatic	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	±2000	V
VE	<sup>SD</sup> discharge	Charged device model (CDM), per JEDEC specification JESD22-C101, all pins <sup>(2)</sup>	±1000	v

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

### **6.3 Recommended Operating Conditions**

Over the recommended operating junction temperature range of -40°C to 150°C (unless otherwise noted)<sup>(1)</sup>.

		MIN	MAX	UNIT	
	VIN	3	65		
Input voltages	EN	- 0.3	65	V	
Input voltages	PGOOD	- 0.3	12	V	
	HYS	- 0.3	5.5		
Output current	I <sub>OUT</sub> (COT mode)	0	150	mA	
Output current	I <sub>OUT</sub> (PFM mode)	0	100	ША	
Temperature	Operating junction temperature	- 40	150	°C	

<sup>(1)</sup> Operating Ratings are conditions under which the device is intended to be functional. For specifications and test conditions, see Electrical Characteristics.

#### 6.4 Thermal Information

		LM5165	
	THERMAL METRIC <sup>(1)</sup>	DRC (VSON)	UNIT
		10 PINS	
R <sub>0</sub> JA	Junction-to-ambient thermal resistance	47.7	°C/W
R <sub>θ JC(top)</sub>	Junction-to-case (top) thermal resistance	59.9	°C/W
R <sub>0</sub> JB	Junction-to-board thermal resistance	22.1	°C/W

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<sup>(2)</sup> If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.

<sup>(3)</sup> Fixed output versions.

<sup>(4)</sup> Adjustable output version.

<sup>(2)</sup> JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



THERMAL METRIC <sup>(1)</sup>		LM5165 DRC (VSON)	
		10 PINS	
ΨJT	Junction-to-top characterization parameter	1	°C/W
ψ ЈВ	Junction-to-board characterization parameter	22.2	°C/W
R <sub>θ JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	4	°C/W

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report.

#### 6.5 Electrical Characteristics

Typical values correspond to  $T_J$  = 25°C. Minimum and maximum limits apply over the -40°C to +125°C junction temperature range.  $V_{IN}$  = 12 V (unless otherwise noted). (1) (2)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
QUIESCENT C	URRENTS					
I <sub>Q-SHD</sub>	VIN DC supply current, shutdown	V <sub>EN</sub> = 0 V, T <sub>A</sub> = 25°C		4.6	6	μA
I <sub>Q-SLEEP</sub>	VIN DC supply current, no load	V <sub>FB</sub> = 1.5 V, T <sub>A</sub> = 25°C		10.5	15	μA
I <sub>Q-SLEEP-VINMAX</sub>	VIN DC supply current, no load	V <sub>FB</sub> = 1.5 V, V <sub>VIN</sub> = 65 V, T <sub>A</sub> = 25°C		11	15	μA
I <sub>Q-ACTIVE-PFM</sub>	VIN DC supply current, active	PFM mode		205		μA
I <sub>Q-ACTIVE-COT</sub>	VIN DC supply current, active	COT mode, R <sub>RT</sub> = 107 k Ω		300		μA
POWER SWITC	CHES					
R <sub>DSON1</sub>	High-side MOSFET R <sub>DS(on)</sub>	I <sub>SW</sub> = - 10 mA		2		Ω
R <sub>DSON2</sub>	Low-side MOSFET R <sub>DS(on)</sub>	I <sub>SW</sub> = 10 mA		1		Ω
CURRENT LIM					1	
I <sub>LIM1-VSON</sub>		ILIM shorted to GND	220	240	264	
I <sub>LIM2-VSON</sub>	High-side peak current threshold	R <sub>ILIM</sub> = 24.9 k Ω	155	180	205	
I <sub>LIM3-VSON</sub>	VSON-10 package	R <sub>ILIM</sub> = 56.2 k Ω	100	120	145	mA
I <sub>LIM4-VSON</sub>	-	R <sub>ILIM</sub> ≥ 100 k Ω	48	60	75	
	COMPARATOR	i.E.iii				
V <sub>VOUT50</sub>	VOUT 5-V DC setpoint	LM5165X	4.9	5	5.1	V
V <sub>VOUT33</sub>	VOUT 3.3-V DC setpoint	LM5165Y	3.23	3.3	3.37	V
- 100133	VOUT pin input current	V <sub>VOUT</sub> = 5 V, LM5165X		6.7		
I <sub>VOUT</sub>		V <sub>VOUT</sub> = 3.3 V, LM5165Y		3.9		μΑ
V <sub>REF1</sub>	Lower FB regulation threshold (PFM, COT)	1001	1.205	1.223	1.241	
V <sub>REF2</sub>	Upper FB regulation threshold (PFM)	Adjustable output version	1.22	1.233	1.246	V
FB <sub>HYS-PFM</sub>	FB comparator PFM hysteresis	PFM mode		10		mV
FB <sub>HYS-COT</sub>	FB comparator dropout hysteresis	COT mode		4		mV
I <sub>FB</sub>	FB pin input bias current	V <sub>FB</sub> = 1 V			100	nA
FB <sub>LINE-REG</sub>	FB threshold variation over line	V <sub>VIN</sub> = 3 V to 65 V		0.001		%/V
VOUT <sub>LINE-REG</sub>	VOUT threshold variation over line	LM5165X, V <sub>VIN</sub> = 6 V to 65 V LM5165Y, V <sub>VIN</sub> = 4.5 V to 65 V		0.001		%/V
POWER GOOD	)				<u>'</u>	
UVT <sub>RISING</sub>	PCOOD comparator	FB voltage rising, relative to V <sub>REF1</sub>		94%		
UVT <sub>FALLING</sub>	PGOOD comparator	FB voltage falling, relative to V <sub>REF1</sub>		87%		
R <sub>PGOOD</sub>	PGOOD on-resistance	V <sub>FB</sub> = 1 V		80	200	Ω
V <sub>INMIN-PGOOD</sub>	Minimum VIN for valid PGOOD	V <sub>VIN</sub> falling, I <sub>PGOOD</sub> = 0.1 mA, V <sub>PGOOD</sub> < 0.5 V	1.2 1		1.65	V
I <sub>PGOOD</sub>	PGOOD off-state leakage current	V <sub>FB</sub> = 1.2 V, V <sub>PGOOD</sub> = 5.5 V		10	100	nA
ENABLE / UVL	.0					

### **6.5 Electrical Characteristics (continued)**

Typical values correspond to  $T_J$  = 25°C. Minimum and maximum limits apply over the -40°C to +125°C junction temperature range.  $V_{IN}$  = 12 V (unless otherwise noted). (1) (2)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT		
V <sub>IN-ON</sub>	Turnon threshold	VIN voltage rising	2.6	2.75	2.95	V		
V <sub>IN-OFF</sub>	Turnoff threshold	VIN voltage falling	2.35	2.45	2.6	V		
V <sub>EN-ON</sub>	Enable turnon threshold	EN voltage rising	1.163	1.212	1.262	V		
V <sub>EN-OFF</sub>	Enable turnoff threshold	EN voltage falling	1.109	1.144	1.178	V		
V <sub>EN-HYS</sub>	Enable hysteresis			68		mV		
V <sub>EN-SD</sub>	EN shutdown threshold	EN voltage falling	0.3	0.6		V		
R <sub>HYS</sub>	HYS on-resistance	V <sub>EN</sub> = 1 V		80	200	Ω		
I <sub>HYS</sub>	HYS off-state leakage current	V <sub>EN</sub> = 1.5 V, V <sub>HYS</sub> = 5.5 V		10	100	nA		
SOFT-STAR	т	·						
I <sub>SS</sub>	Soft-start charging current	V <sub>SS</sub> = 1 V		10		μA		
T <sub>SS-INT</sub>	Soft-start rise time	SS floating		900		μs		
THERMAL S	THERMAL SHUTDOWN							
T <sub>J-SD</sub>	Thermal shutdown threshold			170		°C		
T <sub>J-SD-HYS</sub>	Thermal shutdown hysteresis			10		°C		

<sup>(1)</sup> All hot and cold limits are specified by correlating the electrical characteristics to process and temperature variations and applying statistical process control.

# 6.6 Switching Characteristics

Over operating free-air temperature range (unless otherwise noted).

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
T <sub>ON-MIN</sub>	Minimum controllable PWM on-time			180		ns
T <sub>ON1</sub>	PWM on-time	16 kΩ from RT to GND		250		ns
T <sub>ON2</sub>	PWM on-time	75 kΩ from RT to GND		1000		ns

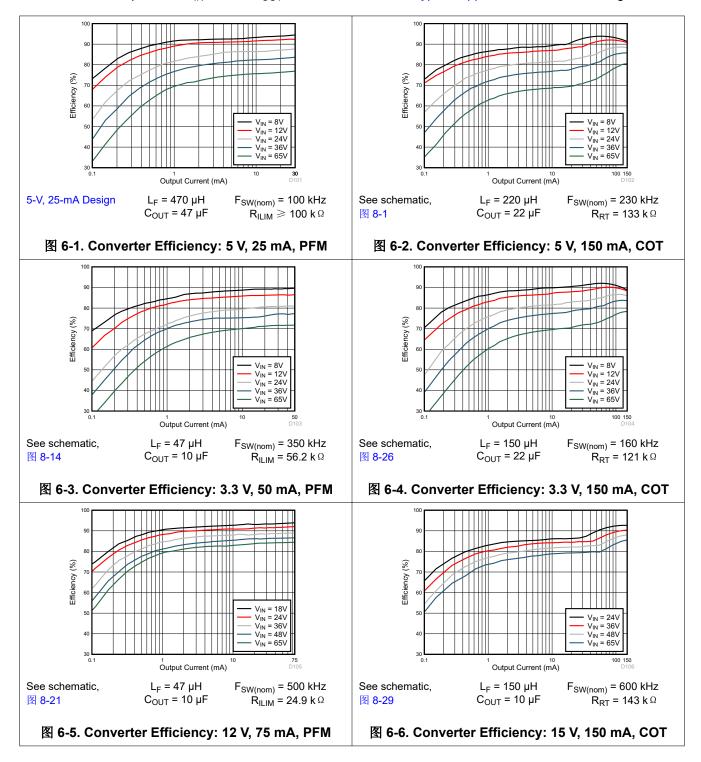
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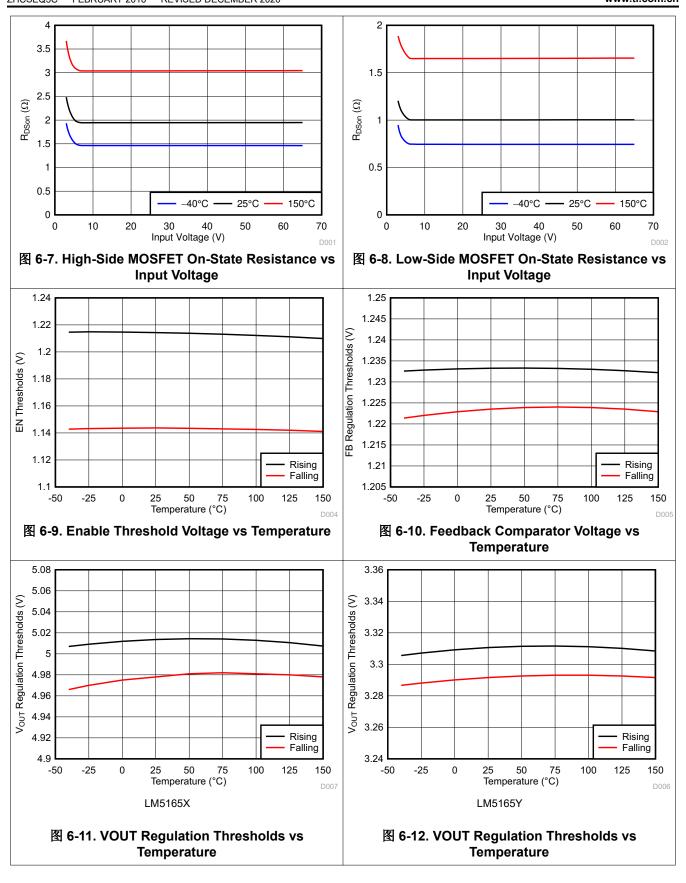
<sup>(2)</sup> The junction temperature ( $T_J$  in °C) is calculated from the ambient temperature ( $T_A$  in °C) and power dissipation ( $P_D$  in Watts) as follows:  $T_J = T_A + (P_D \times R_{\theta JA})$  where  $R_{\theta JA}$  (in °C/W) is the package thermal impedance provided in #6.4.

