

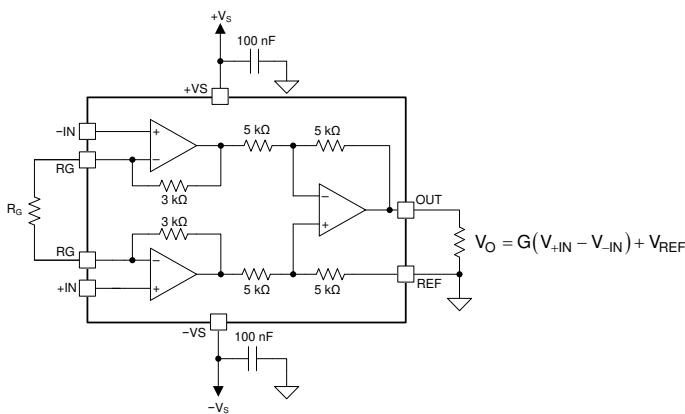
# INA849 Ultra-Low-Noise (1 nV/ $\sqrt{\text{Hz}}$ ), High-Bandwidth, Instrumentation Amplifier

## 1 Features

- Ultra-low noise: 1-nV/ $\sqrt{\text{Hz}}$  input voltage noise (typical)
- Precision super-beta input performance:
  - Low offset voltage: 35  $\mu\text{V}$  (maximum)
  - Low offset voltage drift: 0.4  $\mu\text{V}/^\circ\text{C}$  (maximum)
  - Low input bias current: 20 nA (maximum)
  - Low gain drift: 5 ppm/ $^\circ\text{C}$  for  $G = 1$  (maximum)
- Bandwidth: 28 MHz ( $G = 1$ ), 8 MHz ( $G = 100$ )
- Slew rate: 35 V/ $\mu\text{s}$
- Common-mode rejection: 120 dB (minimum) for maximum gain
- Supply range:
  - Single supply: 8 V to 36 V
  - Dual supply:  $\pm 4$  V to  $\pm 18$  V
- Specified temperature range:  $-40^\circ\text{C}$  to  $+125^\circ\text{C}$
- Packages: 8-pin SOIC and VSSOP

## 2 Applications

- Analog input module
- Microphone preamplifier
- Flow transmitter
- Battery test
- LCD test
- Electrocardiogram (ECG)
- Surgical equipment
- Process analytics (pH, gas, concentration, force and humidity)



INA849 Simplified Internal Schematic

## 3 Description

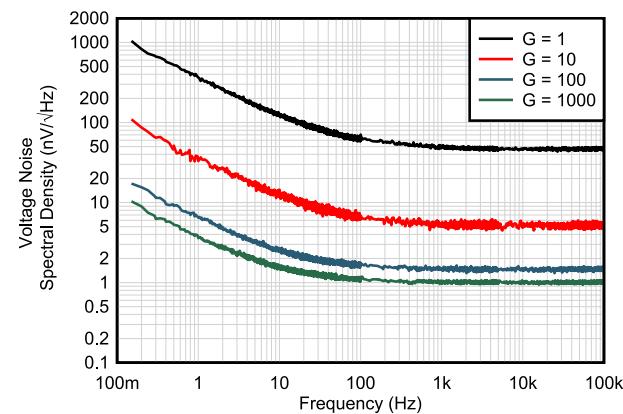
The INA849 is an ultra-low noise instrumentation amplifier optimized for maximum accuracy in high-resolution systems and operation over a wide single-supply or dual-supply range. The device offers significantly lower input bias current than competitors as a result of super-beta input transistors. A state-of-the-art manufacturing process provides exceptionally low voltage noise, input offset voltage, and offset voltage drift.

Precisely matched integrated resistors provide a high, 92-dB ( $G = 1$ ) common-mode rejection across the full input common-mode range. A single external resistor sets any gain from 1 to 10,000. The current-feedback topology of the INA849 provides wide bandwidth at higher gains for very-small, fast-moving signals. For example, the device provides 8 MHz of bandwidth at  $G = 100$ , and 28 MHz at a  $G = 1$ , with a fast 0.4- $\mu\text{s}$  settling time (0.01%) for directly driving high-resolution, analog-to-digital converters (ADCs).

### Device Information

PART NUMBER	PACKAGE <sup>(1)</sup>	BODY SIZE (NOM)
INA849	SOIC (8)	4.90 mm $\times$ 3.91 mm
	VSSOP (8)	3.00 mm $\times$ 3.00 mm

(1) See the package option addendum at the end of the data sheet for all available packages.



Input-Referred Voltage Noise Spectral Density vs Frequency



An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.

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## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

<b>Changes from Revision A (December 2020) to Revision B (April 2021)</b>	<b>Page</b>
• Changed DGK (VSSOP-8) package from advanced information (preview) to production data (active) .....	<b>1</b>
• Changed typical value of current noise from 1.6 pA/ $\sqrt{\text{Hz}}$ to 1.1 pA/ $\sqrt{\text{Hz}}$ .....	<b>5</b>
• Added note 9.....	<b>5</b>
• Changed Figure 7-25, <i>Current Noise Spectral Density vs Frequency (RTI)</i> .....	<b>8</b>
• Changed Figure 7-42, <i>Total Harmonic Distortion vs Frequency</i> .....	<b>8</b>
• Changed Figure 7-43, <i>Total Harmonic Distortion vs Frequency at Different Loads</i> .....	<b>8</b>
• Changed Figure 7-44, <i>Second Harmonic Distortion vs Frequency</i> .....	<b>8</b>
• Changed Figure 7-45, <i>Third Harmonic Distortion vs Frequency</i> .....	<b>8</b>

<b>Changes from Revision * (November 2020) to Revision A (December 2020)</b>	<b>Page</b>
• Changed INA849 device from advanced information (preview) to production data (active).....	<b>1</b>
• Added preview DGK package and associated content.....	<b>1</b>

## 5 Device Comparison Table

DEVICE	DESCRIPTION	GAIN EQUATION	RG PINS AT PIN
<a href="#">INA159</a>	G = 0.2 V differential amplifier for $\pm 10\text{-V}$ to 3-V and 5-V conversion	$G = 0.2 \text{ V/V}$	N/A
<a href="#">INA819</a>	35- $\mu\text{V}$ offset, 0.4- $\mu\text{V}/^\circ\text{C}$ $V_{OS}$ drift, 8- $\text{nV}/\sqrt{\text{Hz}}$ noise, low-power, precision instrumentation amplifier	$G = 1 + 50 \text{ k}\Omega / \text{RG}$	2, 3
<a href="#">INA818</a>	35- $\mu\text{V}$ offset, 0.4- $\mu\text{V}/^\circ\text{C}$ $V_{OS}$ drift, 8- $\text{nV}/\sqrt{\text{Hz}}$ noise, low-power, precision instrumentation amplifier	$G = 1 + 50 \text{ k}\Omega / \text{RG}$	1, 8
<a href="#">INA821</a>	35- $\mu\text{V}$ offset, 0.4- $\mu\text{V}/^\circ\text{C}$ $V_{OS}$ drift, 7- $\text{nV}/\sqrt{\text{Hz}}$ noise, high-bandwidth, precision instrumentation amplifier	$G = 1 + 49.4 \text{ k}\Omega / \text{RG}$	2, 3
<a href="#">INA828</a>	50- $\mu\text{V}$ offset, 0.5- $\mu\text{V}/^\circ\text{C}$ $V_{OS}$ drift, 7- $\text{nV}/\sqrt{\text{Hz}}$ noise, low-power, precision instrumentation amplifier	$G = 1 + 50 \text{ k}\Omega / \text{RG}$	1, 8
<a href="#">INA333</a>	25- $\mu\text{V}$ $V_{OS}$ , 0.1- $\mu\text{V}/^\circ\text{C}$ $V_{OS}$ drift, 1.8-V to 5-V, RRO, 50- $\mu\text{A}$ $I_Q$ , chopper-stabilized INA	$G = 1 + 100 \text{ k}\Omega / \text{RG}$	1, 8
<a href="#">INA848</a>	Ultra-low-noise (1.5- $\text{nV}/\sqrt{\text{Hz}}$ ), high-bandwidth instrumentation amplifier with fixed gain of 2000	$G = 2000 \text{ V/V}$	N/A
<a href="#">PGA280</a>	Zero-drift, high-voltage programmable gain instrumentation amplifier with signal integrity test capability (overload detection, input switch matrix, wire break test, SPI with checksum, GPIO ports)	Digitally programmable	N/A
<a href="#">PGA112</a>	Precision programmable gain op amp with SPI	Digitally programmable	N/A

## 6 Pin Configuration and Functions

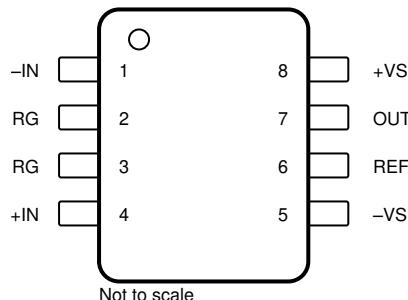


Figure 6-1. D Package (8-Pin SOIC) and DGK Package (8-Pin VSSOP), Top View

Table 6-1. Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
-IN	1	I	Negative (inverting) input
+IN	4	I	Positive (noninverting) input
OUT	7	O	Output
RG	2, 3	—	Gain setting pin. Place a gain resistor between pin 2 and pin 3.
REF	6	I	Reference input. This pin must be driven by a low impedance source.
-VS	5	—	Negative supply
+VS	8	—	Positive supply

## 7 Specifications

### 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

			MIN	MAX	UNIT
V <sub>S</sub>	Supply voltage	Single supply, V <sub>S</sub> = (+V <sub>S</sub> )		40	V
		Dual supply, V <sub>S</sub> = (+V <sub>S</sub> ) – (–V <sub>S</sub> )		±20	
V <sub>I</sub>	Signal input pins	Voltage	(–V <sub>S</sub> ) – 0.5	(+V <sub>S</sub> ) + 0.5	V
		Current	–10	+10	
	Signal differential input voltage	Gain ≤ 4	–V <sub>S</sub>	+V <sub>S</sub>	V
		4 < Gain < 50	(–V <sub>S</sub> ) / Gain	(+V <sub>S</sub> ) / Gain	
		Gain > 50	–1 V	+1 V	
V <sub>REF</sub>	Reference input voltage		(–V <sub>S</sub> ) – 0.5	(+V <sub>S</sub> ) + 0.5	V
V <sub>O</sub>	Signal output voltage		(–V <sub>S</sub> ) – 0.5	(+V <sub>S</sub> ) + 0.5	V
I <sub>S</sub>	Output short-circuit <sup>(2)</sup>		Continuous		
T <sub>A</sub>	Operating temperature <sup>(3)</sup>		–40	125	°C
T <sub>J</sub>	Junction temperature <sup>(3)</sup>		–40	175	°C
T <sub>stg</sub>	Storage temperature		–65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) Short-circuit to V<sub>S</sub> / 2.
- (3) As a result of the quiescent current, the supply voltage and load-dependent self-heating of the device must be considered.

### 7.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±750	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			MIN	MAX	UNIT
V <sub>S</sub>	Supply voltage	Single supply, V <sub>S</sub> = (+V <sub>S</sub> )	8	36	V
		Dual supply, V <sub>S</sub> = (+V <sub>S</sub> ) – (–V <sub>S</sub> )	±4	±18	
T <sub>A</sub>	Specified temperature		–40	125	°C

## 7.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		INA849	INA849	UNIT
		D (SOIC)	DGK (VSSOP)	
		8 PINS	8 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	119.6	168.7	°C/W
$R_{\theta JC(\text{top})}$	Junction-to-case (top) thermal resistance	66.3	61.4	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	61.9	90.0	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	20.5	8.4	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	61.4	88.4	°C/W
$R_{\theta JC(\text{bot})}$	Junction-to-case (bottom) thermal resistance	N/A	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics application report](#).