# **6.7 Typical Characteristics**

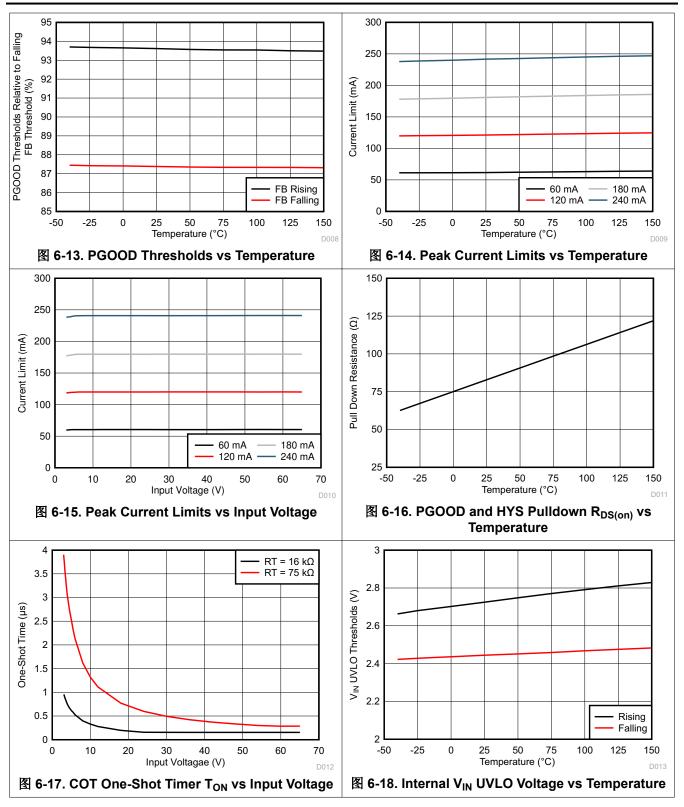
Unless otherwise specified, V<sub>IN</sub> = 12 V, V<sub>OUT</sub> = 5 V. Please refer to *Typical Applications* for circuit designs.



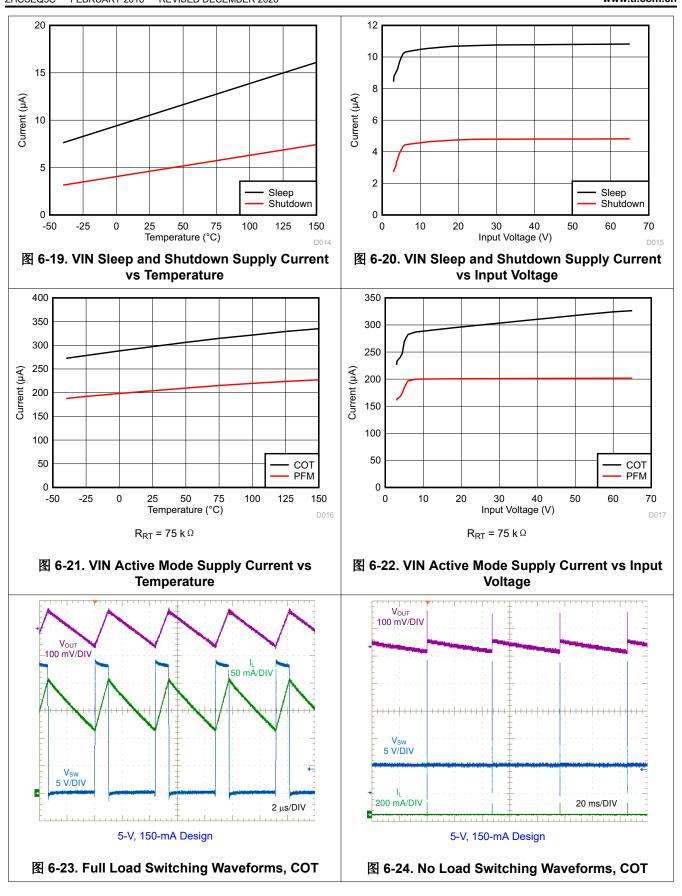


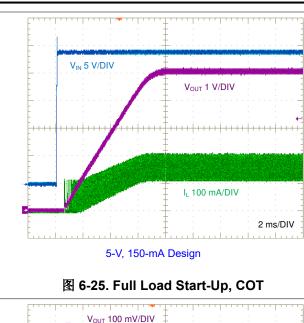


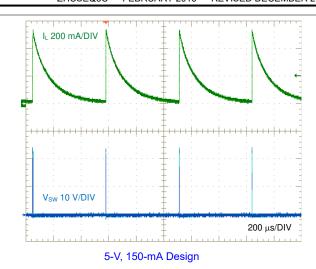


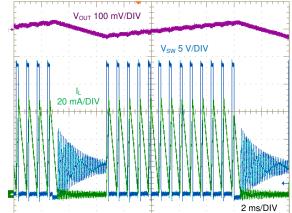














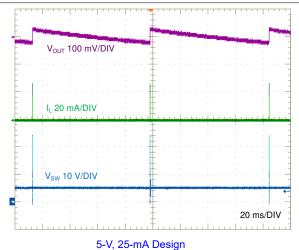


图 6-27. Full Load Switching Waveforms, PFM

5-V, 25-mA Design

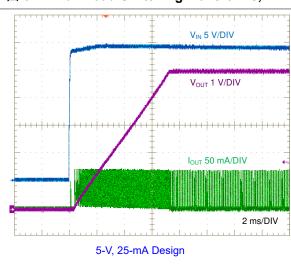


图 6-29. Full Load Start-Up, PFM

图 6-28. No Load Switching Waveforms, PFM

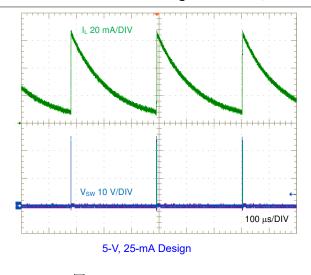


图 6-30. Short Circuit, PFM

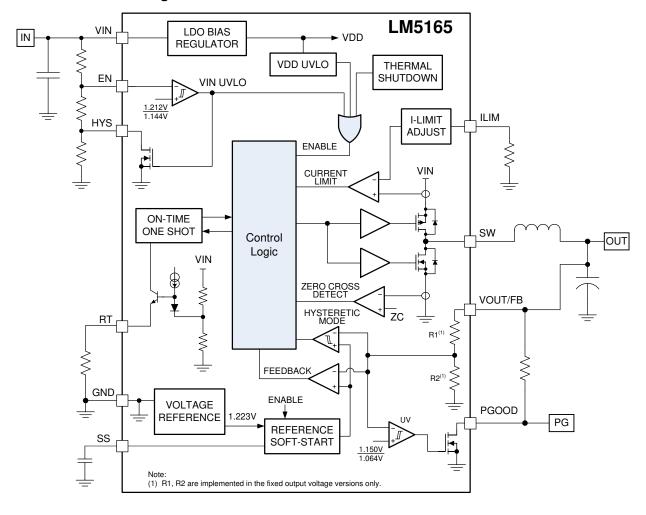
### 7 Detailed Description

#### 7.1 Overview

The LM5165 converter is an easy-to-use synchronous buck DC-DC regulator that operates from a 3-V to 65-V supply voltage. The device is intended for step-down conversions from 3.3-V, 5-V, 12-V, 24-V, and 48-V unregulated, semi-regulated and fully-regulated supply rails. With integrated high-side and low-side power MOSFETs, the LM5165 delivers up to 150-mA DC load current with high efficiency and ultra-low input quiescent current in a very small solution size. Designed for simple implementation, a choice of operating modes offers flexibility to optimize its usage according to the target application. In constant on-time (COT) mode of operation, ideal for low-noise, high current, fast load transient requirements, the device operates with predictive on-time switching pulse. A quasi-fixed switching frequency over the input voltage range is achieved by using an input voltage feedforward to set the on-time. Alternatively, pulse frequency modulation (PFM) mode, complemented by an adjustable peak current limit, achieves exceptional light-load efficiency performance. Control loop compensation is not required with either operating mode, reducing design time and external component count.

The LM5165 incorporates other features for comprehensive system requirements, including an open-drain Power Good circuit for power-rail sequencing and fault reporting, internally-fixed or externally-adjustable soft-start, monotonic start-up into prebiased loads, precision enable with customizable hysteresis for programmable line undervoltage lockout (UVLO), adjustable cycle-by-cycle current limit for optimal inductor sizing, and thermal shutdown with automatic recovery. These features enable a flexible and easy-to-use platform for a wide range of applications. The pin arrangement is designed for simple *Layout*, requiring only a few external components.

### 7.2 Functional Block Diagram



### 7.3 Feature Description

#### 7.3.1 Integrated Power MOSFETs

The LM5165 is a step-down buck converter with integrated high-side PMOS buck switch and low-side NMOS synchronous switch. During the high-side MOSFET on-time, the SW voltage  $V_{SW}$  swings up to approximately  $V_{IN}$ , and the inductor current increases with slope  $(V_{IN} - V_{OUT})/L_F$ . When the high-side MOSFET is turned off by the control logic, the low-side MOSFET turns on after an adaptive deadtime. Inductor current flows through the low-side MOSFET with slope  $-V_{OUT}/L_F$ . Duty cycle D is defined as  $T_{ON}/T_{SW}$ , where  $T_{ON}$  is the high-side MOSFET conduction time and  $T_{SW}$  is the switching period.

### 7.3.2 Selectable PFM or COT Mode Converter Operation

图 7-1 and 图 7-2 show converter schematics for PFM and COT modes of operation.

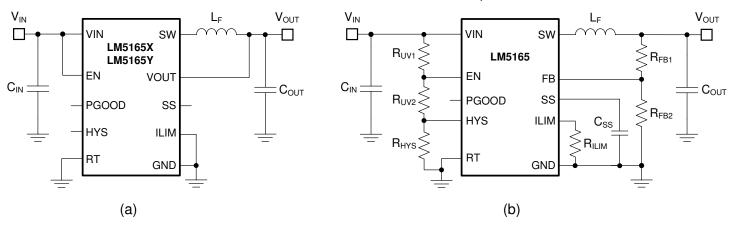


图 7-1. PFM Mode Converter Schematics: (a) Fixed Output Voltage of 5 V or 3.3 V, (b) Adjustable Output Voltage With Programmable Soft Start, Current Limit, and UVLO

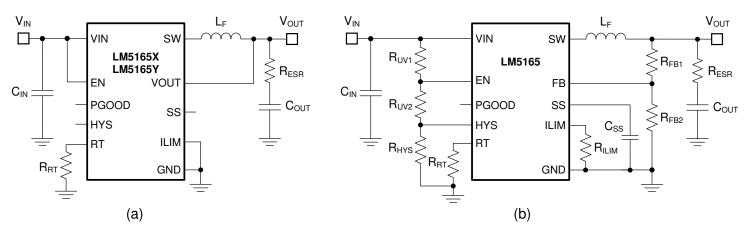


图 7-2. COT Mode Converter Schematics: (a) Fixed Output Voltage of 5 V or 3.3 V, (b) Adjustable Output Voltage With Programmable Soft Start, Current Limit, and UVLO

The LM5165 operates in PFM mode when RT is shorted to GND. Configured as such, the LM5165 behaves as a hysteretic voltage regulator operating in boundary conduction mode, controlling the output voltage within upper and lower hysteresis levels according to the PFM feedback comparator hysteresis of 10 mV. 7-3 is a representation of the relevant output voltage and inductor current waveforms. The LM5165 provides the required switching pulses to recharge the output capacitor, followed by a sleep period where most of the internal circuits are shut off. The load current is supported by the output capacitor during this time, and the LM5165 current consumption approaches the sleep quiescent current of 10.5 μA. The sleep period duration depends on load current and output capacitance.