## 7.5 Electrical Characteristics

at  $T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15 \text{ V}$ ,  $R_L = 10 \text{ k}\Omega$ , connected to ground,  $V_{\text{REF}} = 0 \text{ V}$ ,  $V_{\text{CM}} = 0 \text{ V}$ , and  $G = 1$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>INPUT</b>						
$V_{\text{OSI}}$	Input stage offset voltage <sup>(1) (3)</sup>	$T_A = -40^\circ\text{C} \text{ to } +125^\circ\text{C}$ <sup>(2)</sup>	10	35	μV	
				75		
$V_{\text{OSO}}$	Output stage offset voltage <sup>(1) (3)</sup>	$T_A = -40^\circ\text{C} \text{ to } +125^\circ\text{C}$ <sup>(2)</sup>	0.1	0.4	μV/°C	
			50	500		
$V_{\text{CM}}$	Output stage offset voltage drift	$T_A = -40^\circ\text{C} \text{ to } +125^\circ\text{C}$ <sup>(2)</sup>		2000	μV	
			15	15		
PSRR	Power-supply rejection ratio	$G = 1$ , RTI	106	120	dB	
		$G = 10$ , RTI	114	120		
		$G = 100$ , RTI	121	126		
		$G = 1000$ , RTI	123	128		
$Z_{\text{in}}$	Input impedance		1    7		$\text{G}\Omega \parallel \text{pF}$	
	RFI filter, -3-dB frequency		220		MHz	
$V_{\text{CM}}$	Operating input range <sup>(4)</sup>	$(-V_S) + 2.5$	$(+V_S) - 2.5$		V	
		$V_S = \pm 4 \text{ V} \text{ to } \pm 18 \text{ V}$	See <a href="#">Figure 8-2</a> and <a href="#">Figure 8-3</a>			
CMRR	Common-mode rejection ratio	At dc to 60 Hz, RTI, $V_{\text{CM}} = (V-) + 2.5 \text{ V} \text{ to } (V+) - 2.5 \text{ V}$ , $G = 1$	92	110	dB	
		At dc to 60 Hz, RTI, $V_{\text{CM}} = (V-) + 2.5 \text{ V} \text{ to } (V+) - 2.5 \text{ V}$ , $G = 10$	112	125		
		At dc to 60 Hz, RTI, $V_{\text{CM}} = (V-) + 2.5 \text{ V} \text{ to } (V+) - 2.5 \text{ V}$ , $G = 100$	120	127		
		At dc to 60 Hz, RTI, $V_{\text{CM}} = (V-) + 2.5 \text{ V} \text{ to } (V+) - 2.5 \text{ V}$ , $G = 1000$	120	127		
<b>BIAS CURRENT</b>						
$I_B$	Input bias current	$V_{\text{CM}} = V_S / 2$		20	nA	
	Input bias current drift	$T_A = -40^\circ\text{C} \text{ to } +125^\circ\text{C}$	10	80	$\text{pA}/^\circ\text{C}$	
$I_{\text{os}}$	Input offset current	$V_{\text{CM}} = V_S / 2$		6	nA	
	Input offset current drift	$T_A = -40^\circ\text{C} \text{ to } +125^\circ\text{C}$	5		$\text{pA}/^\circ\text{C}$	

## 7.5 Electrical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15 \text{ V}$ ,  $R_L = 10 \text{ k}\Omega$ , connected to ground,  $V_{\text{REF}} = 0 \text{ V}$ ,  $V_{\text{CM}} = 0 \text{ V}$ , and  $G = 1$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>NOISE VOLTAGE</b>					
$e_{\text{NI}}$	Input stage voltage noise <sup>(8)</sup>	$f = 1 \text{ kHz}$ , $G = 1000$ , $R_S = 0 \Omega$	1		$\text{nV}/\sqrt{\text{Hz}}$
		$f_B = 0.1 \text{ Hz to } 10 \text{ Hz}$ , $G = 1000$ , $R_S = 0 \Omega$	0.06		$\mu\text{V}_{\text{PP}}$
$e_{\text{NO}}$	Output stage voltage noise <sup>(8)</sup>	$f = 1 \text{ kHz}$ , $R_S = 0 \Omega$	45		$\text{nV}/\sqrt{\text{Hz}}$
		$f_B = 0.1 \text{ Hz to } 10 \text{ Hz}$ , $R_S = 0 \Omega$	5		$\mu\text{V}_{\text{PP}}$
$i_N$	Current noise	$f = 1 \text{ kHz}$ <sup>(9)</sup>	1.1		$\text{pA}/\sqrt{\text{Hz}}$
		$f_B = 0.1 \text{ Hz to } 10 \text{ Hz}$	100		$\text{pA}_{\text{PP}}$
<b>GAIN</b>					
G	Gain equation		$1 + (6 \text{ k}\Omega / R_G)$		V/V
	Gain		1	10000	V/V
GE	Gain error <sup>(7)</sup>	$G = 1$ , $V_O = \pm 10 \text{ V}$	$\pm 0.005$	$\pm 0.025$	%
		$G = 10$ , $V_O = \pm 10 \text{ V}$	$\pm 0.025$	$\pm 0.1$	
		$G = 100$ , $V_O = \pm 10 \text{ V}$	$\pm 0.025$	$\pm 0.1$	
		$G = 1000$ , $V_O = \pm 10 \text{ V}$	$\pm 0.05$		
	Gain error drift <sup>(5)</sup>	$G = 1$ , $T_A = -40^\circ\text{C to } +125^\circ\text{C}$		$\pm 5$	$\text{ppm}/^\circ\text{C}$
		$G > 1$ , $T_A = -40^\circ\text{C to } +125^\circ\text{C}$		$\pm 35$	
	Gain nonlinearity	$G = 1$ , $V_O = -10 \text{ V to } +10 \text{ V}$	3		ppm
		$G = 10^{(6)}$ , $V_O = -10 \text{ V to } +10 \text{ V}$	10		
THD	Total harmonic distortion	$f = 1 \text{ kHz}$ , $V_O = 10 \text{ V}_{\text{PP}}$	127		dBc
HD2	Second-order harmonic distortion	$f = 1 \text{ kHz}$ , $V_O = 10 \text{ V}_{\text{PP}}$	127		dBc
HD3	Third-order harmonic distortion	$f = 1 \text{ kHz}$ , $V_O = 10 \text{ V}_{\text{PP}}$	157		dBc
THD	Total harmonic distortion	$f = 10 \text{ kHz}$ , $V_O = 10 \text{ V}_{\text{PP}}$	119		dBc
HD2	Second-order harmonic distortion	$f = 10 \text{ kHz}$ , $V_O = 10 \text{ V}_{\text{PP}}$	130		dBc
HD3	Third-order harmonic distortion	$f = 10 \text{ kHz}$ , $V_O = 10 \text{ V}_{\text{PP}}$	120		dBc
<b>OUTPUT</b>					
	Voltage swing	$R_L = 10 \text{ k}\Omega$	$(V-) + 0.15$	$(V+) - 0.15$	V
	Load capacitance stability		200		pF
$Z_O$	Closed-loop output impedance	$f = 1 \text{ MHz}$	1.5		$\Omega$
$I_{\text{sc}}$	Short-circuit current	Continuous to $V_S / 2$	$\pm 34$		mA
<b>FREQUENCY RESPONSE</b>					
BW	Bandwidth, $-3 \text{ dB}$	$G = 1$	28		MHz
		$G = 10$	13		
		$G = 100$	8		
		$G = 1000$	1.25		
SR	Slew rate	$G = 1$ , $V_{\text{STEP}} = 10 \text{ V}$	35		$\text{V}/\mu\text{s}$
ts	Settling time	0.01%, $G = 1$ to 100, $V_{\text{STEP}} = 10 \text{ V}$	0.4		$\mu\text{s}$
		0.01%, $G = 1000$ , $V_{\text{STEP}} = 10 \text{ V}$	0.4		
		0.001%, $G = 1$ to 100, $V_{\text{STEP}} = 10 \text{ V}$	0.6		
		0.001%, $G = 1000$ , $V_{\text{STEP}} = 10 \text{ V}$	1.5		

## 7.5 Electrical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15 \text{ V}$ ,  $R_L = 10 \text{ k}\Omega$ , connected to ground,  $V_{\text{REF}} = 0 \text{ V}$ ,  $V_{\text{CM}} = 0 \text{ V}$ , and  $G = 1$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>REFERENCE INPUT</b>						
$R_{\text{IN}}$	Input impedance			10		$\text{k}\Omega$
	Input current			80		$\mu\text{A}$
	Reference input voltage		(V $-$ )		(V $+$ )	V
	Gain to output			1		V/V
	Reference gain error	$V_O = \pm 10 \text{ V}$ , inside the voltage swing range		0.01	0.05	%
<b>POWER SUPPLY</b>						
$I_Q$	Quiescent current <sup>(7)</sup>	$V_{\text{IN}} = 0 \text{ V}$ $T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		6.2	6.6	mA
					8.9	

- (1) Total offset, referred-to-input (RTI):  $V_{\text{OSI}} = (V_{\text{OSI}}) + (V_{\text{OSO}} / G)$ .
- (2) Specified by characterization. Not tested in production.
- (3) Offset drifts are uncorrelated. Input-referred offset drift is calculated using:  $\Delta V_{\text{OS(RTI)}} = \sqrt{[\Delta V_{\text{OSI}}^2 + (\Delta V_{\text{OSO}} / G)^2]}$ .
- (4) Input voltage range of the input stage. The input range depends on the common-mode voltage, differential voltage, gain, and reference voltage; see [Figure 7-12](#).
- (5) The values specified for  $G > 1$  do not include the effects of the external gain resistor,  $R_G$ .
- (6) Thermal effects can degrade input stage nonlinearity and thus can scale with gain; See [Figure 9-5](#).
- (7) This parameter is tested in a high speed automatic test environment and does not measure the thermal effects with a longer a time constant. The thermal effect depends on supply voltage, layout, heat sinking and air flow conditions.
- (8) Total RTI voltage noise is equal to:  $e_{\text{N(RTI)}} = \sqrt{[e_{\text{NI}}^2 + (e_{\text{NO}} / G)^2]}$ .
- (9) Input current noise density specified for unbalanced input impedance. Bias current cancellation improves noise performance for balanced systems; See [Figure 7-25](#).

## 7.6 Typical Characteristics

at  $T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{CM}$  at mid-supply,  $VR_L = 10\text{ k}\Omega$ , connected to ground,  $V_{REF} = 0\text{ V}$ , and  $G = 1$  (unless otherwise noted)

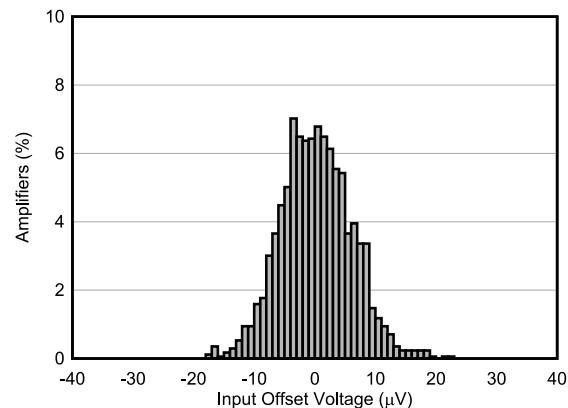


Figure 7-1. Typical Distribution of Input Offset Voltage

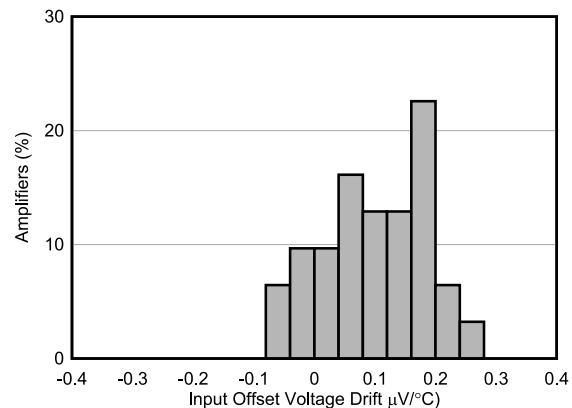


Figure 7-2. Typical Distribution of Input Offset Voltage Drift

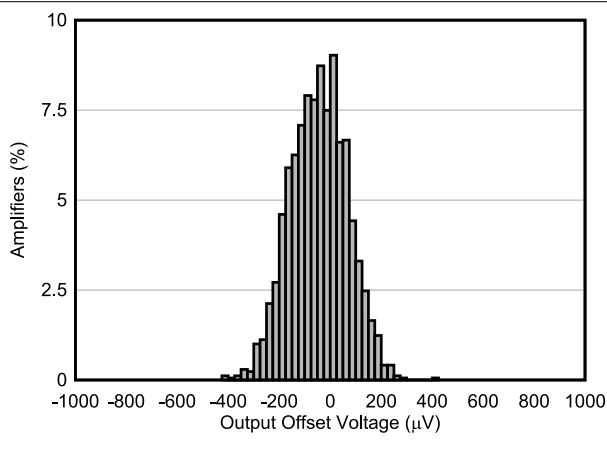


Figure 7-3. Typical Distribution of Output Offset Voltage

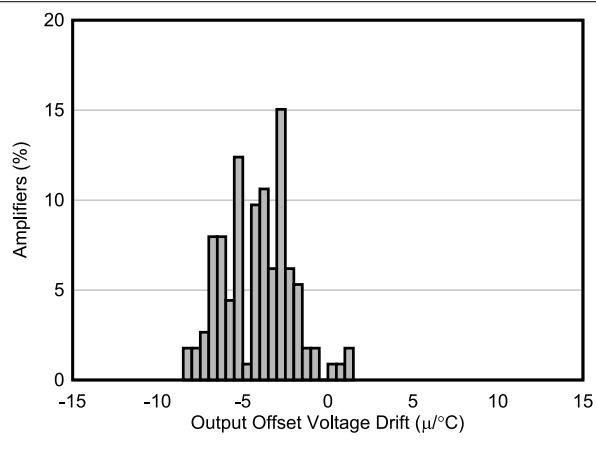


Figure 7-4. Typical Distribution of Output Offset Voltage Drift

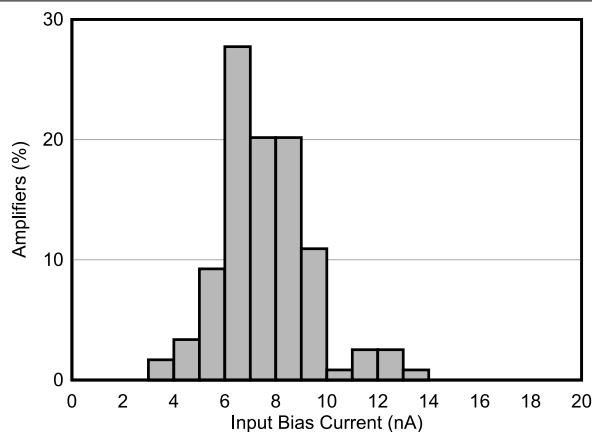


Figure 7-5. Typical Distribution of Input Bias Current

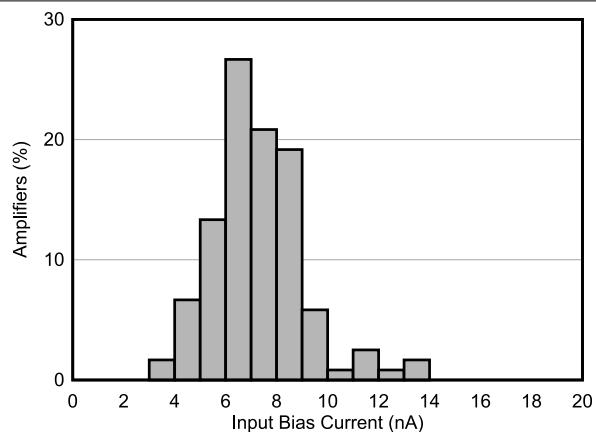


Figure 7-6. Typical Distribution of Input Bias Current at  $85^\circ\text{C}$

## 7.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{CM}$  at mid-supply,  $VR_L = 10\text{ k}\Omega$ , connected to ground,  $V_{REF} = 0\text{ V}$ , and  $G = 1$  (unless otherwise noted)

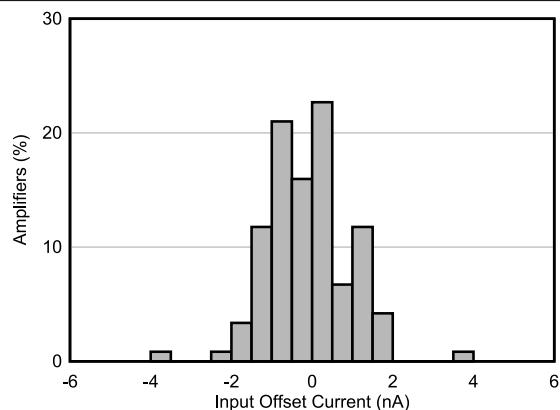


Figure 7-7. Typical Distribution of Input Offset Current

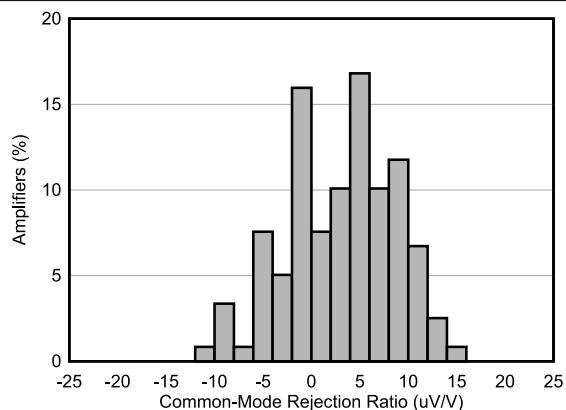


Figure 7-8. Typical CMRR Distribution  $G = 1$

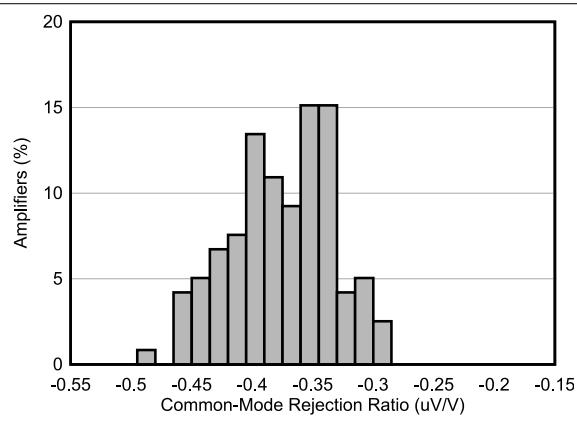


Figure 7-9. Typical CMRR Distribution  $G = 100$

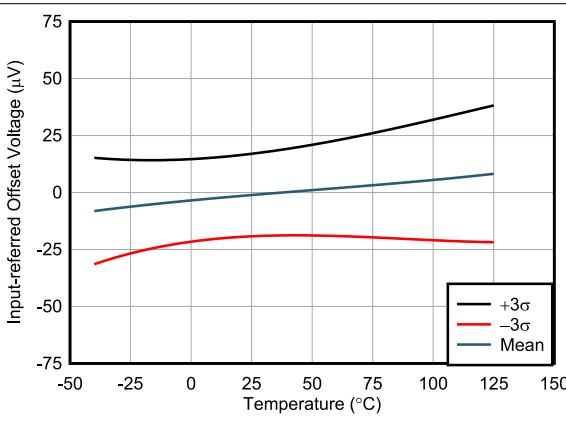


Figure 7-10. Input Stage Offset Voltage vs Temperature

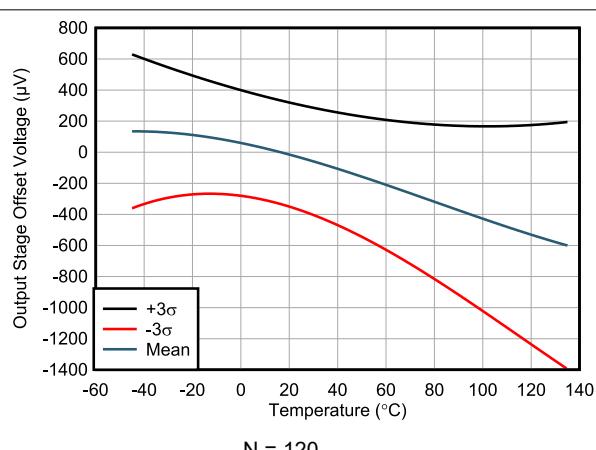


Figure 7-11. Output Stage Offset Voltage vs Temperature

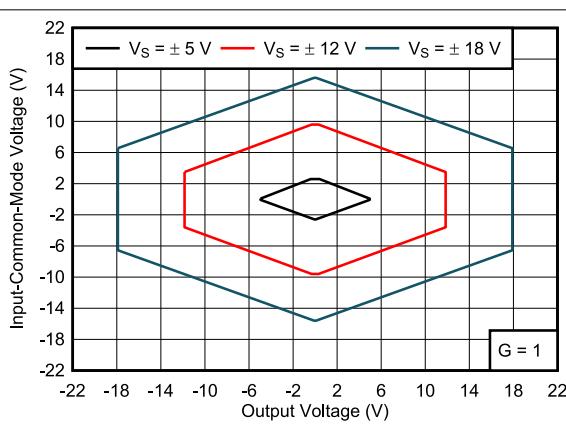
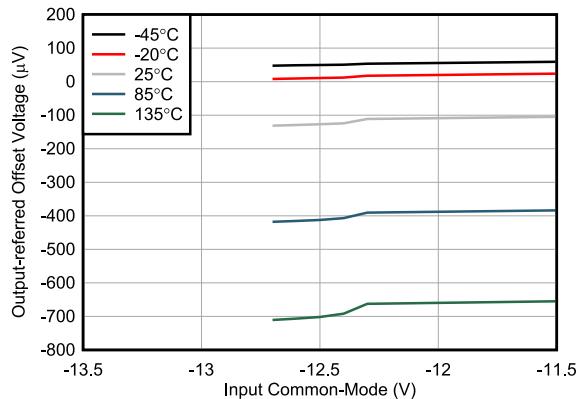


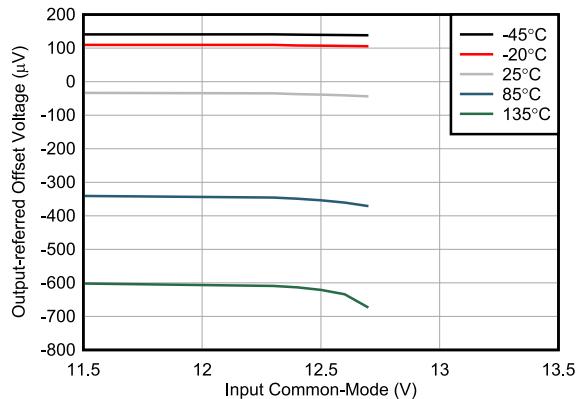
Figure 7-12. Boundary Plot - Input Common-Mode Voltage vs Output Voltage

## 7.6 Typical Characteristics (continued)

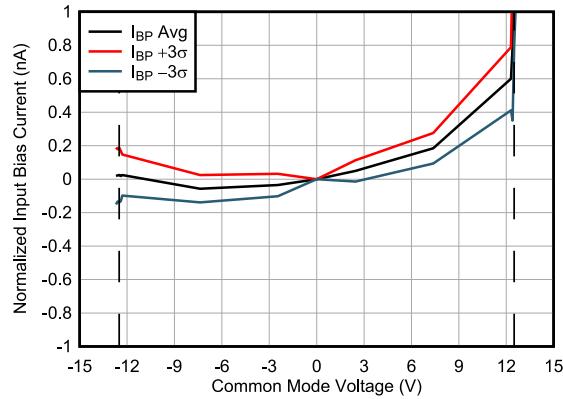
at  $T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{CM}$  at mid-supply,  $V_{RL} = 10\text{ k}\Omega$ , connected to ground,  $V_{REF} = 0\text{ V}$ , and  $G = 1$  (unless otherwise noted)



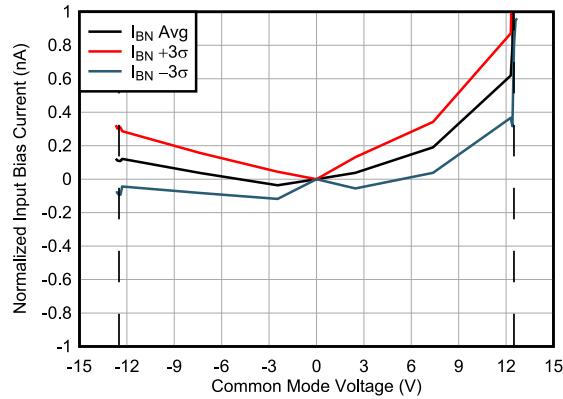
**Figure 7-13. Output-referred Offset Voltage vs Negative Input Common-Mode Voltage**



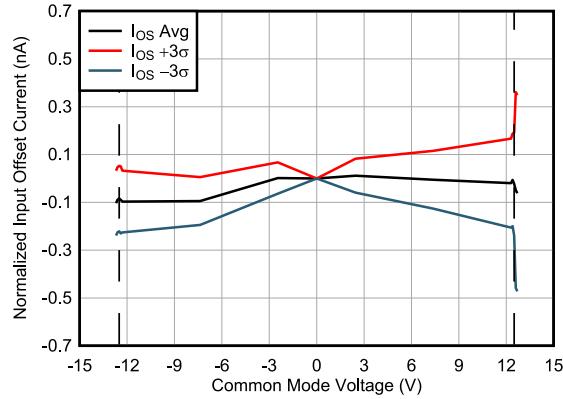
**Figure 7-14. Output-referred Offset Voltage vs Positive Input Common-Mode Voltage**



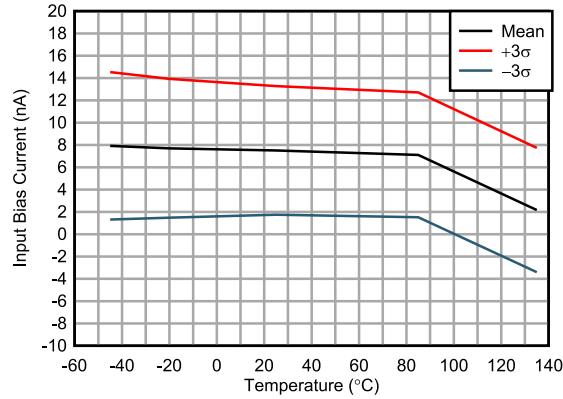
**Figure 7-15. Positive Input Bias Current vs Input Common-Mode Voltage**



**Figure 7-16. Negative Input Bias Current vs Input Common-Mode Voltage**



**Figure 7-17. Input Offset Current vs Input Common-Mode Voltage**



**Figure 7-18. Input Bias Current vs Temperature**

## 7.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{CM}$  at mid-supply,  $VR_L = 10\text{ k}\Omega$ , connected to ground,  $V_{REF} = 0\text{ V}$ , and  $G = 1$  (unless otherwise noted)

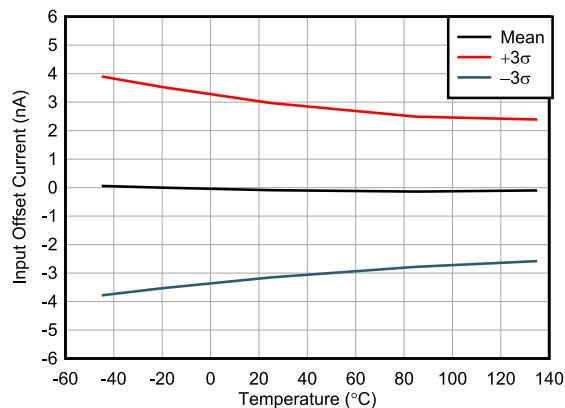


Figure 7-19. Input Offset Current vs Temperature

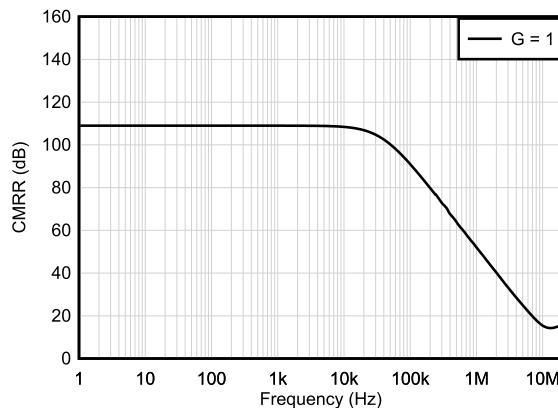


Figure 7-20. CMRR vs Frequency (RTI)

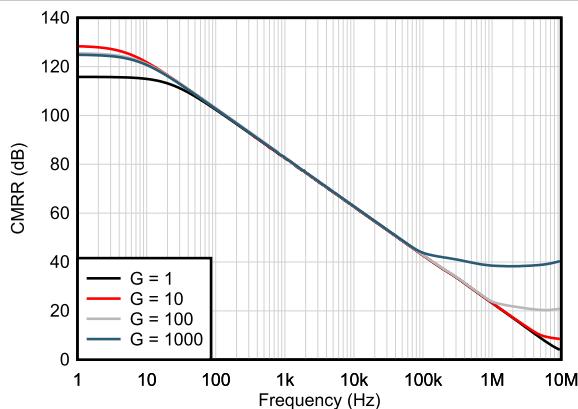


Figure 7-21. CMRR vs Frequency (1-kΩ source imbalance)