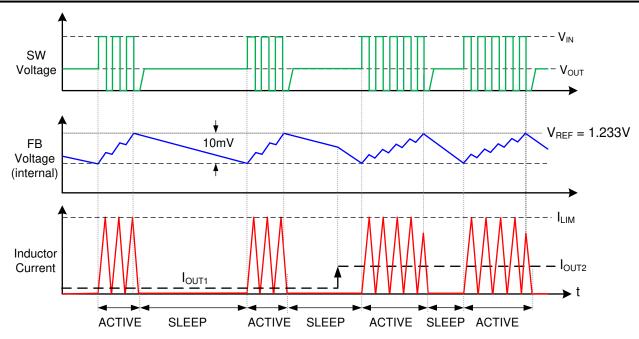


图 7-3. PFM Mode SW Node Voltage, Feedback Voltage, and Inductor Current Waveforms

When operating in PFM mode at given input and output voltages, the chosen filter inductance dictates the PFM pulse frequency in 方程式 1:

$$F_{SW(PFM)} = \frac{V_{OUT}}{L_{F} \cdot I_{PK(PFM)}} \cdot \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$
(1)

#### where

I<sub>PK(PFM)</sub> corresponds to one of the four programmable levels for peak limit of inductor current. See Adjustable
 Current Limit for more detail.

Configured in COT mode, the LM5165 based converter turns on the high-side MOSFET with on-time inversely proportional to  $V_{IN}$  to operate with essentially fixed switching frequency when in continuous conduction mode (CCM). Diode emulation mode (DEM) prevents negative inductor current, and pulse skipping maintains highest efficiency at light load currents by decreasing the effective switching frequency. The COT-controlled LM5165 waveforms in CCM and DEM are represented in  $\[mathbb{R}\]$  7-4. The PWM on-time is set by resistor  $R_{RT}$  connected from RT to GND as shown in  $\[mathbb{R}\]$  7-2. The control loop maintains a constant output voltage by adjusting the PWM off-time.

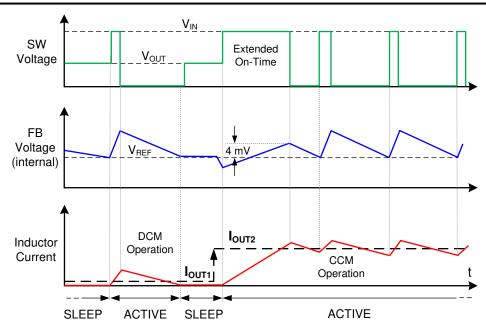


图 7-4. COT Mode SW Node Voltage, Feedback Voltage, and Inductor Current Waveforms

The required on-time adjust resistance for a particular frequency is given in 方程式 2 and tabulated in 表 7-1. The maximum programmable on-time is 15 µs.

$$R_{RT}[k\Omega] = \frac{V_{OUT}[V]}{F_{SW}[kHz]} \cdot \frac{10^4}{1.75}$$
(2)

表 7-1. On-Time Adjust Resistance (E96 EIA Values) for Various Switching Frequencies and Output Voltages

F <sub>SW</sub> (kHz)	R <sub>RT</sub> (kΩ)					
rsw (KHZ)	V <sub>OUT</sub> = 1.8 V	V <sub>OUT</sub> = 3.3 V	V <sub>OUT</sub> = 5 V	V <sub>OUT</sub> = 12 V		
100	102	187	287	681		
200	51.1	95.3	143	240		
300	34	63.4	95.3	226		
400	25.5	47.5	71.5	169		
500	20.5	37.4	57.6	137		
600	16.9	31.6	47.5	115		

The choice of control mode and switching frequency requires a compromise between conversion efficiency, quiescent current, and passive component size. Lower switching frequency implies reduced switching losses (including gate charge losses, transition losses, and so forth) and higher overall efficiency. Higher switching frequency, on the other hand, implies a smaller LC output filter and hence a more compact design. Lower inductance also helps transient response as the large-signal slew rate of inductor current increases. The ideal switching frequency in a given application is a tradeoff and thus is determined on a case-by-case basis. It relates to the input voltage, output voltage, most frequent load current level(s), external component choices, and circuit size requirement. At light loads, the PFM converter has a relatively longer sleep time interval and thus operates with lower input quiescent current and higher efficiency.

#### 7.3.3 COT Mode Light-Load Operation

Diode emulation mode (DEM) operation occurs when the low-side MOSFET switches off as inductor valley current reaches zero. Here, the load current is less than half of the peak-to-peak inductor current ripple in CCM. Turning off the low-side MOSFET at zero current reduces switching loss, and preventing negative current conduction reduces conduction loss. Power conversion efficiency is thus higher in a DEM converter than an equivalent forced-PWM CCM converter. With DEM operation, the duration that both power MOSFETs remain off progressively increases as load current decreases.

#### 7.3.4 Low Dropout Operation and 100% Duty Cycle Mode

If  $R_{DSON1}$  and  $R_{DSON2}$  are the high-side and low-side MOSFET on-state resistances, respectively, and  $R_{DCR}$  is the inductor DC resistance, the duty cycle in COT (CCM) or PFM mode is given by 方程式 3.

$$D = \frac{V_{OUT} + (R_{DSON2} + R_{DCR}) \cdot I_{OUT}}{V_{IN} - (R_{DSON1} - R_{DSON2}) \cdot I_{OUT}} \approx \frac{V_{OUT}}{V_{IN}}$$
(3)

The LM5165 offers a low input voltage to output voltage dropout by engaging the high-side MOSFET at 100% duty cycle. In COT mode, a frequency foldback feature effectively extends maximum duty cycle to 100% during low dropout conditions or load-on transients. Based on the 4-mV FB comparator dropout hysteresis, the duty cycle extends as needed at low input voltage conditions, corresponding to lower switching frequency. The PWM on-time extends based on the requirement that the FB voltage exceeds the dropout hysteresis during a given on-time. 100% duty cycle operation is eventually reached as the input voltage decreases towards the output setpoint. The output voltage stays in regulation at a lower supply voltage, thus achieving an extremely low dropout voltage.

Note that PFM mode operation provides an inherently natural transition to 100% duty cycle if needed for low dropout applications.

Use 方程式 4 to calculate the minimum input voltage to maintain output regulation.

$$V_{IN(min)} = V_{OUT} + I_{OUT} \cdot (R_{DSON1} + R_{DCR})$$
(4)

#### 7.3.5 Adjustable Output Voltage (FB)

Three voltage feedback options are available: the fixed 3.3-V and 5-V versions include internal feedback resistors that sense the output directly through the VOUT pin; the adjustable voltage option senses the output through an external resistor divider connected from the output to the FB pin.

The LM5165 voltage regulation loop regulates the output voltage by maintaining the FB voltage equal to the internal reference voltage,  $V_{REF1}$ . A resistor divider programs the ratio from output voltage  $V_{OUT}$  to FB. For a target  $V_{OUT}$  setpoint, calculate  $R_{FB2}$  based on the selected  $R_{FB1}$  using 方程式 5.

$$R_{FB2} = \frac{1.223V}{V_{OUT} - 1.223V} \cdot R_{FB1}$$
 (5)

Selecting  $R_{FB1}$  in the range of 100 k $\Omega$  to 1 M $\Omega$  is recommended for most applications. A larger  $R_{FB1}$  consumes less DC current, which is mandatory if light-load efficiency is critical. However,  $R_{FB1}$  larger than 1 M $\Omega$  is not recommended as the feedback path becomes more susceptible to noise. High feedback resistances generally require more careful feedback path PCB layout. It is important to route the feedback trace away from the noisy area of the PCB. For more layout recommendations, see *Layout*.

#### 7.3.6 Adjustable Current Limit

The LM5165 manages overcurrent conditions by cycle-by-cycle current limiting of the peak inductor current. The current sensed in the high-side MOSFET is compared every switching cycle to the current limit threshold set by the ILIM pin. Current is sensed after a leading-edge blanking time following the high-side MOSFET turnon transition. The propagation delay of current limit comparator is 100 ns.

Four programmable peak current levels are available: 60 mA, 120 mA, 180 mA and 240 mA, corresponding to resistors of 100 k $\Omega$ , 56.2 k $\Omega$ , 24.9 k $\Omega$  and 0  $\Omega$  connected at the ILIM pin, respectively. In turn, 25-mA, 75-mA, and 100-mA output current levels in boundary conduction mode PFM operation are possible, respectively.

Note that in PFM mode, the inductor current ramps from zero to the chosen peak threshold every switching cycle. Consequently, the maximum output current is equal to half the peak inductor current. Meanwhile, the corresponding output current capability in COT mode is higher as the ripple current is determined by the input and output voltage and the chosen inductance.

### 7.3.7 Precision Enable (EN) and Hysteresis (HYS)

The precision EN input supports adjustable input undervoltage lockout (UVLO) with hysteresis programmed independently through the HYS pin for application specific power-up and power-down requirements. EN connects to a comparator-based input referenced to a 1.212-V bandgap voltage with 68-mV hysteresis. An external logic signal can be used to drive the EN input to toggle the output on and off and for system sequencing or protection. The simplest way to enable the LM5165's operation is to connect EN directly to VIN. This allows the LM5165 to start up when  $V_{IN}$  is within its valid operating range. However, many applications benefit from using a resistor divider  $R_{UV1}$  and  $R_{UV2}$  as shown in  $\boxed{8}$  7-5 to establish a precision UVLO level. In tandem with the EN setting, use HYS to increase the voltage hysteresis as needed.

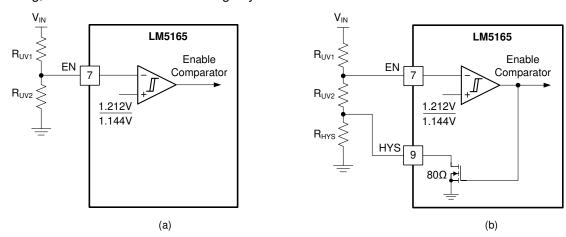


图 7-5. Programmable Input Voltage UVLO With (a) Fixed Hysteresis, (b) Adjustable Hysteresis

Use 方程式 6 and 方程式 7 to calculate the input UVLO voltages turnon and turnoff voltages, respectively.

$$V_{IN(on)} = 1.212V \cdot \left(1 + \frac{R_{UV1}}{R_{UV2}}\right)$$
 (6)

$$V_{IN(off)} = 1.144V \cdot \left(1 + \frac{R_{UV1}}{R_{UV2} + R_{HYS}}\right) \tag{7}$$

There is also a low  $I_Q$  shutdown mode when EN is pulled below a base-emitter voltage drop (approximately 0.6 V at room temperature). If EN is below this hard shutdown threshold, the internal LDO regulator powers off and the internal bias supply rail collapses, shutting down the bias currents of the LM5165. The LM5165 operates in standby mode when the EN voltage is between the hard shutdown and precision enable thresholds.

### 7.3.8 Power Good (PGOOD)

The LM5165 provides a PGOOD flag pin to indicate when the output voltage is within the regulation level. Use the PGOOD signal for start-up sequencing of downstream converters, as shown in 图 7-6, or for fault protection and output monitoring. PGOOD is an open-drain output that requires a pullup resistor to a DC supply not greater

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than 12 V. Typical range of pullup resistance is 10 k $\Omega$  to 100 k $\Omega$ . If necessary, use a resistor divider to decrease the voltage from a higher voltage pullup rail.

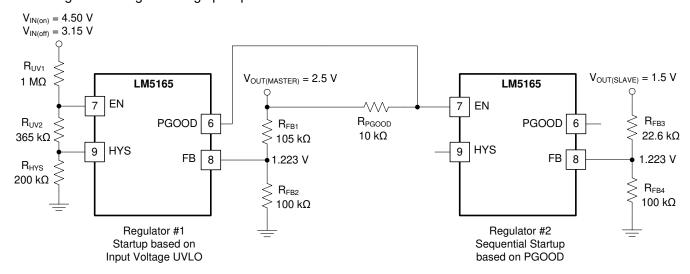


图 7-6. Master-Slave Sequencing Implementation Using PGOOD and EN

When the FB voltage exceeds 94% of the internal reference  $V_{REF1}$ , the internal PGOOD switch turns off and PGOOD can be pulled high by the external pullup. If the FB voltage falls below 87% of  $V_{REF1}$ , the internal PGOOD switch turns on, and PGOOD is pulled low to indicate that the output voltage is out of regulation. The rising edge of PGOOD has a built-in deglitch delay of 5  $\mu$ s.