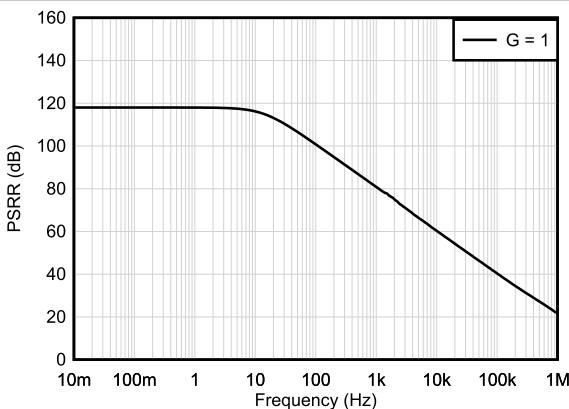


Figure 7-22. Positive PSRR vs Frequency (RTI)

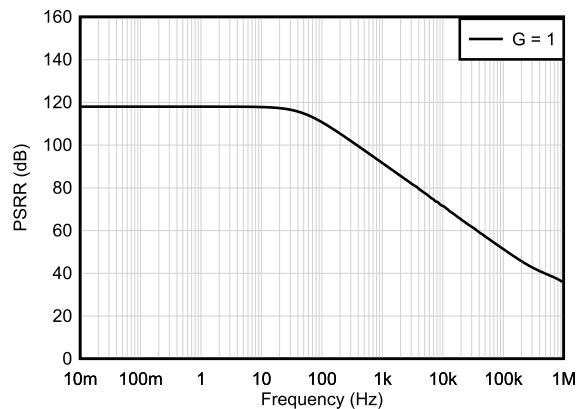


Figure 7-23. Negative PSRR vs Frequency (RTI)

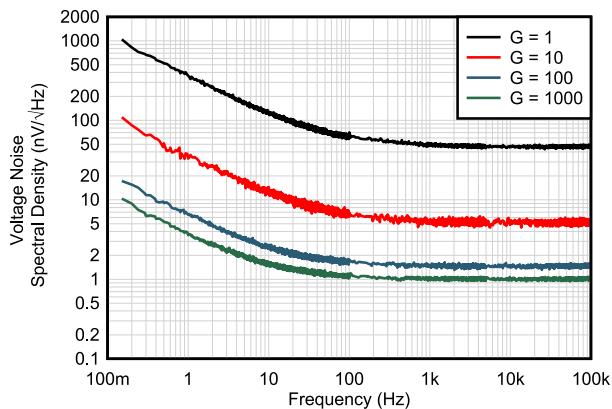


Figure 7-24. Voltage Noise Spectral Density vs Frequency (RTI)

## 7.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{CM}$  at mid-supply,  $VR_L = 10\text{ k}\Omega$ , connected to ground,  $V_{REF} = 0\text{ V}$ , and  $G = 1$  (unless otherwise noted)

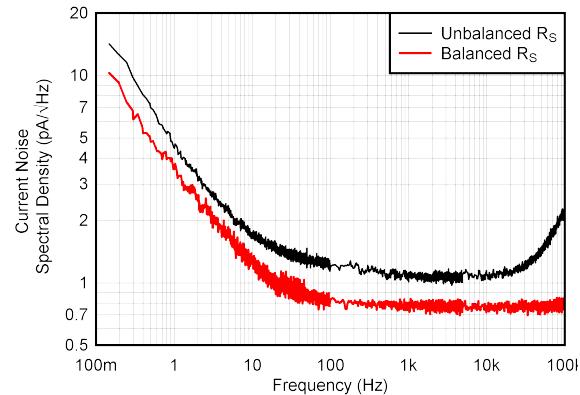


Figure 7-25. Current Noise Spectral Density vs Frequency (RTI)

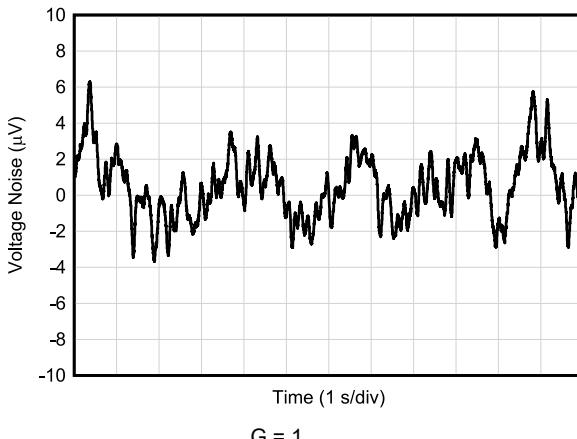


Figure 7-26. 0.1-Hz to 10-Hz RTI Voltage Noise

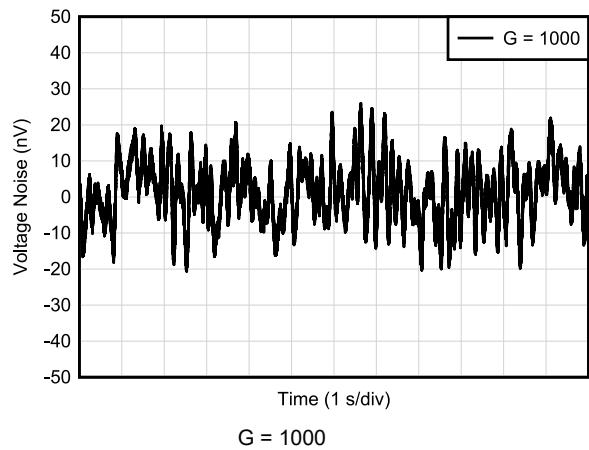


Figure 7-27. 0.1-Hz to 10-Hz RTI Voltage Noise

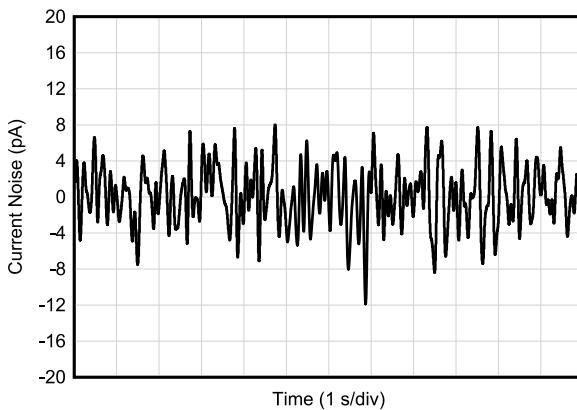


Figure 7-28. 0.1-Hz to 10-Hz RTI Current Noise

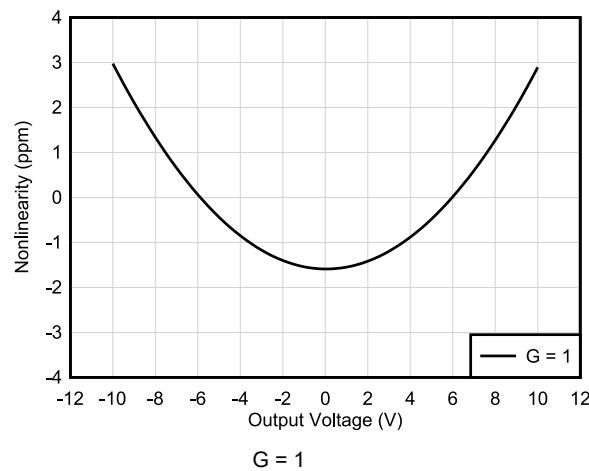


Figure 7-29. Gain Nonlinearity vs Output Voltage

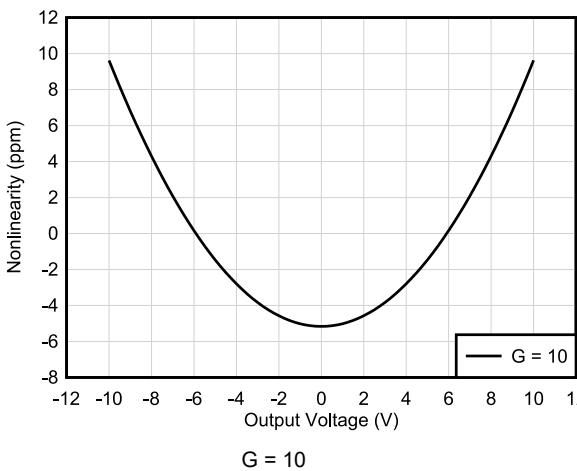


Figure 7-30. Gain Nonlinearity vs Output Voltage

## 7.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{CM}$  at mid-supply,  $VR_L = 10\text{ k}\Omega$ , connected to ground,  $V_{REF} = 0\text{ V}$ , and  $G = 1$  (unless otherwise noted)

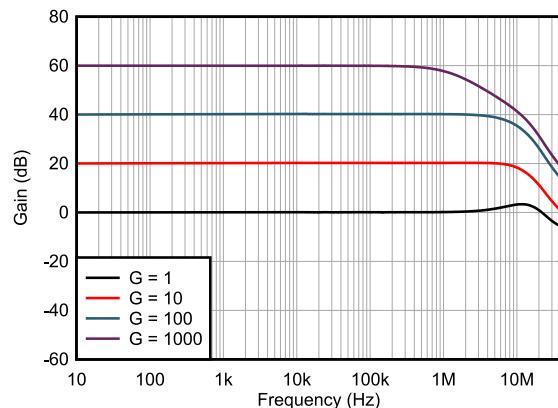


Figure 7-31. Closed-Loop Gain vs Frequency

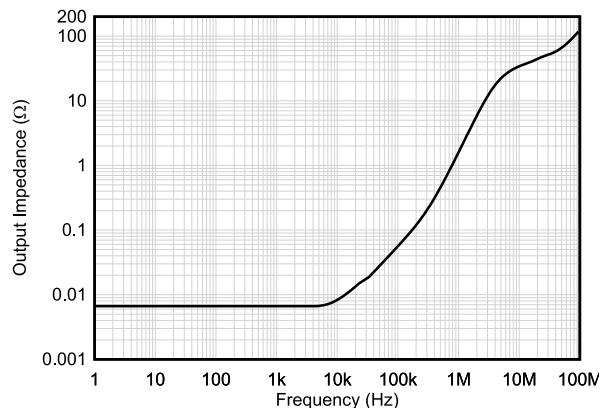


Figure 7-32. Closed-Loop Output Impedance vs Frequency

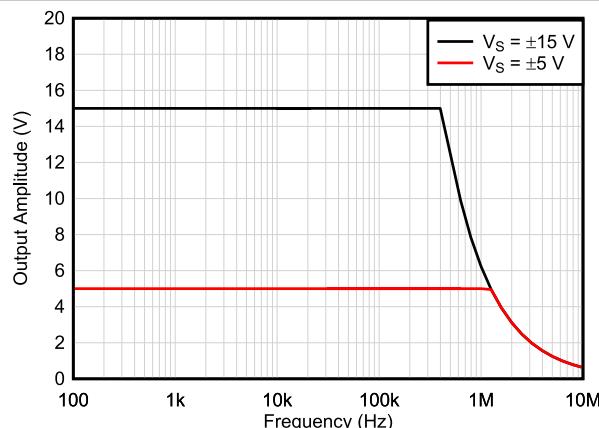


Figure 7-33. Large-Signal Frequency Response

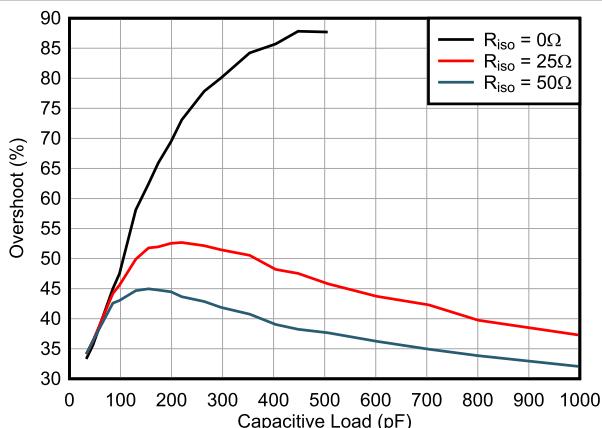
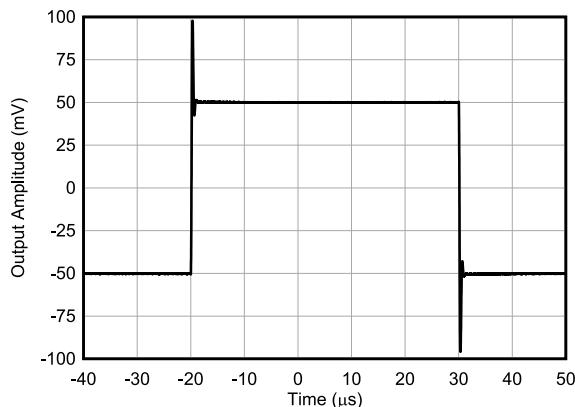
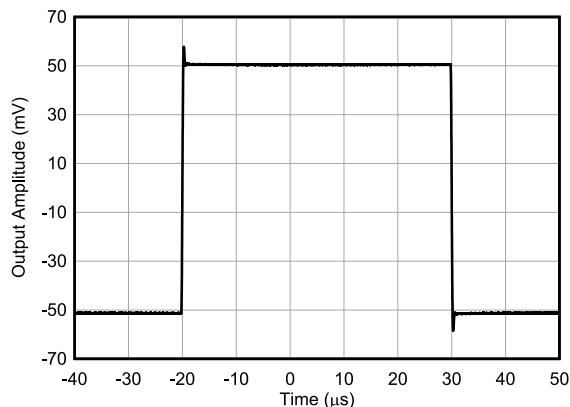