### 7.3.9 Configurable Soft Start (SS)

The LM5165 has a flexible and easy-to-use soft-start control pin, SS. The soft-start feature prevents inrush current impacting the LM5165 and the input supply when power is first applied. Soft start is achieved by slowly ramping up the target regulation voltage when the device is first enabled or powered up. Selectable and adjustable start-up timing options include minimum delay (no soft-start), 900-µs internally fixed soft start, and an externally programmable soft start.

The simplest way to use the LM5165 is to leave the SS pin open. The LM5165 employs the internal soft-start control ramp and starts up to the regulated output voltage in 900  $\mu$ s. In applications with a large amount of output capacitance, higher  $V_{OUT}$ , or other special requirements, extend the soft-start time by connecting an external capacitor  $C_{SS}$  from SS to GND. Longer soft-start time further reduces the supply current needed to charge the output capacitors and supply any output loading. An internal current source  $I_{SS}$  of 10  $\mu$ A charges  $C_{SS}$  and generates a ramp to control the ramp rate of the output voltage. Use 8 to calculate the  $C_{SS}$  capacitance for a desired soft-start time  $I_{SS}$ .

$$C_{SS}[nF] = 8.1 \cdot t_{SS}[ms]$$
(8)

C<sub>SS</sub> is discharged by an internal FET when V<sub>OUT</sub> is shutdown by EN, UVLO, or thermal shutdown.

It is desirable in some applications for the output voltage to reach its nominal setpoint in the shortest possible time. Connecting a 100-k  $\Omega$  resistor from SS to GND disables the soft-start circuit, and the LM5165 operates in current limit during start-up to rapidly charge the output capacitance.

As negative inductor current is prevented, the LM5165 is capable of start-up into prebiased output conditions. With a prebiased output voltage, the LM5165 waits until the soft-start ramp allows regulation above the prebiased voltage and then follows the soft-start ramp to the regulation setpoint.

#### 7.3.10 Thermal Shutdown

Thermal shutdown is an integrated self-protection to limit junction temperature and prevent damage related to overheating. Thermal shutdown turns off the device when the junction temperature exceeds 170°C to prevent

further power dissipation and temperature rise. Junction temperature decreases after shutdown, and the LM5165 restarts when the junction temperature falls to 160°C.

#### 7.4 Device Functional Modes

#### 7.4.1 Shutdown Mode

The EN pin provides ON and OFF control for the LM5165. When  $V_{EN}$  is below approximately 0.6 V, the device is in shutdown mode. Both the internal LDO and the switching regulator are off. The quiescent current in shutdown mode drops to 4.6  $\mu$ A at  $V_{IN}$  = 12 V. The LM5165 also employs internal bias rail undervoltage protection. If the internal bias supply voltage is below its UV threshold, the regulator remains off.

#### 7.4.2 Standby Mode

The internal bias rail LDO has a lower enable threshold than the regulator itself. When  $V_{EN}$  is above 0.6 V and below the precision enable threshold (1.212 V typically), the internal LDO is on and regulating. The precision enable circuitry is turned on once the internal  $V_{CC}$  is above its UV threshold. The switching action and voltage regulation are not enabled until  $V_{EN}$  rises above the precision enable threshold.

#### 7.4.3 Active Mode in COT

The LM5165 is in active mode when  $V_{EN}$  is above the precision enable threshold and the internal bias rail is above its UV threshold. In COT active mode, the LM5165 is in one of three modes depending on the load current:

- CCM with fixed switching frequency when load current is above half of the peak-to-peak inductor current ripple;
- 2. Pulse skipping and diode emulation mode (DEM) when the load current is less than half of the peak-to-peak inductor current ripple in CCM operation. Refer to COT More Light-Load Operation for more detail;
- 3. Frequency foldback mode to maintain output regulation at low dropout and for improved load-on transient response. Refer to Low Dropout Operation and 100% Duty Cycle Mode for more detail.

#### 7.4.4 Active Mode in PFM

Similarly, the LM5165 is in PFM active mode when  $V_{EN}$  and the internal bias rail are above the relevant thresholds, FB has fallen below the lower hysteresis level ( $V_{REF1}$ ), and boundary conduction mode is recharging the output capacitor to the upper hysteresis level ( $V_{REF2}$ ). There is a 4- $\mu$ s wake- $\mu$ p delay from sleep to active states.

#### 7.4.5 Sleep Mode in PFM

The LM5165 is in PFM sleep mode when  $V_{EN}$  and the internal bias rail are above the relevant threshold levels,  $V_{FB}$  has exceeded the upper hysteresis level ( $V_{REF2}$ ), and the output capacitor is sourcing the load current. In PFM sleep mode, the LM5165 operates with very low quiescent current.

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### **8 Applications and Implementation**

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

#### 8.1 Application Information

The LM5165 only requires a few external components to convert from a wide range of supply voltages to a fixed output voltage. To expedite and streamline the process of designing of a LM5165-based converter, a comprehensive LM5165 Quick-start design tool is available for download to assist the designer with component selection for a given application. WEBENCH® online software is also available to generate complete designs, leveraging iterative design procedures and access to comprehensive component databases. The following sections discuss the design procedure for both COT and PFM modes using specific circuit design examples.

As mentioned previously, the LM5165 also integrates several optional features to meet system design requirements, including precision enable, UVLO, programmable soft start, programmable switching frequency in COT mode, adjustable current limit, and PGOOD indicator. Each application incorporates these features as needed for a more comprehensive design. The application circuits detailed below show LM5165 configuration options suitable for several application use cases. Refer to the LM5165EVM-HD-C50X and LM5165EVM-HD-P50A EVM user's guides for more detail.

### 8.2 Typical Applications

For step-by-step design procedure, circuit schematics, bill of materials, PCB files, simulation and test results of an LM5165-powered implementation, refer to Field Transmitter with Bluetooth® Low Energy Connectivity Powered from 4 to 20-mA Current Loop reference design.

# 8.2.1 Design 1: Wide $V_{IN}$ , Low $I_Q$ COT Converter Rated at 5 V, 150 mA

The schematic diagram of a 5-V, 150-mA COT converter is given in 图 8-1.

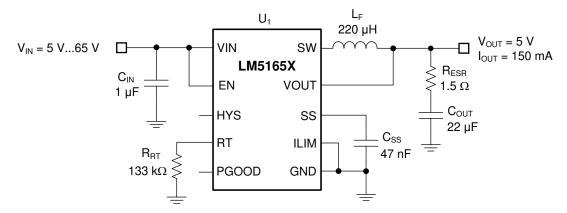


图 8-1. Schematic for Design 1 With  $V_{IN(nom)}$  = 12 V,  $V_{OUT}$  = 5 V,  $I_{OUT(max)}$  = 150 mA,  $F_{SW(nom)}$  = 220 kHz

### 8.2.1.1 Design Requirements

The target full-load efficiency is 91% based on a nominal input voltage of 12 V and an output voltage of 5 V. The required input voltage range is 5 V to 65 V. The LM5165X is chosen to deliver a fixed 5-V output voltage. The switching frequency is set by resistor  $R_{RT}$  at 220 kHz. The output voltage soft-start time is 6 ms. The required components are listed in  $\frac{1}{8}$  8-1.

INSTRUMENTS www.ti.com.cn

#### 表 8-1. List of Components for Design 1

REF DES	QTY	SPECIFICATION	VENDOR	PART NUMBER
C <sub>IN</sub>	1	1 μF, 100 V, X7R, 1206 ceramic	TDK	C3216X7R2A105K160AA
C <sub>OUT</sub>	1	22 μF, 10 V, X7R, 1206 ceramic	Murata	GRM31CR71A226KE15L
L <sub>F</sub>	1	220 μH ±20%, 0.29 A, 0.92 Ω typ DCR, 5.8 x 5.8 x 2.8 mm	Würth Electronik	WE-TPC 5828 744053221
		220 μH ±30%, 0.3 A, 1.25 Ω max DCR, 5.8 x 5.8 x 3.0 mm	Bourns	SRR5028-221Y
R <sub>ESR</sub>	1	1.5 Ω, 5%, 0402	Std	Std
R <sub>RT</sub>	1	133 kΩ, 1%, 0402	Std	Std
C <sub>SS</sub>	1	47 nF, 10 V, X7R, 0402 ceramic	Std	Std
U <sub>1</sub>	1	LM5165X Synchronous Buck Converter, VSON-10, 5V Fixed	TI	LM5165XDRCR

#### 8.2.1.2 Detailed Design Procedure

#### 8.2.1.2.1 Custom Design With WEBENCH® Tools

Click here to create a custom design using the LM5165 device with the WEBENCH® Power Designer.

- Start by entering the input voltage (V<sub>IN</sub>), output voltage (V<sub>OUT</sub>), and output current (I<sub>OUT</sub>) requirements.
- 2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
- 3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

#### 8.2.1.2.2 Switching Frequency - R<sub>T</sub>

As mentioned, the switching frequency of a COT-configured LM5165 is set by the on-time programming resistor at the RT pin. As shown by 方程式 2, a standard 1% resistor of 133 k $\Omega$  gives a switching frequency of 230 kHz.

Note that at very low duty cycles, the minimum controllable on-time of the high-side MOSFET, T<sub>ON(min)</sub>, of 180 ns may affect choice of switching frequency. In CCM, TON(min) limits the voltage conversion step-down ratio for a given switching frequency. The minimum controllable duty cycle is given by 方程式 9:

$$D_{MIN} = T_{ON(min)} \cdot F_{SW}$$
(9)

Given a fixed T<sub>ON(min)</sub>, it follows that higher switching frequency implies a larger minimum controllable duty cycle. Ultimately, the choice of switching frequency for a given output voltage affects the available input voltage range, solution size and efficiency. The maximum supply voltage for a given T<sub>ON(min)</sub> before switching frequency reduction occurs is given by 方程式 10.

$$V_{IN(max)} = \frac{V_{OUT}}{T_{ON(min)} \cdot F_{SW}}$$
(10)

#### 8.2.1.2.3 Filter Inductor - LF

The inductor ripple current (assuming CCM operation) and peak inductor current are given respectively by 方程 式 11 and 方程式 12.



$$\Delta I_{L} = \frac{V_{OUT}}{F_{SW} \cdot L_{F}} \cdot \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \tag{11}$$

$$I_{L(peak)} = I_{OUT(max)} + \frac{\Delta I_L}{2}$$
(12)

For most applications, choose an inductance such that the inductor ripple current,  $\Delta I_L$ , is between 30% and 50% of the rated load current at nominal input voltage. Calculate the inductance using 方程式 13.

$$L_{F} = \frac{V_{OUT}}{F_{SW} \cdot \Delta I_{L(nom)}} \cdot \left(1 - \frac{V_{OUT}}{V_{IN(nom)}}\right)$$
(13)

Choosing a 220-µH inductor in this design results in 55-mA peak-to-peak ripple current at nominal input voltage of 12 V, equivalent to 37% of the 150-mA rated load current. The peak inductor current at maximum input voltage of 65 V is 195 mA, sufficiently below the LM5165 peak current limit of 240 mA.

Check the inductor datasheet to ensure that the inductor's saturation current is well above the current limit setting of a particular design. Ferrite designs have low core loss and are preferred at high switching frequencies, so design goals can then concentrate on copper loss and preventing saturation. However, ferrite core materials exhibit a hard saturation characteristic – the inductance collapses abruptly when the saturation current is exceeded. This results in an abrupt increase in inductor ripple current, higher output voltage ripple, not to mention reduced efficiency and compromised reliability. Note that inductor saturation current generally deceases as the core temperature increases.

#### 8.2.1.2.4 Output Capacitors - COUT

Select the output capacitor to limit the capacitive voltage ripple at the converter output. This is the sinusoidal ripple voltage that arises from the triangular ripple current flowing in the capacitor. Select an output capacitance using 方程式 14 to limit the voltage ripple component to 0.5% of the output voltage.

$$C_{OUT} \ge \frac{\Delta I_{L(nom)} \cdot 100}{F_{SW} \cdot V_{OUT}}$$
(14)

Substituting  $\Delta$  I<sub>L(nom)</sub> of 55 mA gives C<sub>OUT</sub> greater than 5  $\mu$  F. Mindful of the voltage coefficient of ceramic capacitors, select a 22- $\mu$ F, 10-V capacitor with X7R dielectric in 1206 footprint.