Figure 7-34. Overshoot vs Capacitive Loads



$G = 1, C_L = 100\text{ pF}$

Figure 7-35. Small-Signal Step Response at  $G = 1$



$G = 10, C_L = 100\text{ pF}$

Figure 7-36. Small-Signal Step Response at  $G = 10$

## 7.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{CM}$  at mid-supply,  $VR_L = 10\text{ k}\Omega$ , connected to ground,  $V_{REF} = 0\text{ V}$ , and  $G = 1$  (unless otherwise noted)

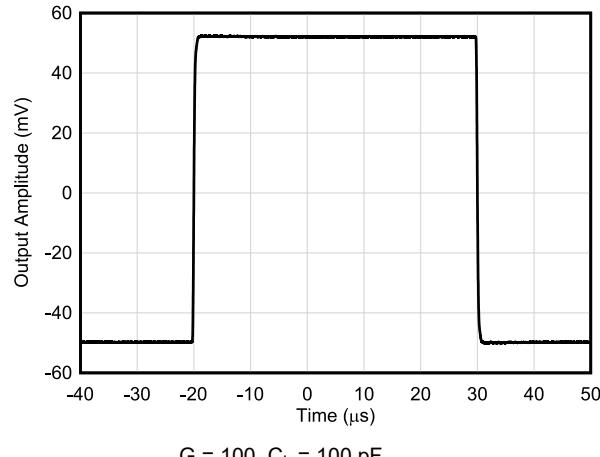


Figure 7-37. Small-Signal Step Response at  $G = 100$

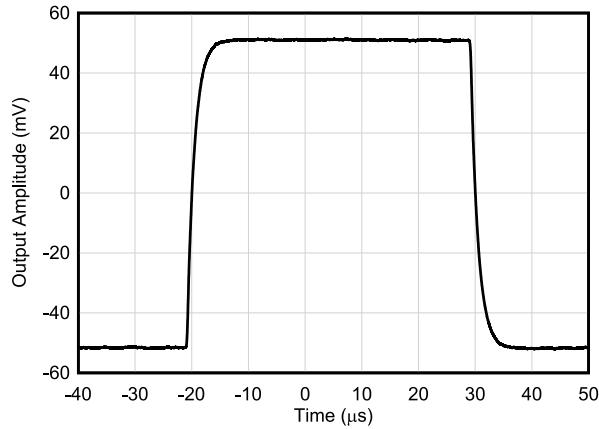


Figure 7-38. Small-Signal Step Response at  $G = 1000$

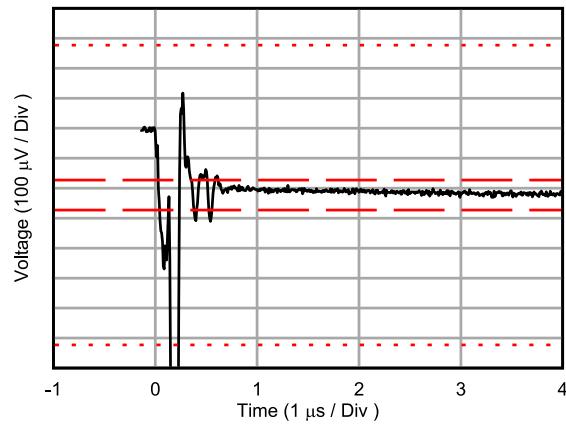


Figure 7-39. Settling Time for  $G = 1$

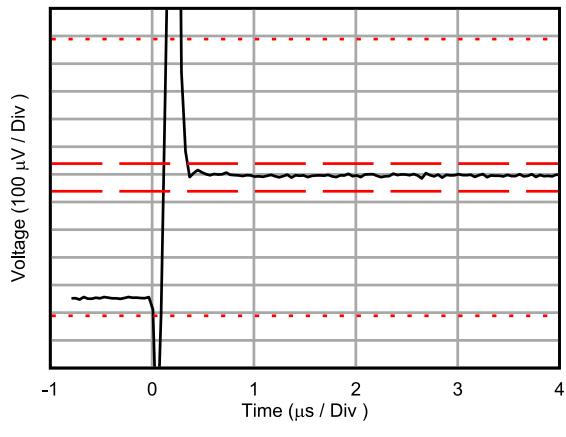


Figure 7-40. Settling Time for  $G = 100$

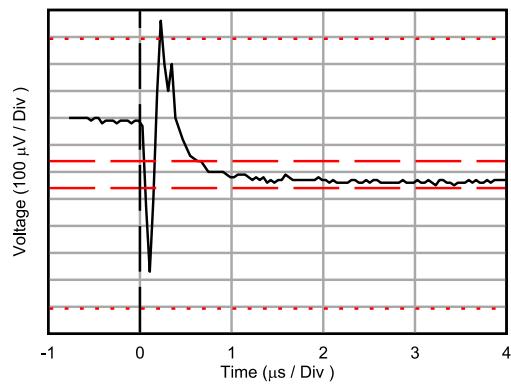


Figure 7-41. Settling Time for  $G = 1000$

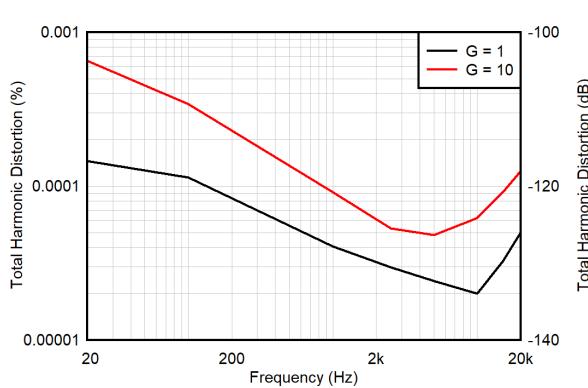


Figure 7-42. Total Harmonic Distortion vs Frequency

## 7.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{CM}$  at mid-supply,  $VR_L = 10\text{ k}\Omega$ , connected to ground,  $V_{REF} = 0\text{ V}$ , and  $G = 1$  (unless otherwise noted)

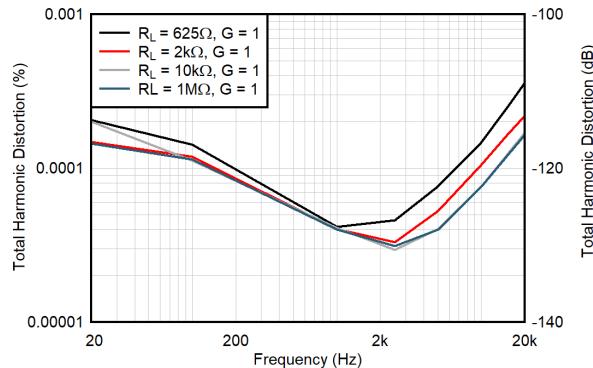


Figure 7-43. Total Harmonic Distortion vs Frequency at Different Loads

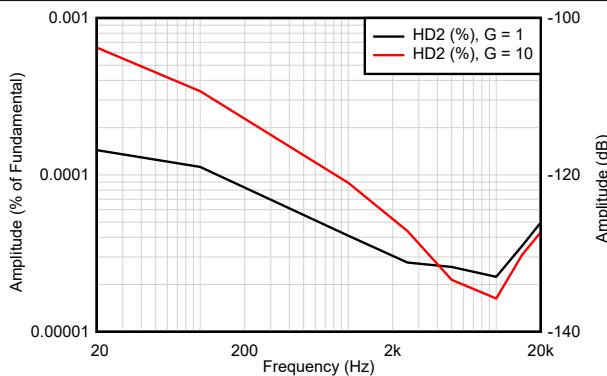


Figure 7-44. Second Harmonic Distortion vs Frequency

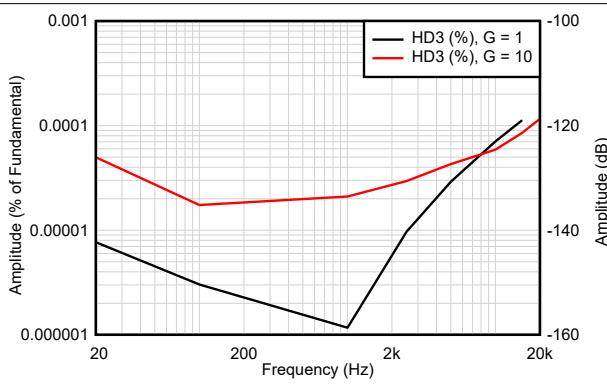


Figure 7-45. Third Harmonic Distortion vs Frequency

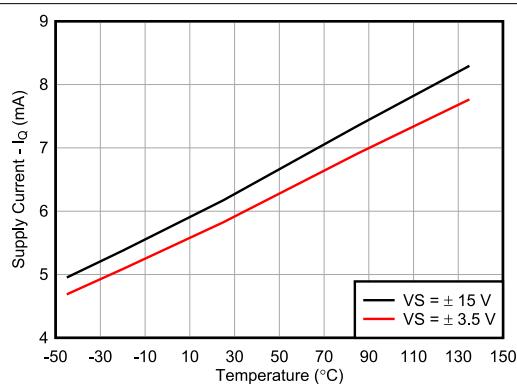


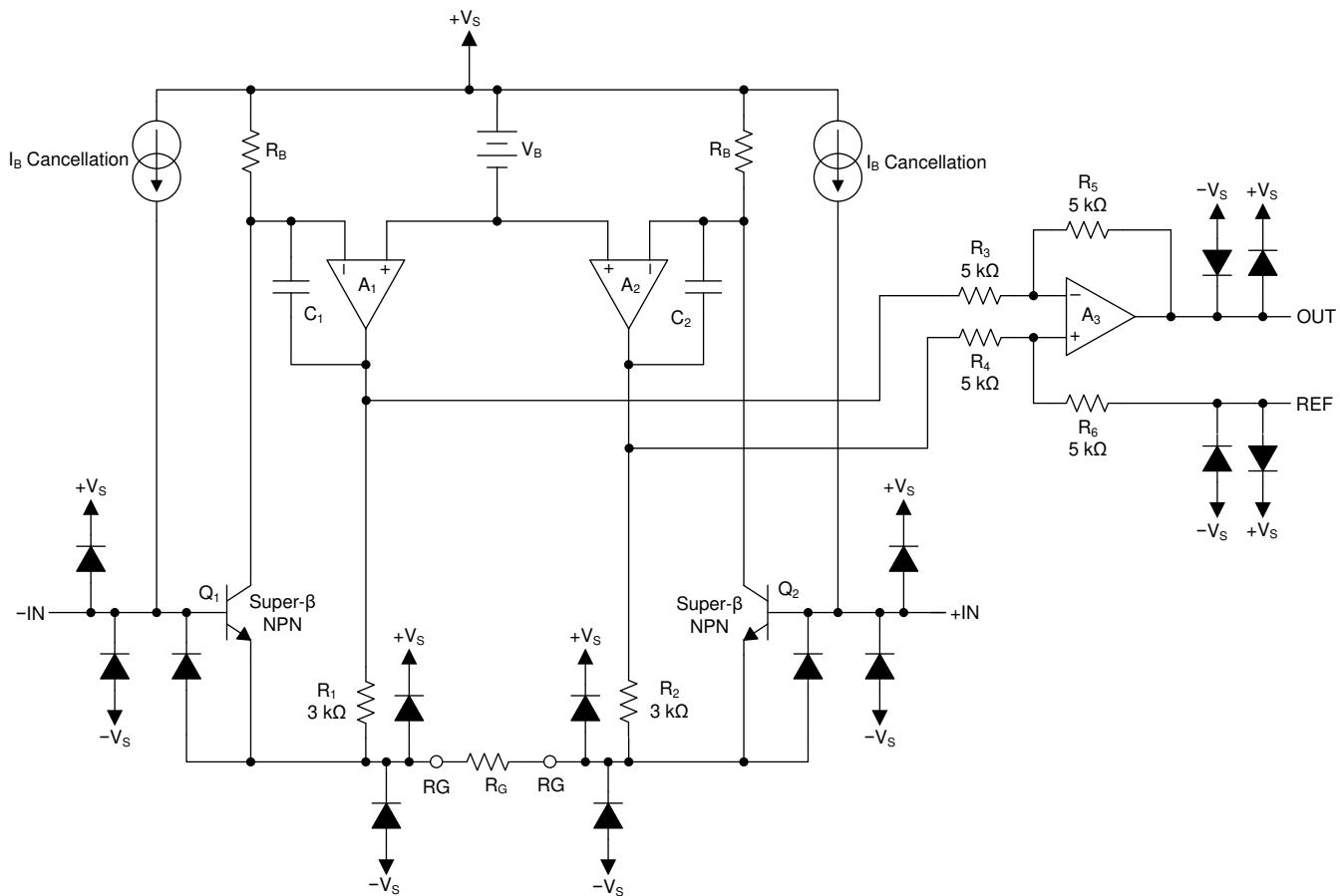
Figure 7-46. Supply Current vs Temperature

## 8 Detailed Description

## 8.1 Overview

The INA849 is a monolithic, precision, instrumentation amplifier that incorporates a current-feedback input stage and a four-resistor difference amplifier output stage. The functional block diagram in the next section shows how the differential input voltage is buffered by  $Q_1$  and  $Q_2$ , and is forced across  $R_G$ , which causes a signal current to flow through  $R_G$ ,  $R_1$ , and  $R_2$ . The output difference amplifier,  $A_3$ , removes the common-mode component of the input signal and refers the output signal to the REF pin. The  $V_{BE}$  and voltage drop across  $R_1$  and  $R_2$  produce output voltages on  $A_1$  and  $A_2$  that are approximately 0.8 V lower than the input voltages.