### 8.2.1.2.5 Series Ripple Resistor - R<sub>ESR</sub>

Select a series resistor such that sufficient ripple in phase with the SW node voltage appears at the feedback node, FB. Use 5 Reg. 15 to calculate the required ripple resistance, designated R<sub>ESR</sub>.

$$R_{ESR} \ge \frac{20mV \cdot V_{OUT}}{V_{REF} \cdot \Delta I_{L(nom)}}$$
(15)

With  $V_{OUT}$  of 5 V,  $V_{REF}$  of 1.223 V, and  $\triangle$   $I_{L(nom)}$  of 55 mA at the nominal input voltage of 12 V, the required  $R_{ESR}$  is 1.5  $\Omega$ . Calculate the total output voltage ripple in CCM using 方程式 16.

$$\Delta V_{OUT} = \Delta I_{L} \cdot \sqrt{R_{ESR}^{2} + \left(\frac{1}{8 \cdot F_{SW} \cdot C_{OUT}}\right)^{2}}$$
(16)

#### 8.2.1.2.6 Input Capacitor - CIN

An input capacitor is necessary to limit the input ripple voltage while providing switching-frequency AC current to the buck power stage. To minimize the parasitic inductance in the switching loop, position the input capacitors as

close as possible to the VIN and GND pins of the LM5165. The input capacitors conduct a square-wave current of peak-to-peak amplitude equal to the output current. It follows that the resultant capacitive component of AC ripple voltage is a triangular waveform. Together with the ESR-related ripple component, the peak-to-peak ripple voltage amplitude is given by 方程式 17.

$$\Delta V_{IN} = \frac{I_{OUT} \cdot D \cdot (1 - D)}{F_{SW} \cdot C_{IN}} + I_{OUT} \cdot R_{ESR}$$
(17)

The input capacitance required for a particular load current, based on an input voltage ripple specification of  $\Delta V_{IN}$ , is given by 方程式 18.

$$C_{IN} \ge \frac{I_{OUT} \cdot D \cdot (1 - D)}{F_{SW} \cdot (\Delta V_{IN} - I_{OUT} \cdot R_{ESR})}$$
(18)

The recommended high-frequency capacitance is 1  $\mu$ F or higher and should be a high-quality ceramic type X5R or X7R with sufficient voltage rating. Based on the voltage coefficient of ceramic capacitors, choose a voltage rating of twice the maximum input voltage. Additionally, some bulk capacitance is required if the LM5165 circuit is not located within approximately 5 cm from the input voltage source. This capacitor provides damping to the resonance associated with parasitic inductance of the supply lines and high-Q ceramics.

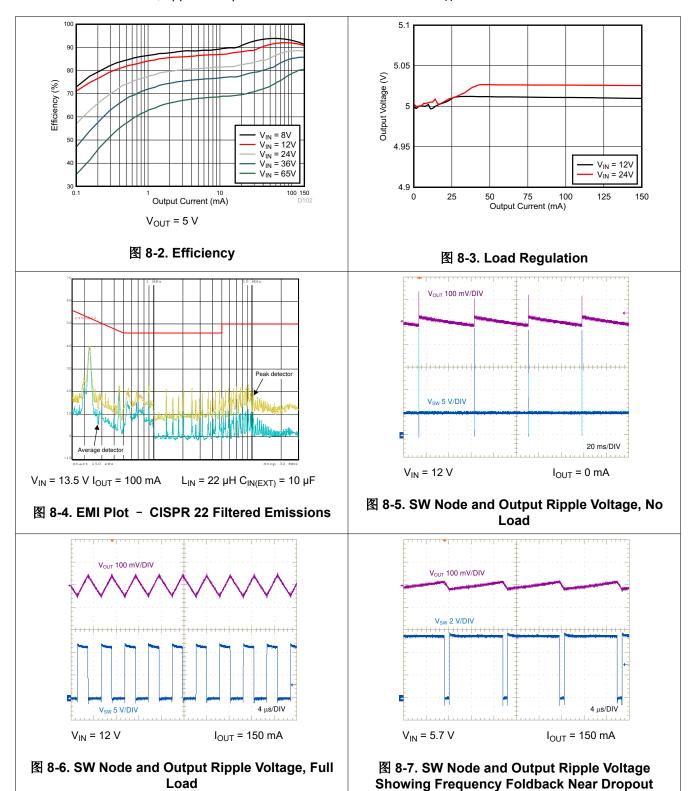
### 8.2.1.2.7 Soft-Start Capacitor - CSS

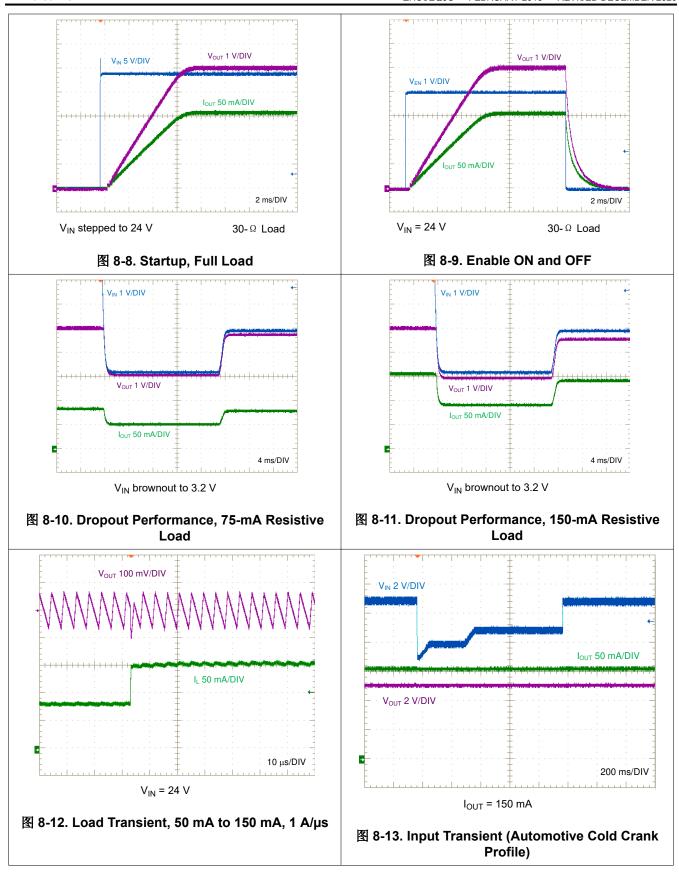
Connect an external soft-start capacitor for a specific soft-start time. In this example, select a soft-start capacitance of 47 nF based on 方程式 8 to achieve a soft-start time of 6 ms.



### 8.2.1.3 Application Curves

Unless otherwise stated, application performance curves were taken at  $T_A$  = 25°C.





#### 8.2.2 Design 2: Small Solution Size PFM Converter Rated at 3.3 V, 50 mA

The schematic diagram of a 3.3-V, 50-mA PFM converter with minimum component count is given in 🗵 8-14.

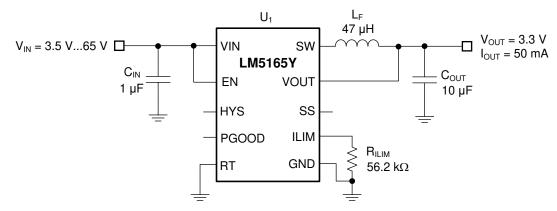


图 8-14. Schematic for Design 2 With  $V_{IN(nom)}$  = 12 V,  $V_{OUT}$  = 3.3 V,  $I_{OUT(max)}$  = 50 mA,  $F_{SW(nom)}$  = 350 kHz

#### 8.2.2.1 Design Requirements

The target full-load efficiency of this design is 88% based on a nominal input voltage of 12 V and an output voltage of 3.3 V. The required total input voltage range is 3.5 V to 65 V. The LM5165 has an internally-set soft-start time of 900  $\mu$ s and an adjustable peak current limit threshold. The BOM is listed in  $\frac{1}{8}$  8-2.

表 8-2. List of Components for Design 2

₹ 6 2. Elst of Components for Besign 2				
REF DES	QTY	SPECIFICATION	VENDOR	PART NUMBER
C <sub>IN</sub>	1	1 μF, 100 V, X7S, 0805 ceramic	TDK	C2012X7S2A474M125AE
C <sub>OUT</sub> 1	1	10 μF, 6.3 V, X7R, 0805 ceramic	Taiyo Yuden	JMK212AB7106KG-T
	'		Murata	GRM21BR70J106KE76K
L <sub>F</sub>	1	47 μH ±20%, 0.56 A, 650 m $\Omega$ maximum DCR, 3.9 × 3.9 × 1.7 mm	Coilcraft	LPS4018-473MRC
		47 μH ±20%, 0.7 A, 620 m Ω typical DCR, 4.0 × 4.0 × 1.8 mm	Würth	74404042470
		47 μH ±20%, 0.57 A, 650 m Ω typical DCR, 4.0 × 4.0 × 1.8 mm	Taiyo Yuden	NR4018T470M
R <sub>ILIM</sub>	1	56.2 k Ω , 1%, 0402	Std	Std
U <sub>1</sub>	1	LM5165Y Synchronous Buck Converter, VSON-10, 3.3-V Fixed	TI	LM5165YDRCR

#### 8.2.2.2 Detailed Design Procedure

### 8.2.2.2.1 Peak Current Limit Setting - RILIM

Install a 56.2-k  $\Omega$  resistor from ILIM to GND to select a 120-mA peak current limit threshold setting to meet the rated output current of 50 mA.

#### 8.2.2.2 Switching Frequency - LF

$$L_{F} = \frac{V_{OUT}}{F_{SW(PFM)} \cdot I_{PK(PFM)}} \cdot \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$
(19)

I<sub>PK(PFM)</sub> in this example is the peak current limit setting of 120 mA plus an additional 10% margin added to include the effect of the 100-ns peak current comparator delay. An additional constraint on the inductance is the 180-ns minimum on-time of the high-side MOSFET. Therefore, to keep the inductor current well controlled,

choose an inductance that is larger than  $L_{F(min)}$  using 方程式 20 where  $V_{IN(max)}$  is the maximum input supply voltage for the application,  $t_{ON(min)}$  is 180 ns, and  $I_{L(max)}$  is the maximum allowed peak inductor current.

$$L_{F(min)} = \frac{V_{IN(max)} \cdot t_{ON(min)}}{I_{L(max)}}$$
(20)

Choose an inductor with saturation current rating above the peak current limit setting, and allow for derating of the saturation current at the highest expected operating temperature.

#### 8.2.2.3 Output Capacitor - COUT

$$\Delta V_{OUT} = \frac{I_{OUT} \cdot 4\mu s}{C_{OUT}} + \frac{V_{OUT}}{123}$$
(21)

Also, the output capacitance must be large enough to accept the energy stored in the inductor without a large deviation in output voltage. Setting this voltage change equal to 0.5% of the output voltage results in:

$$C_{OUT} \ge 100 \cdot L_{F} \cdot \left(\frac{I_{PK(PFM)}}{V_{OUT}}\right)^{2}$$
(22)

In general, select the capacitance of  $C_{OUT}$  to limit the output voltage ripple at full load current, ensuring that it is rated for worst-case RMS ripple current given by  $I_{RMS} = I_{PK(PFM)}/2$ . In this design example, choose a 10- $\mu$ F, 6.3-V ceramic output capacitor with X7R dielectric and 0805 footprint.

#### 8.2.2.2.4 Input Capacitor - CIN

The input capacitor,  $C_{IN}$ , filters the high-side MOSFET's triangular current waveform, see  $\boxed{8}$  10-1. To prevent large ripple voltage, use a low-ESR ceramic input capacitor sized for the worst-case RMS ripple current given by  $I_{RMS} = I_{OUT}/2$ . In this design example, choose a 1- $\mu$ F, 100-V ceramic input capacitor with X7S dielectric and 0805 footprint.

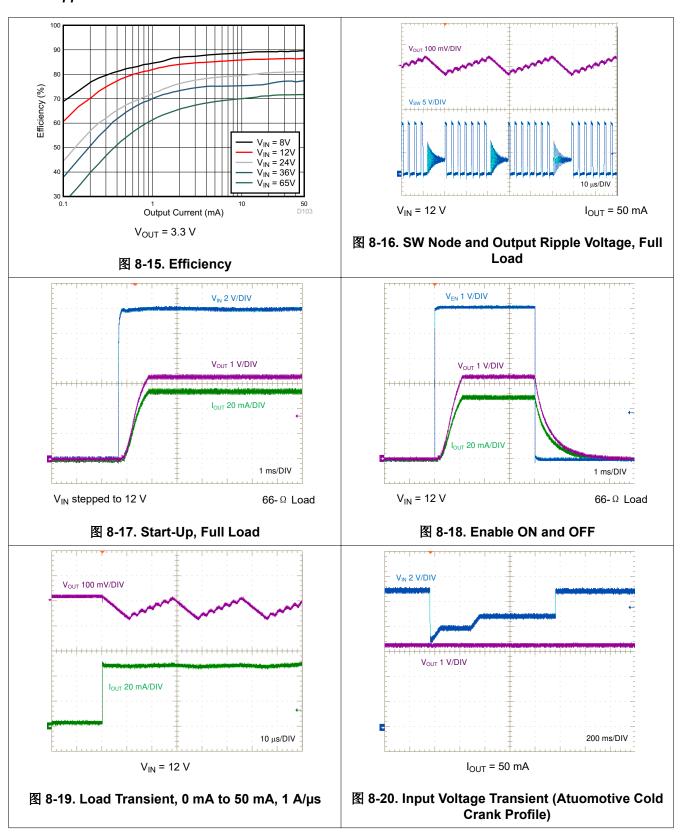
For technical solutions, industry trends, and insights for designing and managing power supplies, please refer to TI's *Power House* blog series.

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#### 8.2.2.3 Application Curves



#### 8.2.3 Design 3: High Density 12-V, 75-mA PFM Converter

The schematic diagram of 12-V, 75-mA PFM converter is given in 

■ 8-21.

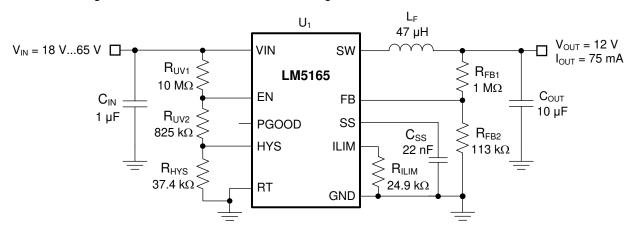


图 8-21. Schematic for Design 3 With  $V_{IN(nom)}$  = 24 V,  $V_{OUT}$  = 12 V,  $I_{OUT(max)}$  = 75 mA,  $F_{SW(nom)}$  = 500 kHz

#### 8.2.3.1 Design Requirements

The full-load efficiency specification is 92% based on a nominal input voltage of 24 V and an output voltage of 12 V. The total input voltage range is 18 V to 65 V, with UVLO turnon and turnoff at 16 V and 14.5 V, respectively. The output voltage setpoint is established by feedback resistors,  $R_{FB1}$  and  $R_{FB2}$ . The switching frequency is set by inductor  $L_F$  at 500 kHz at nominal input voltage. The required components are listed in  $\frac{1}{8}$  8-3.

REF DES	QTY	SPECIFICATION	VENDOR	PART NUMBER
C <sub>IN</sub>	1	1 μF, 100 V, X7S, 0805 ceramic	Murata	GRJ21BC72A105KE11L
		1 μF, 100 V, X7S, 0805 ceramic, AEC-Q200	TDK	CGA4J3X7S2A105K125AE
	_	10 μF, 16 V, X7R, 0805 ceramic	Taiyo Yuden	EMK212BB7106MG-T
C <sub>OUT</sub>	'	10 μF, 16 V, X7R, 0805 ceramic, AEC-Q200	TDK	CGA4J1X7S1C106K125AC
L <sub>F</sub>	1	47 μH ±20%, 0.56 A, 650 m $\Omega$ maximum DCR, 3.9 × 3.9 × 1.7 mm AEC-Q200	Coilcraft	LPS4018-473MRC
R <sub>ILIM</sub>	1	24.9 kΩ, 1%, 0402	Std	Std
R <sub>FB1</sub>	1	1 M Ω , 1%, 0402	Std	Std
R <sub>FB2</sub>	1	113 kΩ, 1%, 0402	Std	Std
R <sub>UV1</sub>	1	10 MΩ, 1%, 0603	Std	Std
R <sub>UV2</sub>	1	825 k Ω , 1%, 0402	Std	Std
R <sub>HYS</sub>	1	37.4 kΩ, 1%, 0402	Std	Std
C <sub>SS</sub>	1	22 nF, 10 V, X7R, 0402	Std	Std
U <sub>1</sub>	1	LM5165 Synchronous Buck Converter, VSON-10, 3 mm × 3 mm	TI	LM5165DRCR

表 8-3. List of Components for Design 3

#### 8.2.3.2 Detailed Design Procedure

The component selection procedure for this PFM design is quite similar to that of Design 2, see 88-14.

#### 8.2.3.2.1 Peak Current Limit Setting - RILIM

Install a 24.9-k  $\Omega$  resistor from ILIM to GND to select the 180-mA peak current limit setting for a rated output current of 75 mA.

#### 8.2.3.2.2 Switching Frequency - L<sub>F</sub>

Tie RT to GND to select PFM mode of operation. Set the switching frequency by the filter inductance,  $L_F$ . Calculate an inductance of 47  $\mu$ H based on the target PFM converter switching frequency of 500 kHz at 24-V

input using 方程式 19. Use a peak current limit setting,  $I_{PK(PFM)}$ , of 180 mA plus an additional 50% margin in this high-frequency design to include the effect of the 100-ns current limit comparator delay. Choose an inductor with saturation current rating well above the peak current limit setting, and allow for derating of the saturation current at the highest expected operating temperature.

### 8.2.3.2.3 Input and Output Capacitors - CIN, COUT

Choose a 1- $\mu$ F, 100-V ceramic input capacitor with 0805 footprint. Such a capacitor is typically available in X5R or X7S dielectric. Based on 方程式 22, select a 10- $\mu$ F, 16-V ceramic output capacitor with X7R dielectric and 0805 footprint.

#### 8.2.3.2.4 Feedback Resistors - RFB1, RFB2

The output voltage of the LM5165 is externally adjustable using a resistor divider network. The divider network comprises the upper feedback resistor  $R_{FB1}$  and lower feedback resistor  $R_{FB2}$ . Select  $R_{FB1}$  of 1 M  $\Omega$  to minimize quiescent current and improve light-load efficiency in this application. With the desired output voltage setpoint of 12 V and  $V_{FB}$  = 1.223 V, calculate the resistance of  $R_{FB2}$  using 5 as 113.5 k  $\Omega$  . Choose the closest available standard value of 113 k  $\Omega$  for  $R_{FB2}$ . Please refer to *Adjustable Output Voltage (FB)* for more detail.

### 8.2.3.2.5 Undervoltage Lockout Setpoint - R<sub>UV1</sub>, R<sub>UV2</sub>, R<sub>HYS</sub>

Adjust the undervoltage lockout (UVLO) using an externally-connected resistor divider network of  $R_{UV1}$ ,  $R_{UV2}$ , and  $R_{HYS}$ . The UVLO has two thresholds, one for power up when the input voltage is rising and one for power down or brownouts when the input voltage is falling. The EN rising threshold for the LM5165 is 1.212 V.

Rearranging 方程式 6 and 方程式 7, the expressions to calculate R<sub>UV2</sub> and R<sub>HYS</sub> are as follows:

$$R_{UV2} = \frac{V_{EN(on)}}{V_{IN(on)} - V_{EN(on)}} \cdot R_{UV1}$$
(23)

$$R_{HYS} = \frac{V_{EN(off)}}{V_{IN(off)} - V_{EN(off)}} \cdot R_{UV1} - R_{UV2}$$
(24)

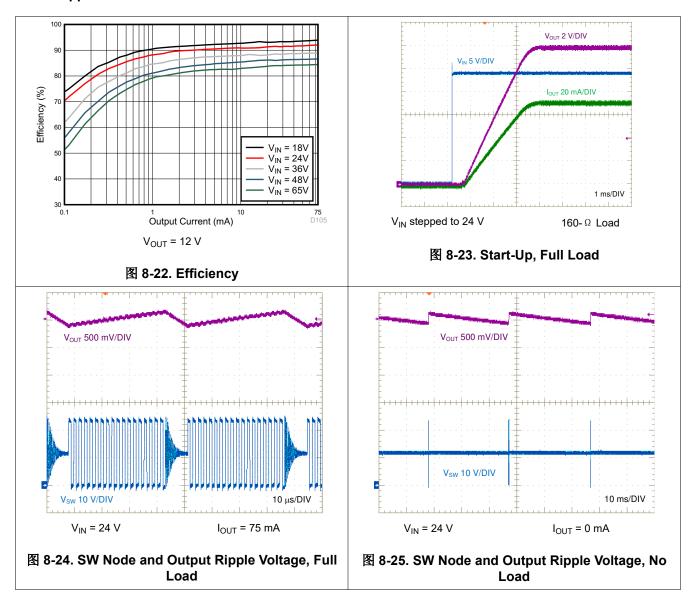
Choose  $R_{UV1}$  as 10  $M\Omega$  to minimize input quiescent current. Given the desired input voltage UVLO thresholds of 16 V and 14.5 V, calculate the resistance of  $R_{UV2}$  and  $R_{HYS}$  as 825  $k\Omega$  and 37.4  $k\Omega$ , respectively. See #7.3.7 for more detail.

#### 8.2.3.2.6 Soft Start - C<sub>SS</sub>

Install a 22-nF capacitor from SS to GND for a soft-start time of 3 ms.



### 8.2.3.3 Application Curves





#### 8.2.4 Design 4: 3.3-V, 150-mA COT Converter With High Efficiency

The schematic diagram of a 3.3-V, 150-mA COT converter is given in 图 8-26.

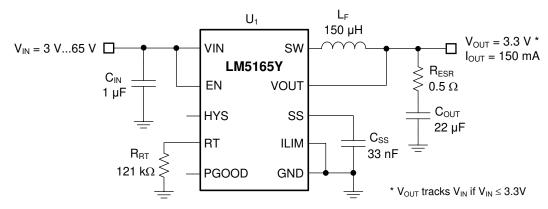


图 8-26. Schematic for Design 4 With  $V_{IN(nom)}$  = 24 V,  $V_{OUT}$  = 3.3 V,  $I_{OUT(max)}$  = 150 mA,  $F_{SW(nom)}$  = 160 kHz

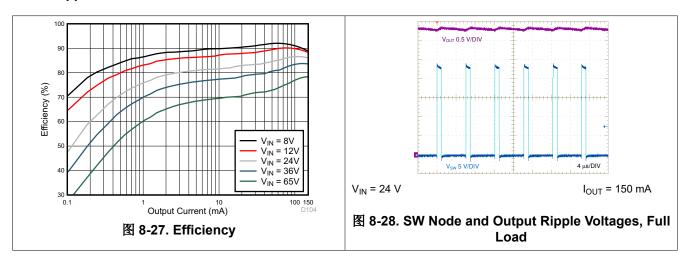
### 8.2.4.1 Design Requirements

The target full-load efficiency is 91% based on a nominal input voltage of 24 V and an output voltage of 3.3 V. The required input voltage range is 3 V to 65 V. The LM5165Y is chosen to deliver a fixed 3.3-V output voltage. The switching frequency is set by resistor  $R_{RT}$  at approximately 160 kHz. The output voltage soft-start time is 4 ms. The required components are listed in  $\frac{1}{8}$  8-4. The component selection procedure for this COT design is quite similar to that of Design 1, see  $\frac{1}{8}$  8-1.

REF DES	QTY	SPECIFICATION	VENDOR	PART NUMBER
KLI DLO	QII	or Loil IOATION	VENDOR	PART NOWIDER
C <sub>IN</sub>	1	1 μF, 100 V, X7R, 1206 ceramic	Murata	GRM31CR72A105KA01L
C <sub>OUT</sub>	1	22 μF, 6.3 V, X7S, 0805 ceramic	Murata	GRM21BR660J226ME39K
L <sub>F</sub>	1	150 μH ±20%, 0.29 A, 0.86 Ω typical DCR, 4.8 × 4.8 × 2.9 mm	Coilcraft	LPS5030-154MLC
R <sub>ESR</sub>	1	0.5 Ω, 5%, 0402	Std	Std
R <sub>RT</sub>	1	121 kΩ, 1%, 0402	Std	Std
C <sub>SS</sub>	1	33 nF, 10 V, X7R, 0402 ceramic	Std	Std
U <sub>1</sub>	1	LM5165Y Synchronous Buck Converter, VSON-10, 3.3-V Fixed	TI	LM5165YDRCR

表 8-4. List of Components for Design 4

#### 8.2.4.2 Application Curves



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#### 8.2.5 Design 5: 15-V, 150-mA, 600-kHz COT Converter

The schematic diagram of a 15-V, 150-mA COT converter is given in 图 8-29.