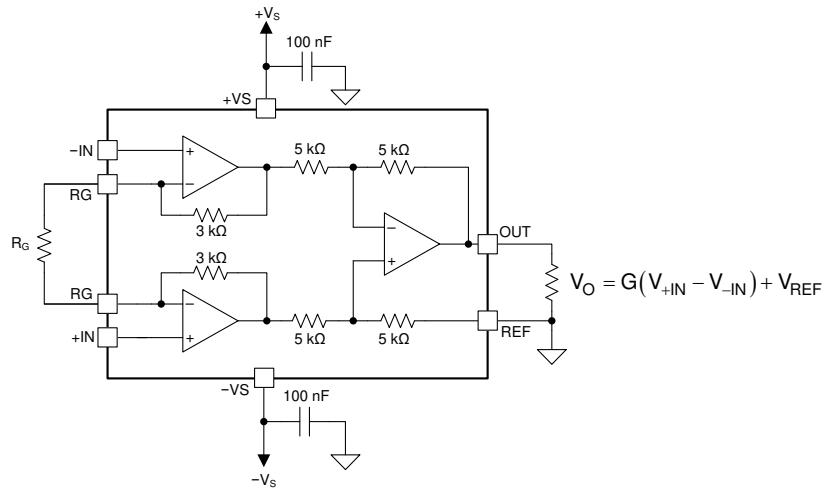
## 8.2 Functional Block Diagram



## 8.3 Feature Description

### 8.3.1 Adjustable Gain Setting

Figure 8-1 shows that the gain of the INA849 is set by a single external resistor ( $R_G$ ) connected between the RG pins (pins 2 and 3).



**Figure 8-1. Simplified Diagram of the INA849 with Output Equation**

The value of  $R_G$  is selected according to the following equation:

$$G = 1 + \frac{6 \text{ k}\Omega}{R_G} \quad (1)$$

Table 8-1 lists several commonly used gains and resistor values. The 6-kΩ term in Equation 1 is a result of the sum of the two internal 3-kΩ feedback resistors. These on-chip resistors are laser-trimmed to accurate, absolute values. The accuracy and temperature coefficients of these resistors are included in the gain accuracy and drift specifications of the INA849.

**Table 8-1. Commonly Used Gains and Resistor Values**

DESIRED GAIN (V/V)	STANDARD 1% $R_G$ (Ω)	CALCULATED GAIN (V/V)	CALCULATED GAIN ERROR (%)
1	Not connected	N/A	N/A
2	6.04 k	1.9933	0.33
5	1.50 k	5	0
10	665	10.022	-0.23
20	316	19.987	0.06
50	121	50.586	-1.17
100	60.4	100.337	-0.34
200	30.1	200.335	-0.17
500	12.1	496.867	0.63
1000	6.04	994.377	0.56

The 5-kΩ feedback resistors in the output stage are ratiometrically matched to achieve unity-gain stability. These resistors may shift up to 15% depending on production.

As shown in Figure 8-1 and explained in more detail in Figure 11-1, make sure to connect low-ESR, 0.1-μF, ceramic bypass capacitors between each supply pin and ground, placed as close to the device as possible.

### 8.3.2 Gain Drift

The stability and temperature drift of external gain setting resistor  $R_G$  also affects gain. The contribution of  $R_G$  to gain accuracy and drift is determined from [Equation 1](#).

The best gain drift of 5 ppm/ $^{\circ}\text{C}$  (maximum) is achieved when the INA849 uses  $G = 1$  without  $R_G$  connected. In this case, gain drift is limited by the mismatch of the temperature coefficient of the integrated 5-k $\Omega$  resistors in differential amplifier  $A_3$ . At gains greater than 1, gain drift increases as a result of the individual drift of the 3-k $\Omega$  resistors in the feedback of  $A_1$  and  $A_2$ , relative to the drift of external gain resistor  $R_G$ .

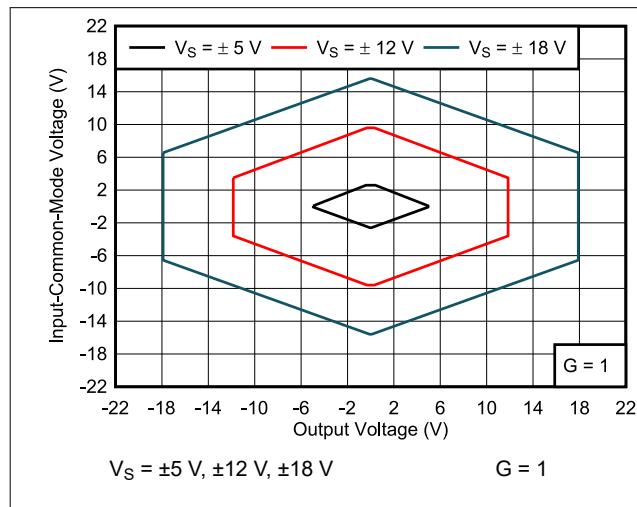
The low temperature coefficient of the internal feedback resistors improves the overall temperature stability of applications using gains greater than 1 V/V over alternate solutions.

The low resistor values required for high gain make wiring resistance an important consideration. Sockets add to the wiring resistance and contribute additional gain error (such as a possible unstable gain error) at gains of approximately 100 or greater.

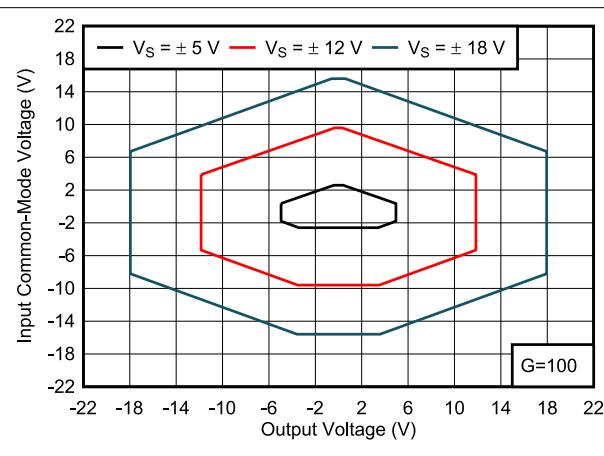
To maintain stability, avoid parasitic capacitance of more than a few picofarads at the  $R_G$  connections. Careful matching of any parasitics on the  $R_G$  pins maintains optimal CMRR over frequency.

### 8.3.3 Wide Input Common-Mode Range

The linear input voltage range of the INA849 input circuitry extends within 2.5 V (maximum) of both power supplies, and maintains excellent common-mode rejection throughout this range. The common-mode range for the most common operating conditions are shown in [Figure 8-2](#) and [Figure 8-3](#). The common-mode range for other operating conditions is best calculated using the [Common-Mode Input Range Calculator for Instrumentation Amplifiers](#).



**Figure 8-2. Input Common-Mode Voltage vs Output Voltage**



**Figure 8-3. Input Common-Mode Voltage vs Output Voltage**

## 8.4 Device Functional Modes

The INA849 has a single functional mode and is operational when the power-supply voltage is greater than 8 V ( $\pm 4$  V). The maximum power-supply voltage for the INA849 is 36 V ( $\pm 18$  V).

## 9 Application and Implementation

### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

### 9.1 Application Information

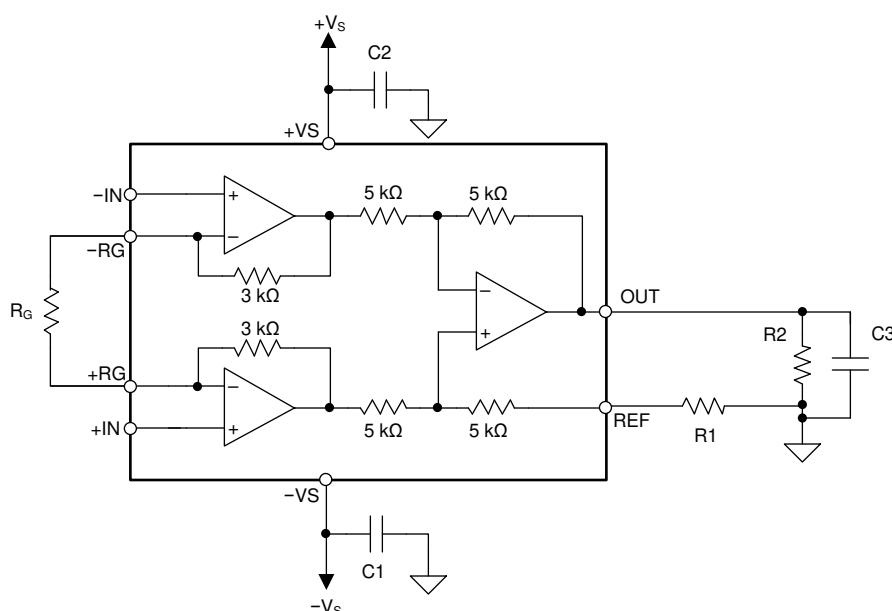
#### 9.1.1 Reference Pin

The output voltage of the INA849 is developed with respect to the voltage on reference pin REF.

Use the REF pin to offset the output signal to a precise midsupply level. Typically, this offset is 2.5 V in a 5-V supply environment. To accomplish this level shift, a voltage source must be connected to the REF pin to level-shift the output so that the INA849 drives a single-supply analog-to-digital converter (ADC).

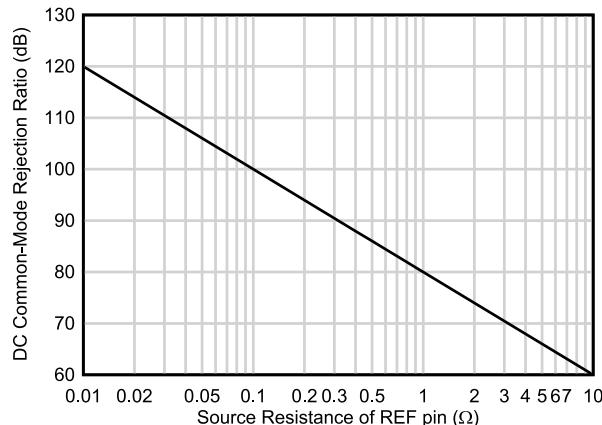
For dual-supply operation, the reference pin is typically connected to the low-impedance system ground.

The voltage source applied to the reference pin must have a low output impedance. As shown in [Figure 9-1](#), any resistance at the reference pin (shown as  $R_{REF}$ ) is in series with an internal 5-k $\Omega$  resistor that creates an imbalance in the four resistors of the internal difference amplifier.



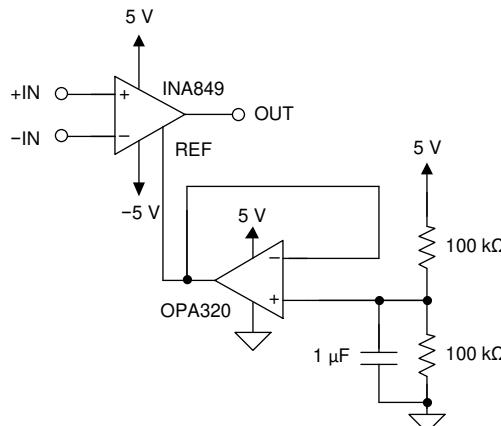
**Figure 9-1. Parasitic Resistance Shown at the Reference Pin**

This imbalance results in a degraded common-mode rejection ratio (CMRR). Figure 9-2 shows how the common-mode rejection ratio degrades depending on the source resistance on the reference pin. For best performance, keep the dc CMRR greater than 100 dB by keeping the source impedance to the REF pin (represented as R1) to less than 0.1  $\Omega$ .



**Figure 9-2. Effect of Parasitic Resistance at the Reference Pin**

Voltage-reference devices are an excellent option for providing a low-impedance voltage source for the reference pin. However, if a resistor voltage divider generates a reference voltage, the divider must be buffered by an op amp (as Figure 9-3 shows) to avoid CMRR degradation.

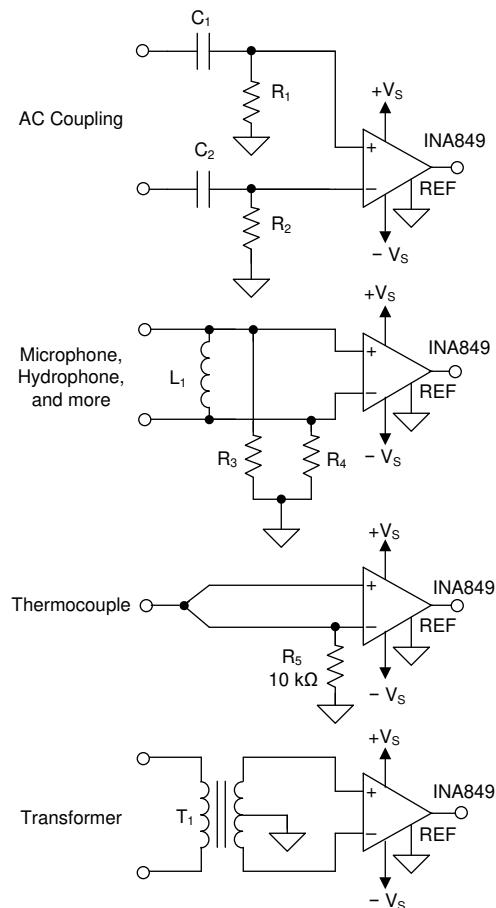


**Figure 9-3. Using an Op Amp to Buffer Reference Voltages**

### 9.1.2 Input Bias Current Return Path

The input impedance of the INA849 is extremely high (approximately  $100\text{ G}\Omega$ ). However, a path must be provided for the input bias current of both inputs. This input bias current is typically  $6\text{ nA}$ . High input impedance means that this input bias current changes little with varying input voltage.