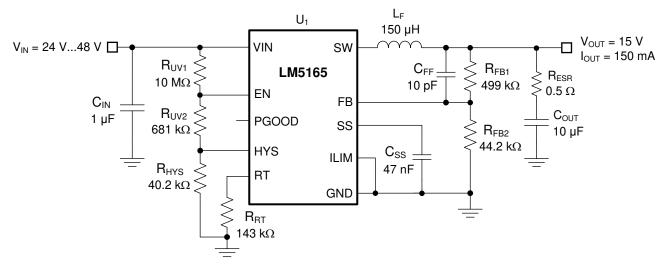


图 8-29. Schematic for Design 5 With  $V_{IN(nom)}$  = 36 V,  $V_{OUT}$  = 15 V,  $I_{OUT(max)}$  = 150 mA,  $F_{SW(nom)}$  = 600 kHz

#### 8.2.5.1 Design Requirements

The target full-load efficiency is 92% based on a nominal input voltage of 36 V and an output voltage of 15 V. The input voltage operating range is 24 V to 48 V, but transients as high as 65 V are possible in the application. UVLO turnon and turnoff are set at 19 V and 17 V, respectively. The LM5165 switching frequency is set at approximately 600 kHz by resistor  $R_{RT}$  of 143 k $\Omega$ . The output voltage soft-start time is 6 ms. The required components are listed in  $\frac{1}{8}$  8-5. The component selection procedure for this COT design is quite similar to that of Design 1, see 8-1.

REF DES	QTY	SPECIFICATION	VENDOR	PART NUMBER
C <sub>IN</sub>	1	1 μF, 100 V, X7R, 1206 ceramic	AVX	12061C105KAT2A
C <sub>OUT</sub>	1	10 μF, 25 V, X7R, 1206 ceramic	Taiyo Yuden	TMK316B7106KL-TD
L <sub>F</sub>	1	150 μH ±20%, 0.29 A, 0.86 Ω typical DCR, 4.8 × 4.8 × 2.9 mm	Coilcraft	LPS5030-154MLC
R <sub>ESR</sub>	1	2.2  \Omega, 5\%, 0402	Std	Std
R <sub>RT</sub>	1	143 k Ω , 1%, 0402	Std	Std
R <sub>FB1</sub>	1	499 k Ω , 1%, 0402	Std	Std
R <sub>FB2</sub>	1	44.2 k Ω , 1%, 0402	Std	Std
R <sub>UV1</sub>	1	10 M Ω , 1%, 0603	Std	Std
R <sub>UV2</sub>	1	681 kΩ, 1%, 0402	Std	Std
R <sub>HYS</sub>	1	40.2 kΩ, 1%, 0402	Std	Std
C <sub>FF</sub>	1	10 pF, 10 V, X7R, 0402 ceramic	Std	Std
C <sub>SS</sub>	1	47 nF, 10 V, X7R, 0402 ceramic	Std	Std
U <sub>1</sub>	1	LM5165 Synchronous Buck Converter, VSON-10, 3 mm × 3 mm	TI	LM5165DRCR

表 8-5. List of Components for Design 5

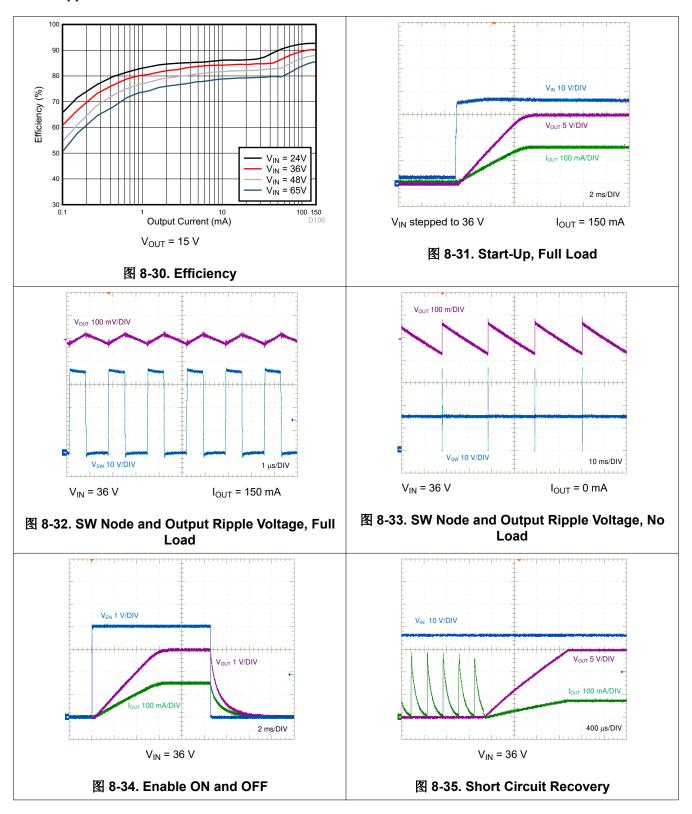
#### 8.2.5.2 Detailed Design Procedure

### 8.2.5.2.1 COT Output Ripple Voltage Reduction

Depending on the required ripple resistance when operating in COT mode, the resultant output voltage ripple may be deemed too high for a given application. One option is to place a feedforward capacitor  $C_{FF}$  in parallel with the upper feedback resistor  $R_{FB1}$ . Capacitor  $C_{FF}$  increases the high-frequency gain from  $V_{OUT}$  to  $V_{FB}$  close to unity such that the output voltage ripple couples directly to the FB node.



### 8.2.5.3 Application Curves



### 9 Power Supply Recommendations

The LM5165 is designed to operate from an input voltage supply range between 3 V and 65 V. This input supply should be able to provide the maximum input current and maintain a voltage above 3 V. Ensure that the resistance of the input supply rail is low enough that an input current transient does not cause a high enough drop at the LM5165 supply rail to cause a false UVLO fault triggering and system reset. If the input supply is located more than a few inches from the LM5165 converter, additional bulk capacitance may be required in addition to the ceramic input capacitance. A 4.7-  $\mu$  F electrolytic capacitor is a typical choice for this function, whereby the capacitor ESR provides a level of damping against input filter resonances. A typical ESR of 0.5  $\Omega$  provides enough damping for most input circuit configurations.

### 10 Layout

The performance of any switching converter depends as much upon PCB layout as it does the component selection. The following guidelines are provided to assist with designing a PCB with the best power conversion performance, thermal performance, and minimized generation of unwanted EMI.

#### 10.1 Layout Guidelines

PCB layout is a critical for good power supply design. There are several paths that conduct high slew-rate currents or voltages that can interact with stray inductance or parasitic capacitance to generate noise and EMI or degrade the power supply's performance.

- Bypass the VIN pin to GND with a low-ESR ceramic capacitor of X5R or X7R dielectric. Place C<sub>IN</sub> as close as
  possible to the LM5165 VIN and GND pins. Ground return paths for both the input and output capacitors
  should consist of localized top-side planes that connect to the GND pin and exposed PAD.
- 2. Minimize the loop area formed by the input capacitor connections and the VIN and GND pins.
- 3. Locate the power inductor close to the SW pin. Minimize the area of the SW trace or plane to prevent excessive capacitive coupling.
- 4. Tie the GND pin directly to the power pad under the device and to a heat-sinking PCB ground plane.
- 5. Use a ground plane in one of the middle layers as a noise shielding and heat dissipation path.
- 6. Have a single-point ground connection to the plane. Route the ground connections for the feedback, soft-start, and enable components to the ground plane. This prevents any switched or load currents from flowing in analog ground traces. If not properly handled, poor grounding results in degraded load regulation or erratic output voltage ripple behavior.
- 7. Make V<sub>IN</sub>, V<sub>OUT</sub> and ground bus connections as wide as possible. This reduces any voltage drops on the input or output paths of the converter and maximizes efficiency.
- 8. Minimize trace length to the FB pin. Locate both feedback resistors close to the FB pin. Place C<sub>FF</sub> (if used) directly in parallel with R<sub>FB1</sub>. Route the V<sub>OUT</sub> sense path away from noisy nodes and preferably on a layer at the other side of a shielding layer.
- 9. Locate the components at RT and SS as close as possible to the device. Route with minimal trace lengths.
- 10. Provide adequate heatsinking for the LM5165 to keep the junction temperature below 150°C. For operation at full rated load, the top-side ground plane is an important heat-dissipating area. Use an array of heat-sinking vias to connect the exposed PAD to the PCB ground plane. If the PCB has multiple copper layers, connect these thermal vias to inner-layer ground planes.

#### 10.1.1 Compact PCB Layout for EMI Reduction

Radiated EMI generated by high di/dt components relates to pulsing currents in switching converters. The larger area covered by the path of a pulsing current, the more electromagnetic emission is generated. The key to minimize radiated EMI is to identify the pulsing current path and minimize the area of that path.

The critical switching loop of the power stage in terms of EMI is denoted in 🛭 10-1. The topological architecture of a buck converter means that a particularly high di/dt current effective path exists in the loop comprising the input capacitor and the LM5165's integrated MOSFETs, and it becomes mandatory to reduce the parasitic inductance of this loop by minimizing the effective loop area.



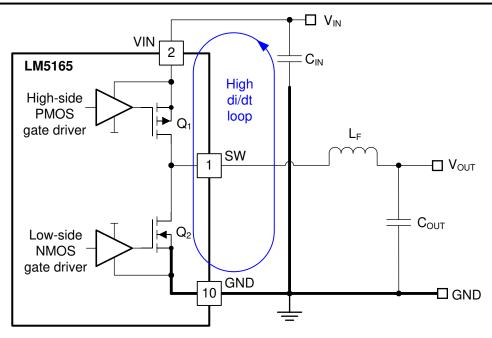


图 10-1. Synchronous Buck Converter With Power Stage Critical Switching Loop

The input capacitor provides the primary path for the high di/dt components of the high-side MOSFET's current. Placing a ceramic capacitor as close as possible to the VIN and GND pins is the key to EMI reduction. Keep the trace connecting SW to the inductor as short as possible and just wide enough to carry the load current without excessive heating. Use short, thick traces or copper pours (shapes) for current conduction path to minimize parasitic resistance. Place the output capacitor close to the  $V_{OUT}$  side of the inductor, and connect the capacitor's return terminal to the LM5165's GND pin and exposed PAD.

#### 10.1.2 Feedback Resistor Layout

For the adjustable output voltage version of the LM5165, reduce noise sensitivity of the output voltage feedback path by placing the resistor divider close to the FB pin, rather than close to the load. This reduces the trace length of FB signal and noise coupling. The FB pin is the input to the feedback comparator and, as such, is a high impedance node sensitive to noise. The output node is a low impedance node, so the trace from  $V_{OUT}$  to the resistor divider can be long if a short path is not available.

Route the voltage sense trace from the load to the feedback resistor divider away from the SW node path, the inductor and  $V_{IN}$  path to avoid contaminating the feedback signal with switch noise, while also minimizing the trace length. This is most important when high feedback resistances, greater than 100 k $\Omega$ , are used to set the output voltage. Also, route the voltage sense trace on a different layer from the inductor, SW node and  $V_{IN}$  path, such that there is a ground plane that separates the feedback trace from the inductor and SW node copper polygon. This provides further shielding for the voltage feedback path from switching noise sources.



# 10.2 Layout Example

☑ 10-2 shows an example layout for the PCB top layer of a single-sided design. The bottom layer is essentially a full ground plane except for short connecting traces for SW, EN, and PGOOD.