Input circuitry must provide a path for this input bias current for proper operation. Figure 9-4 shows various provisions for an input bias current path. Without a bias current path, the inputs float to a potential that exceeds the common-mode range of the INA849, and the input amplifiers saturate. If the differential source resistance is low, the bias current return path connects to one input (as shown in the thermocouple example). With a higher source impedance, using two equal resistors provides a balanced input with possible advantages of a lower input offset voltage as a result of bias current, and better high-frequency common-mode rejection.



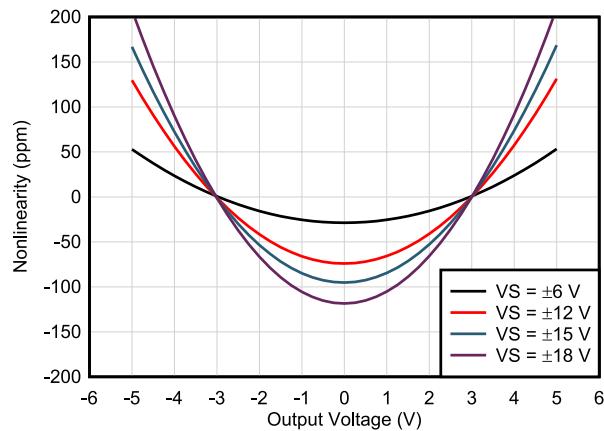
NOTE: Center tap in the transformer provides bias current return.

**Figure 9-4. Providing an Input Common-Mode Current Path**

### 9.1.3 Thermal Effects due to Power Dissipation

The INA849 dissipates approximately 200 mW of power under quiescent conditions at a  $\pm 15$ -V supply voltage. The internal resistor network and output load drive causes an additional power dissipation that depends on the input signal. The small silicon area of the INA849 causes the internal circuitry to experience temperature gradients that might adversely affect the electrical performance.

Precision parameters, such as offset voltage, linearity, common-mode rejection ratio, and total harmonic distortion, can be impacted as a result of these thermal effects in the silicon. The thermal gradient particularly affects the performance of low-frequency input signals with higher gains ( $> 10$ ) and large output voltage variation. As shown in the measurement [Figure 9-5](#), the thermal effect can be minimized by lowering the supply voltage, if the application permits.

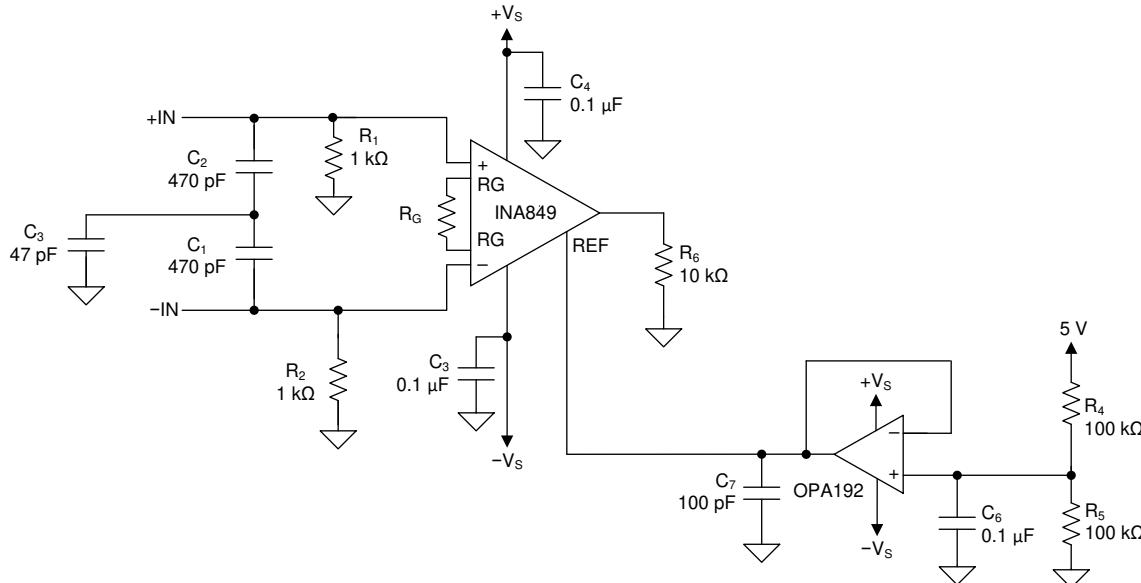


**Figure 9-5. Linearity vs Supply Voltage for  $G = 1000$**

## 9.2 Typical Application

### 9.2.1 Sensor Conditioning Circuit

Figure 9-6 shows a typical application for the INA849.



**Figure 9-6. Sensor Conditioning Circuit**

#### 9.2.1.1 Design Requirements

For the typical application, the design requirements are:

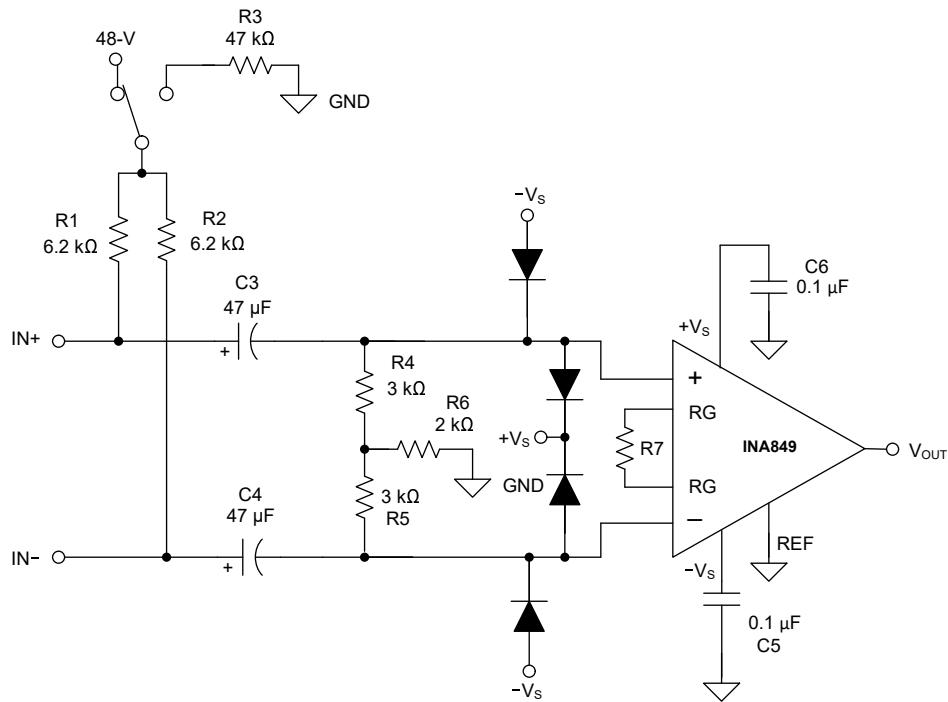
- Power-supply voltage of  $V_S = \pm 15$  V
- AC-coupled input signal
  - Capacitor tolerance of 5%
- Reference voltage buffered to  $V_{REF} = 2.5$  V
- Output range within 0 V to 5 V
- First-order filter stage with –3-dB frequency of 27 kHz

#### 9.2.1.2 Detailed Design Procedure

If the instrumentation amplifier is used to drive ac-coupled input signals, an input bias current path must be provided as described in Section 9.1.2, represented with resistors  $R_1$  and  $R_2$  in Figure 9-6. For the selection of the resistor value, a trade-off must be made between input current noise that increases at lower values and input voltage noise that increases at higher values.

Section 9.1.1 states that the reference pin must be connected to a low-impedance reference, as shown in the application circuit example of the [Sensor Conditioning Circuit](#). The reference pin must be connected to a 2.5-V reference voltage established through a high-resistive divider. The OPA192 helps to buffer the reference voltage. The effective output impedance of the OPA192 is derived as follows. The dc open-loop impedance of the OPA192 amplifier is approximately 3 kΩ. In a buffer configuration ( $A_V = 1$ ), the output impedance of an amplifier degrades by the open-loop voltage gain. The OPA192 specifies a typical  $A_{OL}$  of 126 dB, thereby resulting in an output impedance of  $R_{OUT} = 1.5$  mΩ.

### 9.2.2 Phantom Power in Microphone Preamplifier Circuit



**Figure 9-7. Phantom Power in Microphone Preamplifier Circuit**

Figure 9-7 shows a typical application circuit for a microphone input amplifier used to generate phantom power. Phantom power is a technique that provides power and the audio signal using the same signal path.

R1 and R2 connected to the 48-V supply define the current path in the case when the microphone must be powered. Therefore, C3 and C4 are used as blocking capacitors to protect the INA849. When the input connections are shorted in a fault scenario, a large surge current discharges the dc blocking capacitor through the Shottky diodes. For 48-V phantom power, the surge current exceeds 4 A for a short duration of time. Make sure to use Shottky diodes that are specified for at least a 10-A surge current. Additional series resistance with the dc blocking capacitor limits the surge current, but must be traded off because these add noise to the circuit.

One of the key criteria for high-performance microphones is to enable an optimum source impedance throughout the audible frequency range. The exceptional ultra-low noise performance of the INA849 permits direct input without the need for a transformer.

R4 and R5 in parallel with R1 and R2 provide the bias current path for the INA849. The input bias current (maximum of 20 nA) provides a dc differential input voltage that reflects as an voltage error on the output. Use the lowest possible value resistors to make sure that the thermal noise of these resistors does not dominate.

The mismatch of the input ac-coupling capacitors (C3 and C4) can reduce the common-mode rejection ratio significantly at low frequencies. An additional resistor (R6) connected to both of the bias resistors (R4 and R5) can mitigate this effect.

Use the [TINA TI™ simulation software](#) for a detailed analysis.

## 10 Power Supply Recommendations

The nominal performance of the INA849 is specified with a supply voltage of  $\pm 15$  V and midsupply reference voltage. The device also operates using power supplies from  $\pm 4$  V (8 V) to  $\pm 18$  V (36 V) and non-midsupply reference voltages with excellent performance. [Section 7.6](#) shows the parameters that can vary significantly with operating voltage and reference voltage.

## 11 Layout

### 11.1 Layout Guidelines

Use good PCB layout practices for best operational performance of the device, including:

- To avoid converting common-mode signals into differential signals and thermal electromotive forces (EMFs), make sure that both input paths are symmetrical and well-matched for source impedance and capacitance.
- Place the external gain resistor close to the RG pins to keep the loop inductance as low as possible and to avoid a potential parasitic coupling path, but also so that capacitance mismatch between the RG pins is minimized.
- Noise can propagate into analog circuitry through the power pins of the circuit as a whole and of the device. Bypass capacitors reduce the coupled noise by providing low-impedance power sources local to the analog circuitry.
  - Connect low-ESR, 0.1- $\mu$ F, ceramic bypass capacitors between each supply pin and ground, placed as close as possible to the device.
  - A single bypass capacitor from V+ to ground is applicable for single-supply applications.
- To reduce parasitic coupling, run the input traces as far away as possible from the supply or output traces. If these traces cannot be kept separate, crossing the sensitive trace perpendicular is much better than in parallel with the noisy trace.
- Keep traces as short as possible.
- Minimize the number of thermal junctions. Ideally, the signal path is routed within a single layer without vias.
- Keep sufficient distance from major thermal energy sources (circuits with high power dissipation). If not possible, place the device such that it matches the thermal energy source on the differential signal path.

## 11.2 Layout Example

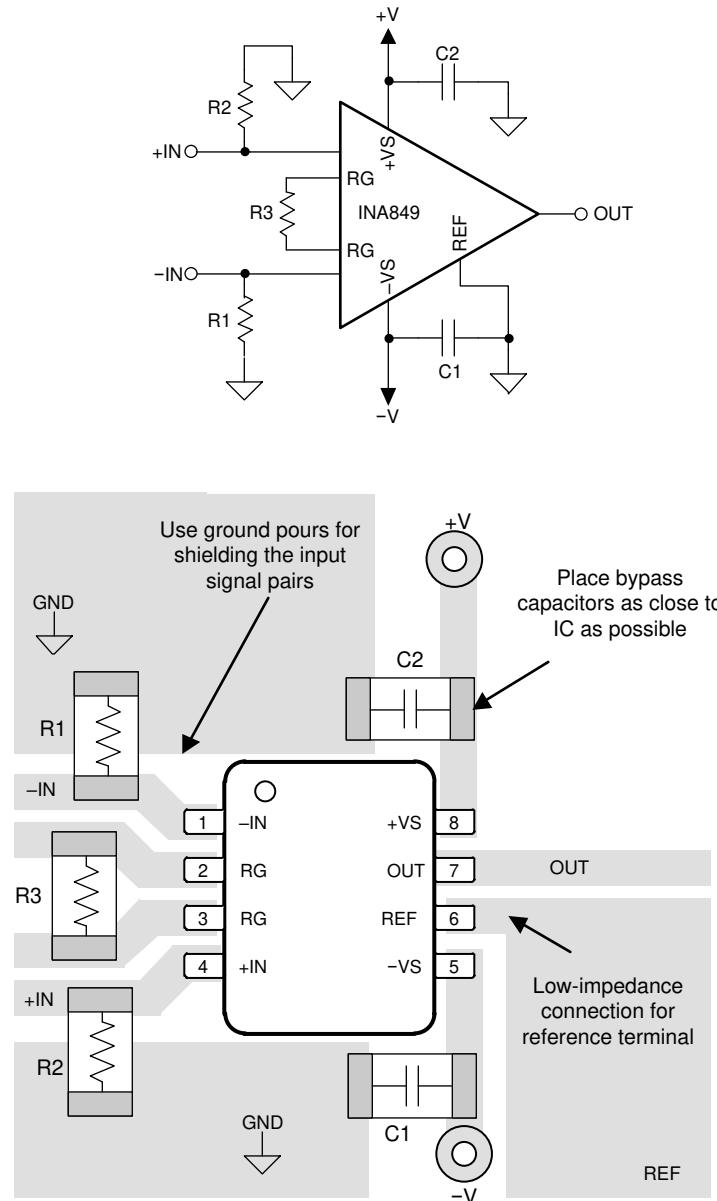


Figure 11-1. Example Schematic and Associated PCB Layout

## 12 Device and Documentation Support

### 12.1 Documentation Support

#### 12.1.1 Related Documentation

For related documentation see the following:

- Texas Instruments, [Comprehensive Error Calculation for Instrumentation Amplifiers](#) application note

### 12.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](#). Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 12.3 Support Resources

[TI E2E™ support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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### 12.4 Trademarks

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### 12.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 12.6 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
INA849DGKR	ACTIVE	VSSOP	DGK	8	2500	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2ENJ	<span style="background-color: red; color: white; padding: 2px;">Samples</span>
INA849DGKT	ACTIVE	VSSOP	DGK	8	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2ENJ	<span style="background-color: red; color: white; padding: 2px;">Samples</span>
INA849DR	ACTIVE	SOIC	D	8	2500	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	INA849	<span style="background-color: red; color: white; padding: 2px;">Samples</span>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

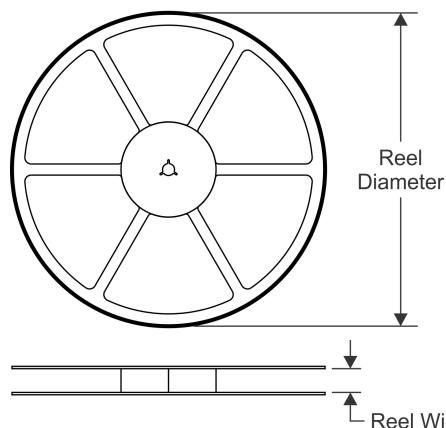
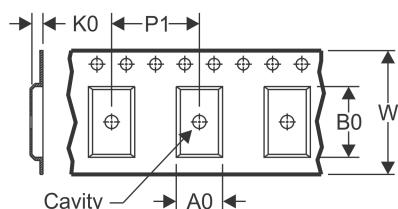
(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

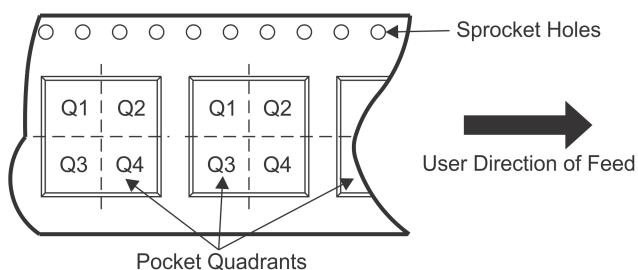
(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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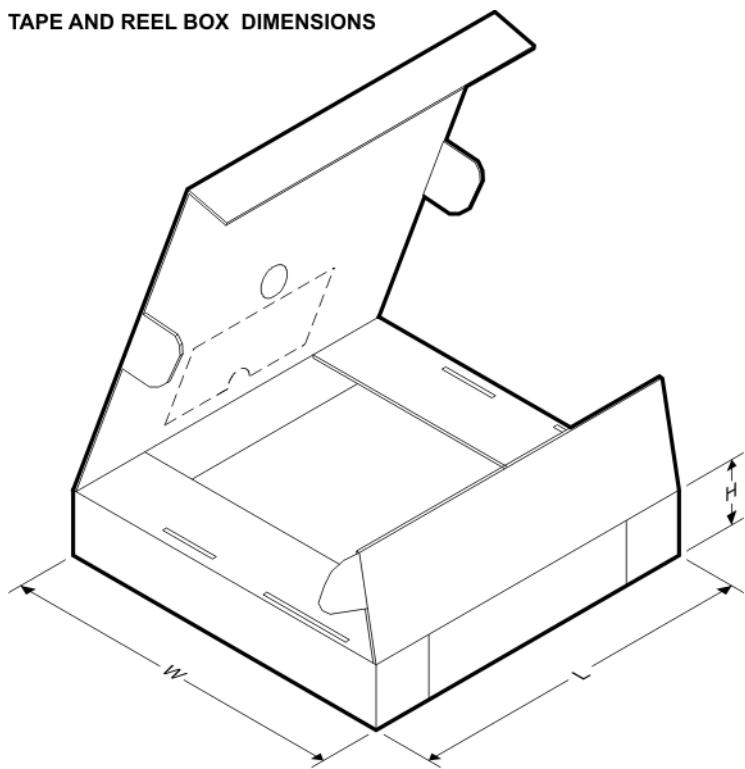
**TAPE AND REEL INFORMATION**
**REEL DIMENSIONS**

**TAPE DIMENSIONS**


A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
INA849DGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA849DGKT	VSSOP	DGK	8	250	180.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
INA849DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

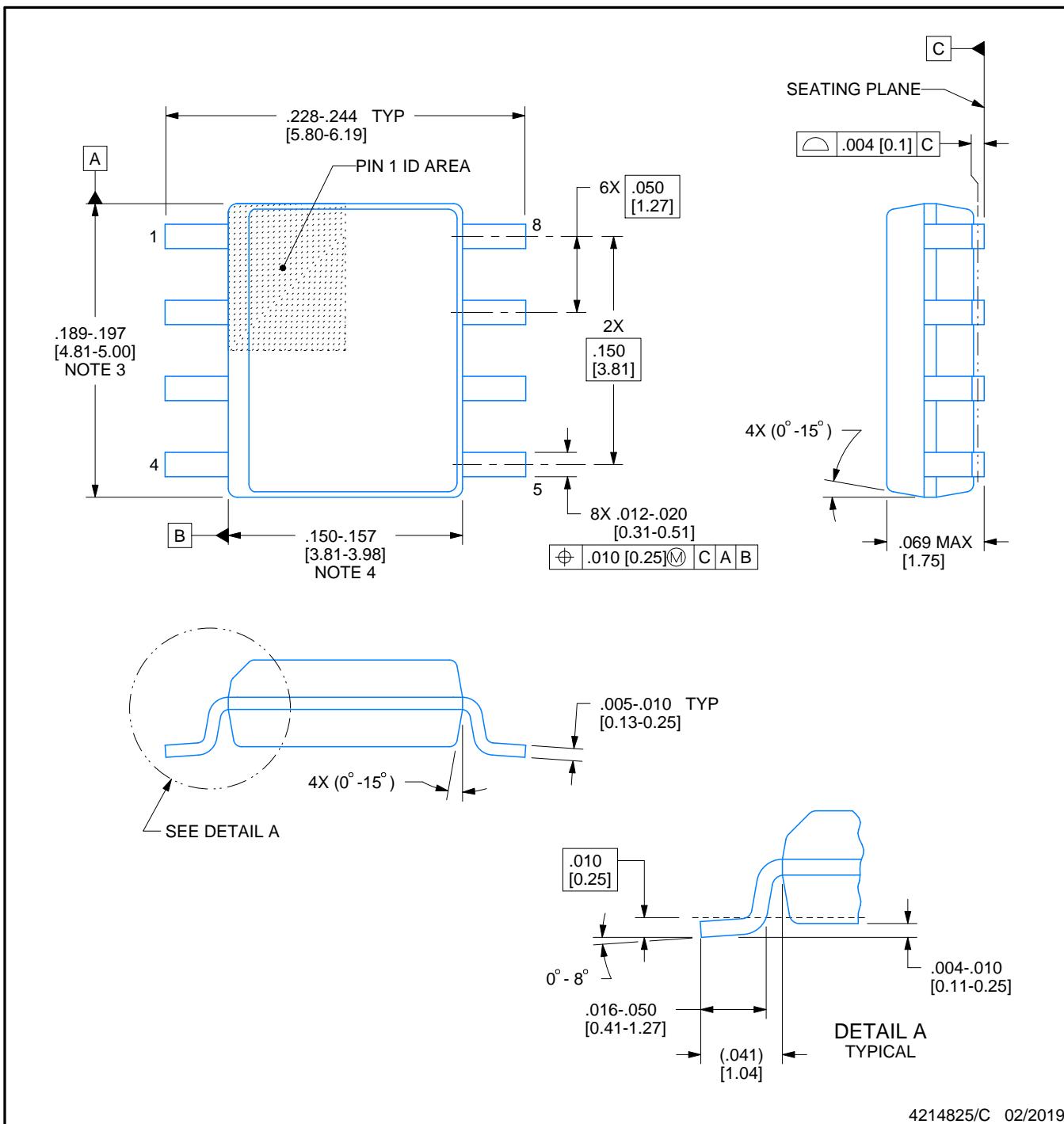
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
INA849DGKR	VSSOP	DGK	8	2500	853.0	449.0	35.0
INA849DGKT	VSSOP	DGK	8	250	210.0	185.0	35.0
INA849DR	SOIC	D	8	2500	853.0	449.0	35.0



# PACKAGE OUTLINE

## SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



### NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

# EXAMPLE BOARD LAYOUT

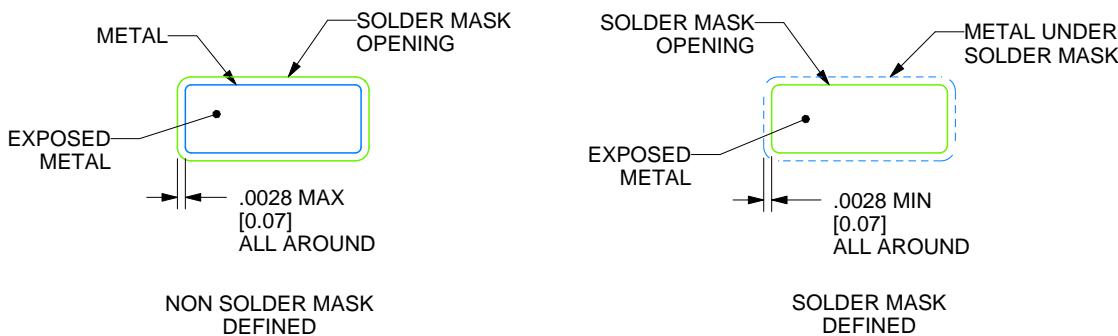
D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:8X



SOLDER MASK DETAILS

4214825/C 02/2019

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

# EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE  
BASED ON .005 INCH [0.125 MM] THICK STENCIL  
SCALE:8X

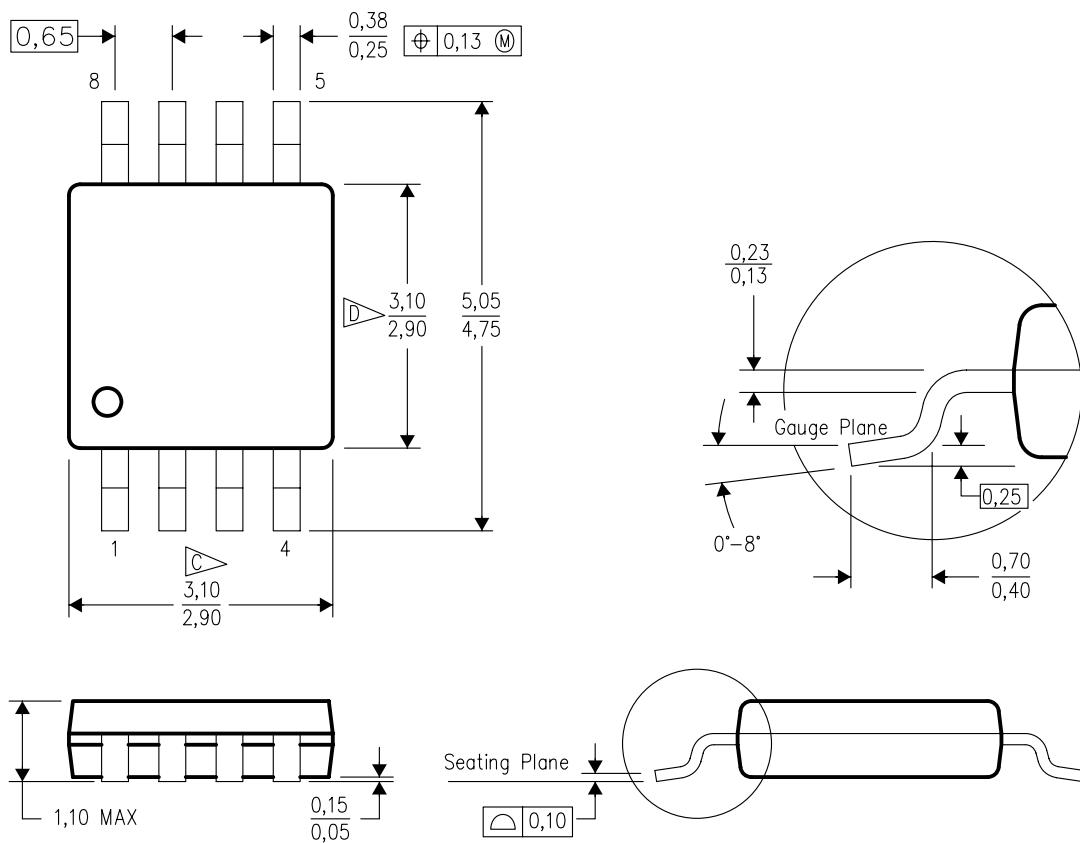
4214825/C 02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

## DGK (S-PDSO-G8)

## PLASTIC SMALL-OUTLINE PACKAGE



4073329/E 05/06

NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

 Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 per end.

 Body width does not include interlead flash. Interlead flash shall not exceed 0.50 per side.

E. Falls within JEDEC MO-187 variation AA, except interlead flash.

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