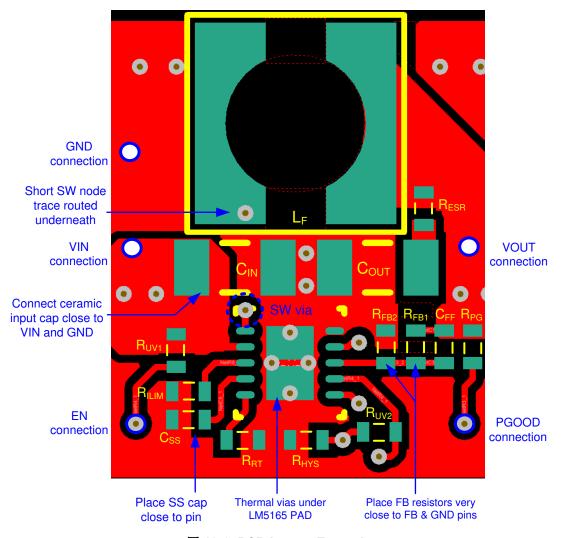


图 10-2. PCB Layout Example



# 11 Device and Documentation Support

# 11.1 Device Support

# 11.1.1 Third-Party Products Disclaimer

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## 11.1.2 Development Support

For development support, see the following:

- LM5165 Quick-start Design Tool
- LM5165 Simulation Models
- For TI's reference design library, visit TIDesigns
- For TI's WEBENCH Design Environment, visit the WEBENCH® Design Center
- To view a related device of this product, see the LM5166

### 11.1.3 Custom Design With WEBENCH® Tools

Click here to create a custom design using the LM5165 device with WEBENCH® Power Designer.

- 1. Start by entering the input voltage  $(V_{IN})$ , output voltage  $(V_{OUT})$ , and output current  $(I_{OUT})$  requirements.
- 2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
- 3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- · Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- · Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

### 11.2 Documentation Support

#### 11.2.1 Related Documentation

For related documentation, see the following:

- LM5165EVM-HD-P50A EVM User's Guide (SNVU474)
- LM5165EVM-HD-C50X EVM User's Guide (SNVU511)
- LM5166EVM-C50A EVM User's Guide (SNVU485)
- Low-I<sub>O</sub> Synchronous Buck Converter Enables Intelligent Field-sensor Applications (SLYT671)
- Low EMI Buck Converter Powers a Multivariable Sensor Transmitter with BLE Connectivity (SLYT693)
- TI Designs:
  - Field Transmitter with Bluetooth® Low Energy Connectivity Powered from 4 to 20-mA Current Loop (TIDUC27)
  - 24-V AC Power Stage with Wide V<sub>IN</sub> Converter and Battery Backup for Smart Thermostat (TIDUCE1)
  - 24-V AC Power Stage with Wide V<sub>IN</sub> Converter and Battery Gauge for Smart Thermostat (TIDUCW0)
- Industrial Strength Blogs:
  - Powering Smart Sensor Transmitters in Industrial Applications

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- Trends in Building Automation: Predictive Maintenance
- Trends in Building Automation: Connected Sensors for User Comfort



- · White Paper:
  - Valuing Wide V<sub>IN</sub>, Low-EMI Synchronous Buck Circuits for Cost-Effective, Demanding Applications (SLYY104)
- Selecting an Ideal Ripple Generation Network for Your COT Buck Converter (SNVA776)
- AN-2162: Simple Success with Conducted EMI from DC-DC Converters (SNVA489)
- Automotive Cranking Simulator User's Guide (SLVU984)
- Using New Thermal Metrics (SBVA025)
- Semiconductor and IC Package Thermal Metrics (SPRA953)

# 11.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

## 11.4 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

#### 11.5 Trademarks

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### 11.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 11.7 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this datasheet, refer to the left-hand navigation.

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10-Dec-2020

#### PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
LM5165DRCR	ACTIVE	VSON	DRC	10	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 150	5165	Samples
LM5165DRCT	ACTIVE	VSON	DRC	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 150	5165	Samples
LM5165XDRCR	ACTIVE	VSON	DRC	10	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 150	5165X	Samples
LM5165XDRCT	ACTIVE	VSON	DRC	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 150	5165X	Samples
LM5165YDRCR	ACTIVE	VSON	DRC	10	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 150	5165Y	Samples
LM5165YDRCT	ACTIVE	VSON	DRC	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 150	5165Y	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.



# **PACKAGE OPTION ADDENDUM**

10-Dec-2020

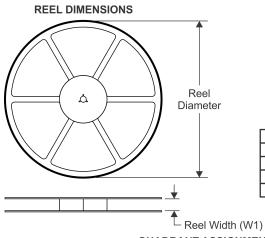
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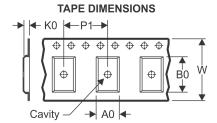
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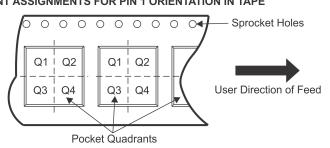
# TAPE AND REEL INFORMATION





	Dimension designed to accommodate the component width
	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

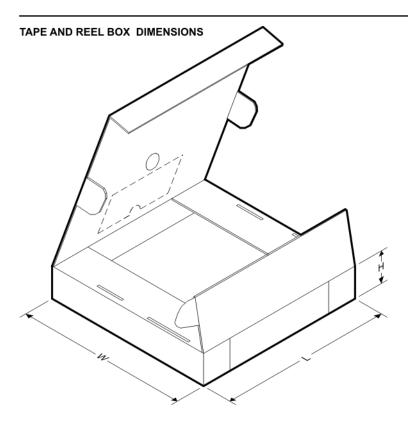


### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LM5165DRCR	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LM5165DRCR	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LM5165DRCT	VSON	DRC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LM5165DRCT	VSON	DRC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LM5165XDRCR	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LM5165XDRCR	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LM5165XDRCT	VSON	DRC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LM5165XDRCT	VSON	DRC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LM5165YDRCR	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LM5165YDRCR	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LM5165YDRCT	VSON	DRC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LM5165YDRCT	VSON	DRC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2



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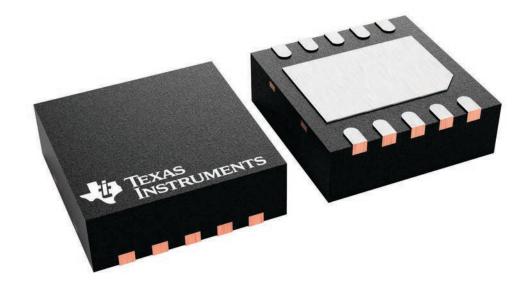
\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LM5165DRCR	VSON	DRC	10	3000	367.0	367.0	35.0
LM5165DRCR	VSON	DRC	10	3000	367.0	367.0	35.0
LM5165DRCT	VSON	DRC	10	250	210.0	185.0	35.0
LM5165DRCT	VSON	DRC	10	250	210.0	185.0	35.0
LM5165XDRCR	VSON	DRC	10	3000	367.0	367.0	35.0
LM5165XDRCR	VSON	DRC	10	3000	367.0	367.0	35.0
LM5165XDRCT	VSON	DRC	10	250	210.0	185.0	35.0
LM5165XDRCT	VSON	DRC	10	250	210.0	185.0	35.0
LM5165YDRCR	VSON	DRC	10	3000	367.0	367.0	35.0
LM5165YDRCR	VSON	DRC	10	3000	367.0	367.0	35.0
LM5165YDRCT	VSON	DRC	10	250	210.0	185.0	35.0
LM5165YDRCT	VSON	DRC	10	250	210.0	185.0	35.0

3 x 3, 0.5 mm pitch

PLASTIC SMALL OUTLINE - NO LEAD

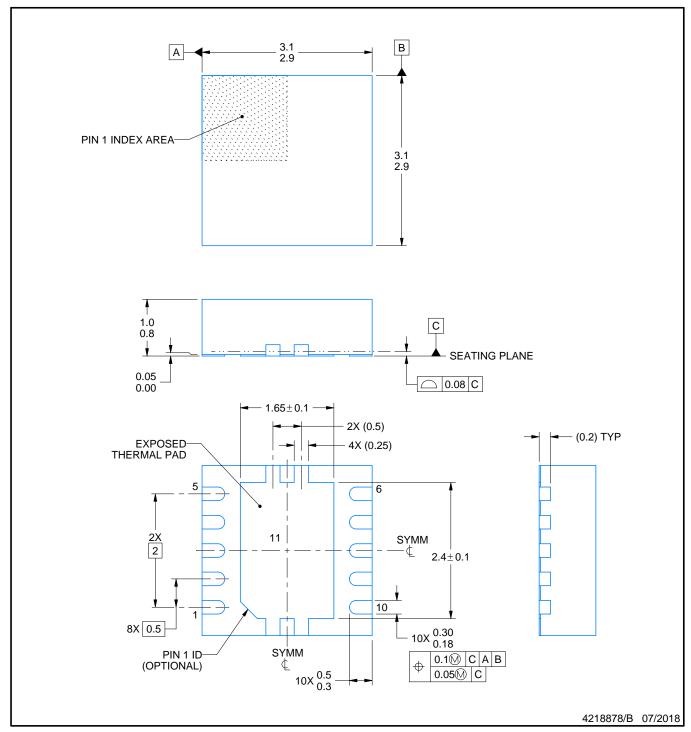
This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



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PLASTIC SMALL OUTLINE - NO LEAD

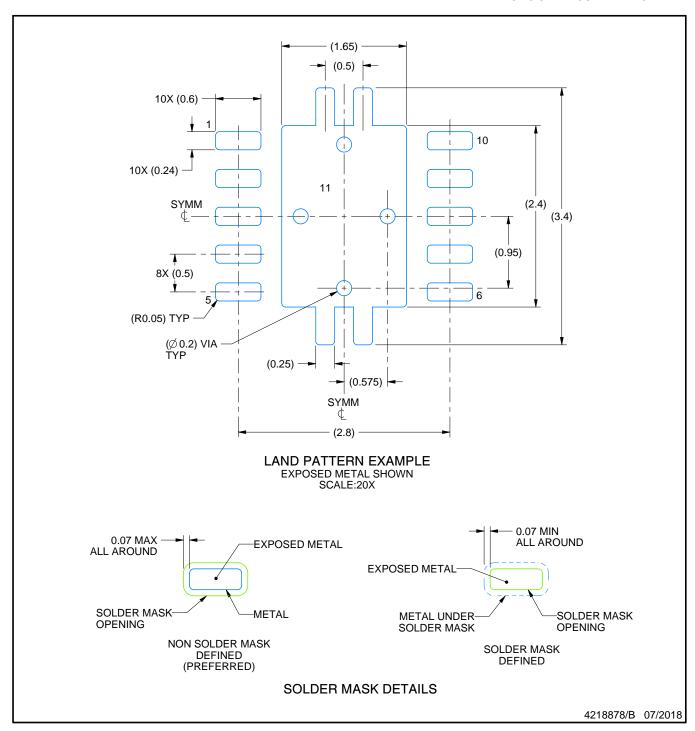


### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
  2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.



PLASTIC SMALL OUTLINE - NO LEAD

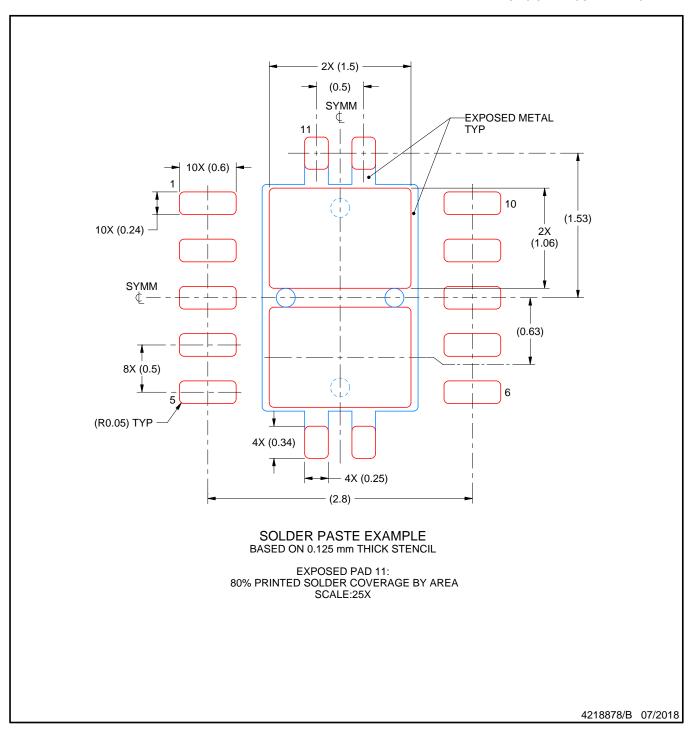


NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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